

***LIRA*, the Low-counts Image Restoration and Analysis Package: a Teaching Version via R**

A. Connors¹, Nathan M. Stein², David van Dyk³, Vinay Kashyap⁴, and Aneta Siemiginowska⁴

¹*Eureka Scientific, 2452 Delmer St. Suite 100, Oakland CA 94602*

²*Harvard Statistics, 1 Oxford St., Cambridge MA 02138*

³*UCI Statistics, Bren Hall 2019, Irvine CA 92697*

⁴*Harvard-Smithsonian Center for Astrophysics, 60 Garden St., Cambridge MA 02138*

Abstract. In low-count discrete photon imaging systems, such as in high energy astrophysics, the spatial distribution of a very few (or no!) photons per pixel can indeed carry important information about the shape of interesting emission. Our Low-counts Image Restoration and Analysis package, *LIRA*, was designed to: ‘deconvolve’ any unknown sky components; give a fully Poisson ‘goodness-of-fit’ for any best-fit model; and quantify uncertainties on the existence and shape of unknown sky components. *LIRA* does this without resorting to χ^2 or rebinning, which can lose high-resolution information. However, since it combines a Poisson-specific multi-scale model for the sky with a full instrument response, within a (Bayesian) probability framework, sampled via MCMC — running it thoughtfully requires understanding several key areas.

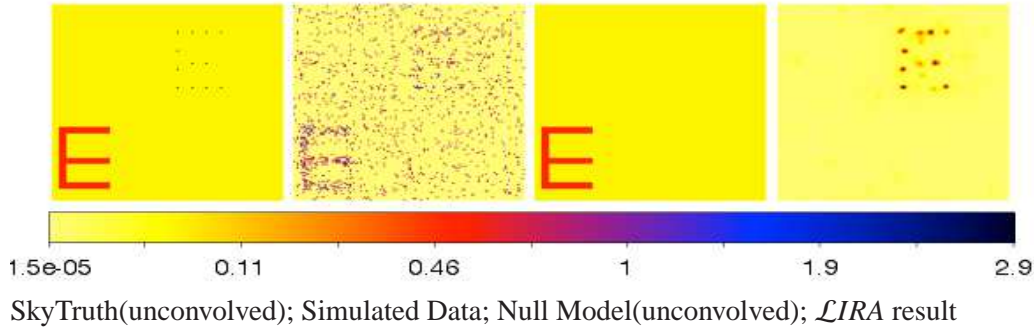
To this end, we have created and are releasing a ‘teaching’ version of *LIRA*. It is implemented in R (cran.r-project.org). The accompanying tutorial and R-scripts step through all the basic analysis steps, from simple multi-scale representation and deconvolution; to model-testing; setting quantitative limits; and even simple ways of incorporating uncertainties in the instrument response.

1. Intro: Wonder, Glee, Skepticism, and *LIRA*

As one confronts beautiful, beautifully processed, astronomical images – such as many in these proceedings – who does not feel the pull of wonder? As well, when one recognizes that a newly visible feature appears to match one’s theory, isn’t there a sharp pull of glee? Yet, in this paper, we advocate doubt: “where are the error bars?”.

LIRA was developed precisely to quantify this doubt, for low-count Poisson data. To do this, *LIRA* brings together several different kinds of machinery, from Multi-scale (MS) models to Markov chain Monte Carlo (MCMC) in a Bayesian framework [1,2,3]. Although made for Poisson counts, our schema of: a flexible or non- or semi-parametric model; with a background or Null model; within a full likelihood framework; can serve as a model for more general data. The combination can at first feel un-intuitive for even seasoned researchers. Hence, we have created a ‘teaching’ version, with many examples, within the easy-to-use public statistical package ‘R’. *LIRA* is available from: [nathanmstein at gmail.com](mailto:nathanmstein@gmail.com) or [aconnors at eurekabayes.com](mailto:aconnors@eurekabayes.com)

Here, we briefly exhibit parts of one of the teaching examples. It is based on a hypothetical ‘skytruth’ of a diffuse component (a broad letter E) and a cluster of point sources (also forming a letter E) on a flat background, in 128x128 bins, as shown in the first figure. The instrument smearing, or point-spread function (PSF), is assumed to be a circular Gauss-Normal distribution with $\sigma = 1.5$ bins. Simulated Poisson data D based on these is shown in the 2nd panel. We display a ‘Null Model’ of the diffuse emission based on hypothetical measurements and theory: a broad ‘E’ – in the 3rd panel. The simulated data, PSF, and Null model, are inputs to \mathcal{LIRA} ; one of the outputs is the mean ‘mismatch’ between the data and theory, shown in the last panel of the 1st figure.



2. \mathcal{LIRA} Mechanics:

\mathcal{LIRA} can be termed a ‘forward-fitting’ likelihood-based method, built under a ‘Bayesian umbrella’. That is, we use a Bayesian framework to successively add ‘spokes’ to the total likelihood: Poisson likelihood of the data D (red); given a Null Model with parameters θ , be designated by $M(\theta)$ (blue); and the Instrument Response by IR (brown). Then, using Bayes’ theorem, the posterior probability can be written as in the first panel of the second figure, where @ designates a convolution.

$$\begin{aligned}
 &P(\text{Model } \mathcal{M}(\theta) | \text{Data } D, \text{Instrument Response } IR, \text{etc}) = & P(\text{Model } \mathcal{M}(\theta), \text{MisMatch}(f, \mathcal{M}S) | \text{Data } D, \text{Response } IR, \text{etc}) = \\
 &P(D | \mathcal{M}(\theta), IR \text{ etc}) P(\mathcal{M}, \theta | \text{etc}) / P(D | IR, \text{etc}) = & P(D | (f\mathcal{M}(\theta) + \mathcal{M}S), IR \text{ etc}) P(f, \mathcal{M}, \alpha | \text{etc}) / P(D | IR, \text{etc}) = \\
 &\text{Pois}(D | \mathcal{M} @ IR) \Gamma(\theta) \pi(\mathcal{M}) / P(D) & \text{Pois}(D | (f\mathcal{M} + \mathcal{M}S) @ IR) \Gamma(f) \pi(\mathcal{M}) \pi(\alpha) / P(D)
 \end{aligned}$$

→ → → →

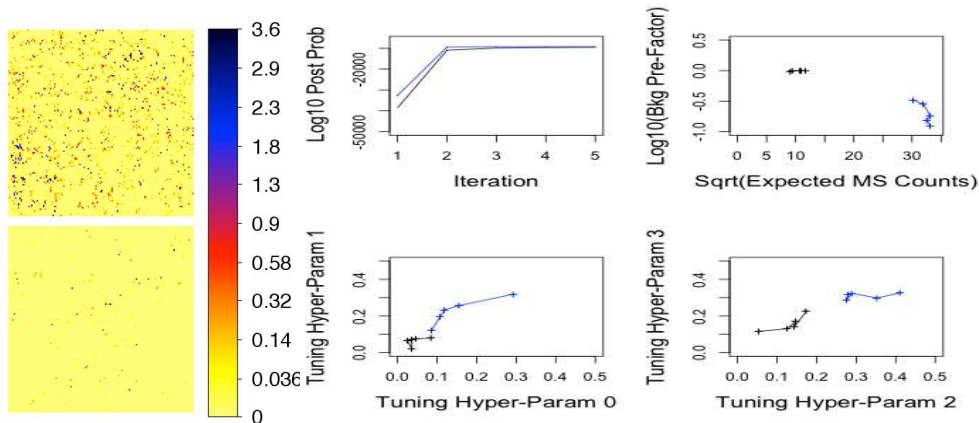
Bayes Umbrellas: Adding a spoke (right panel; green).

In this form, it is easy for us to add a *model/data mis-match* ‘spoke’ (green) to our Bayesian umbrella. In our low-count regime, we formulate the *mode/data mis-match* term to be a *prefactor* times the null model, plus a Poisson-tailored *multi-scale model* [1,2,4] that will handle both fine details and broad features. But now there are a great many parameters: rates at each successively finer multi-scale level, given the previous

level; tuning (or smoothing or regularization) hyper-parameters, for each level; the Null Model prefactor. Hence rather than e.g. a Powell or Levenberg-Marquardt method for finding a mode, we use Markov chain Monte Carlo to map out the full probability space. This allows us to get both a ‘best fit’, and a way to express uncertainties on any feature from the data/model mis-match.

3. Running $\mathcal{L}IRA$

In the next several figures, we illustrate MCMC in action, mapping out the shape of our posterior likelihood (or Bayesian Umbrella from the second figure). It shows both a ‘burn-in’ phase and a converged phase. Finally we illustrate that, in order to get full quantitative limits, we must perform the same $\mathcal{L}IRA$ analysis on a handful of simulated data sets based on the Null Model (convolved with the instrument response). We then use a small subset of the parameters — in this case, the total counts inferred to be in the multi-scale (MS) component — as a *summary statistic* of the ‘distance’ between the data and the null of the summary statistic give the upper and lower bounds on the *shape* of the Data/Null-Model mis-match.

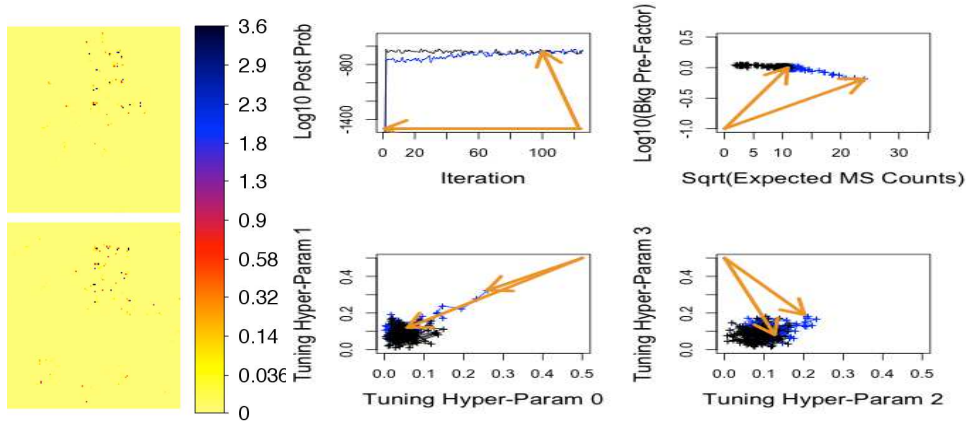


Iteration 005 Two start values: high (top image; ‘+’); low (bottom image; ‘+’).

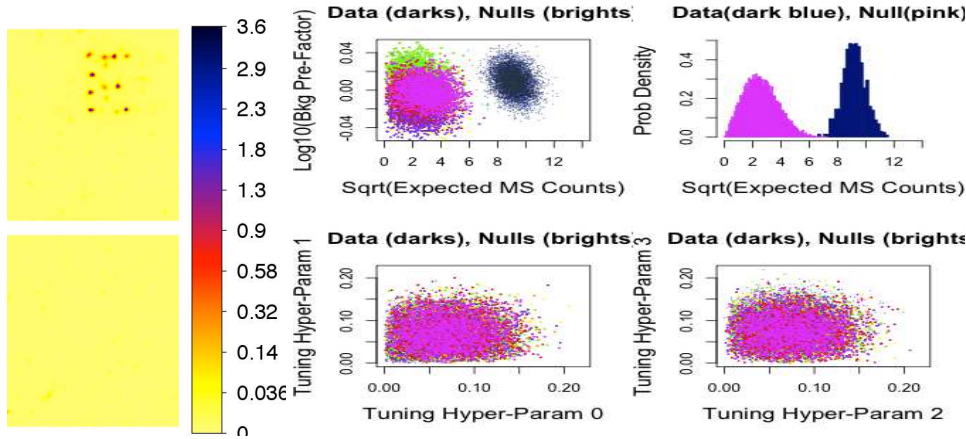
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References

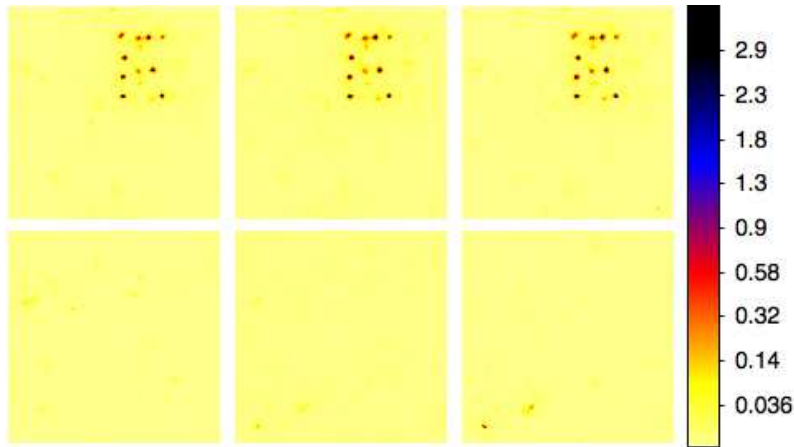
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Iteration 125. Two start values: high (top image, '+'); low (bottom image, '+'). Orange arrows roughly indicate burn-in range for high starting values.



LIRA Results, after burn-in. Left: Mean Images from Data (top) vs. Simulated Nulls (bottom). Right: Distributions of Data (dark colors) vs Simulated Nulls (bright colors).



LIRA Results, limits on shape. Data (top) vs Simulated Null (bottom): Left: lower 5% limit; Middle: Mean; Right: upper 95% limits