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## ***LIRA*, the Low-counts Image Restoration and Analysis Package: a Teaching Version via R**

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**Abstract.** In low-count discrete photon imaging systems, such as in high energy astrophysics, the spatial distribution of a very few (or no!) photons per pixel can indeed carry important information about the shape of interesting emission. Our Low-counts Image Restoration and Analysis package, *LIRA*, was designed to: ‘deconvolve’ any unknown sky components; give a fully Poisson ‘goodness-of-fit’ for any best-fit model; and quantify uncertainties on the existence and shape of unknown sky components. *LIRA* does this without resorting to  $\chi^2$  or rebinning, which can lose high-resolution information. However, since it combines a Poisson-specific multi-scale model for the sky with a full instrument response, within a (Bayesian) probability framework, sampled via MCMC — running it thoughtfully requires understanding several key areas.

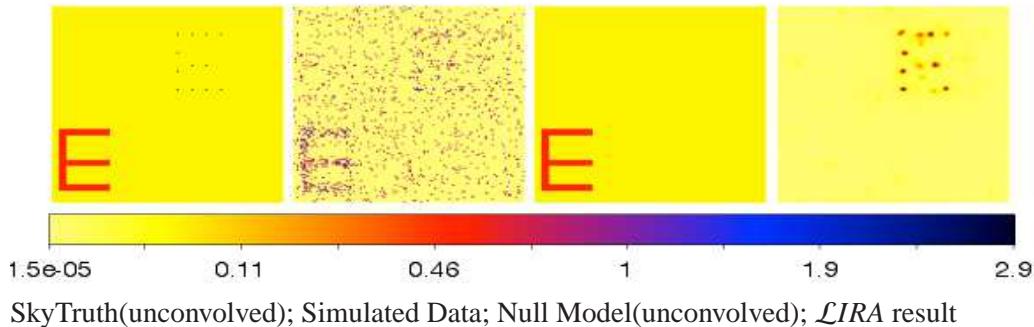
To this end, we have created and are releasing a ‘teaching’ version of *LIRA*. It is implemented in R ([cran.r-project.org](http://cran.r-project.org)). The accompanying tutorial and R-scripts step through all the basic analysis steps, from simple multi-scale representation and deconvolution; to model-testing; setting quantitative limits; and even simple ways of incorporating uncertainties in the instrument response.

### **1. Intro: Wonder, Glee, Skepticism, and *LIRA***

As one confronts beautiful, beautifully processed, astronomical images – such as many in these proceedings – who does not feel the pull of wonder? As well, when one recognizes that a newly visible feature appears to match one’s theory, isn’t there a sharp pull of glee? Yet, in this paper, we advocate doubt: “where are the error bars?”.

*LIRA* was developed precisely to quantify this doubt, for low-count Poisson data. To do this, *LIRA* brings together several different kinds of machinery, from Multi-scale (MS) models to Markov chain Monte Carlo (McMC) in a Bayesian framework [1,2,3]. Although made for Poisson counts, our schema of: a flexible or non- or semi-parametric model; with a background or Null model; within a full likelihood framework; can serve as a model for more general data. The combination can at first feel un-intuitive for even seasoned researchers. Hence, we have created a ‘teaching’ version, with many examples, within the easy-to-use public statistical package ‘R’. *LIRA* is available from: nathanmstein at gmail.com or aconnors at eurekabayes.com

Here, we briefly exhibit parts of one of the teaching examples. It is based on a hypothetical ‘skytruth’ of a diffuse component (a broad letter E) and a cluster of point sources (also forming a letter E) on a flat background, in 128x128 bins, as shown in the first figure. The instrument smearing, or point-spread function (PSF), is assumed to be a circular Gauss-Normal distribution with  $\sigma = 1.5$  bins. Simulated Poisson data  $D$  based on these is shown in the 2nd panel. We display a ‘Null Model’ of the diffuse emission based on hypothetical measurements and theory: a broad ‘E’ – in the 3rd panel. The simulated data, PSF, and Null model, are inputs to  $\mathcal{LIRA}$ ; one of the outputs is the mean ‘mismatch’ between the data and theory, shown in the last panel of the 1st figure.



## 2. $\mathcal{LIRA}$ Mechanics:

$\mathcal{LIRA}$  can be termed a ‘forward-fitting’ likelihood-based method, built under a ‘Bayesian umbrella’. That is, we use a Bayesian framework to successively add ‘spokes’ to the total likelihood: Poisson likelihood of the data  $D$  (red); given a Null Model with parameters  $\theta$ , be designated by  $M(\theta)$  (blue); and the Instrument Response by  $IR$  (brown). Then, using Bayes’ theorem, the posterior probability can be written as in the first panel of the second figure, where @ designates a convolution.

$$\begin{aligned} P(\text{Model } M(\theta) | \text{Data } D, \text{Instrument Response } IR, \text{etc}) &= \\ P(D | M(\theta), IR \text{ etc}) P(M(\theta) | \text{etc}) / P(D | IR, \text{etc}) &= \\ \text{Pois}(D | M @ IR) \Gamma(\theta) \pi(M) / P(D) & \\ \text{Shape of Math} & \\ \end{aligned} \quad \begin{aligned} P(\text{Model } M(\theta), \text{MisMatch}(f, MS) | \text{Data } D, \text{Response } IR, \text{etc}) &= \\ P(D | (fM(\theta) + MS), IR \text{ etc}) P(f, M, \alpha | \text{etc}) / P(D | IR, \text{etc}) &= \\ \text{Pois}(D | (fM + MS) @ IR) \Gamma(f) \pi(M) \pi(\alpha) / P(D) & \\ \text{Shape of Math} & \\ \text{Hyper-Priors on Tuning Params} & \end{aligned}$$

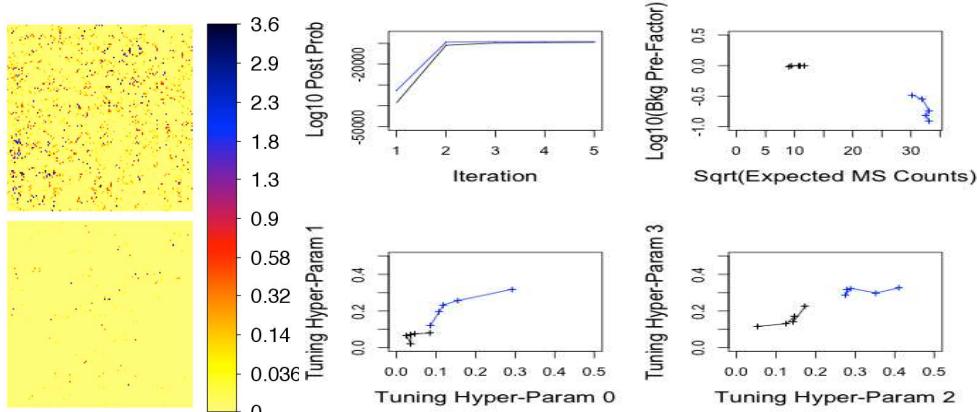
Bayes Umbrellas: Adding a spoke (right panel; green).

In this form, it is easy for us to add a *model/data mis-match* ‘spoke’ (green) to our Bayesian umbrella. In our low-count regime, we formulate the *mode/data mis-match* term to be a *prefactor* times the null model, plus a Poisson-tailored *multi-scale model* [1,2,4] that will handle both fine details and broad features. But now there are a great many parameters: rates at each successively finer multi-scale level, given the previous

level; tuning (or smoothing or regularization) hyper-parameters, for each level; the Null Model prefactor. Hence rather than e.g. a Powell or Levenberg-Marquardt method for finding a mode, we use Markov chain Monte Carlo to map out the full probability space. This allows us to get both a ‘best fit’, and a way to express uncertainties on any feature from the data/model mis-match.

### 3. Running *LIRA*

In the next several figures, we illustrate McMC in action, mapping out the shape of our posterior likelihood (or Bayesian Umbrella from the second figure). It shows both a ‘burn-in’ phase and a converged phase. Finally we illustrate that, in order to get full quantitative limits, we must perform the same *LIRA* analysis on a handful of simulated data sets based on the Null Model (convolved with the instrument response). We then use a small subset of the parameters — in this case, the total counts inferred to be in the multi-scale (*MS*) component — as a *summary statistic* of the ‘distance’ between the data and the null of the summary statistic give the upper and lower bounds on the *shape* of the Data/Null-Model mis-match.

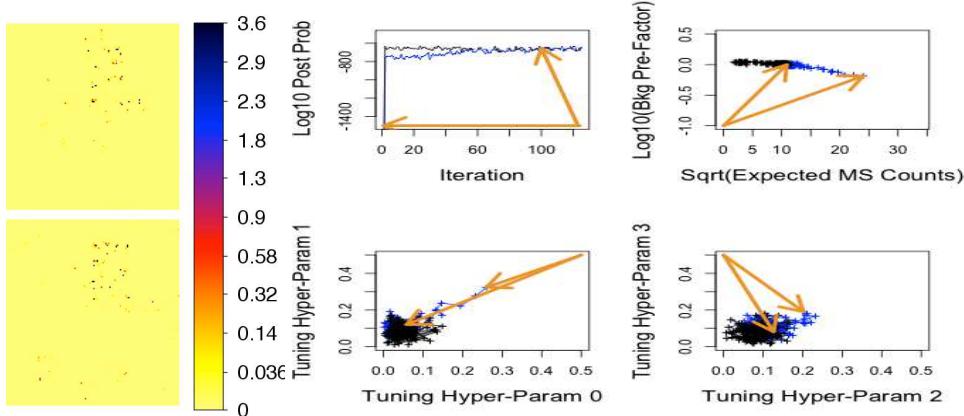


**Iteration 005** Two start values: high (top image; ‘+’); low (bottom image; ‘+’).

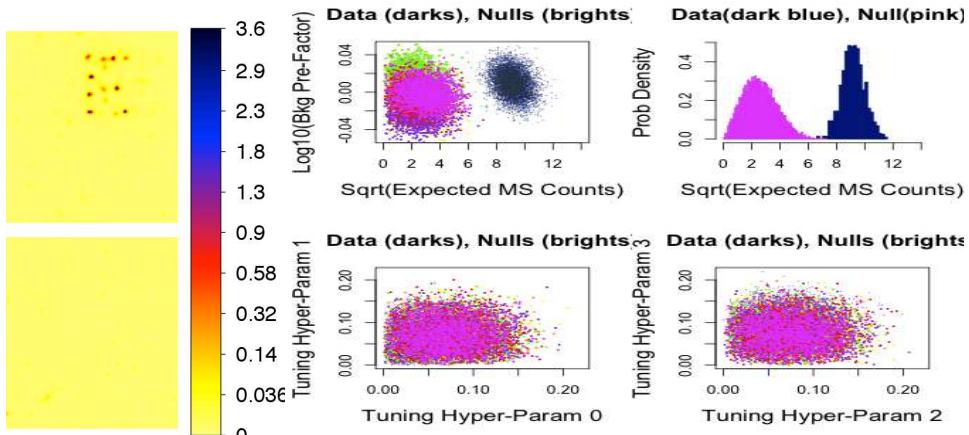
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### References

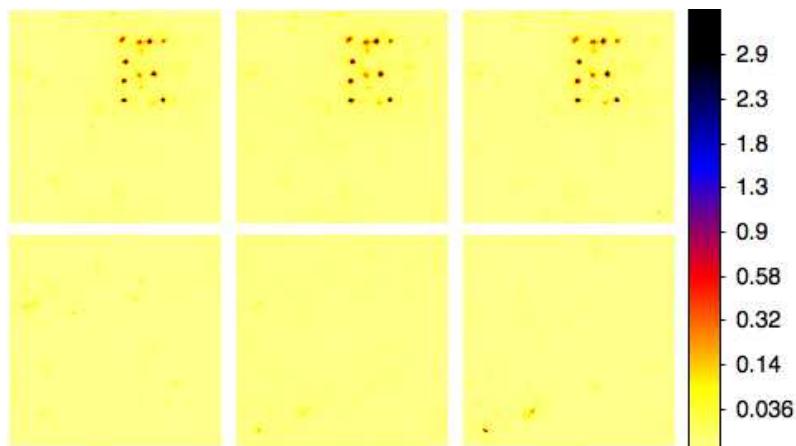
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**Iteration 125.** Two start values: high (top image, ‘+’); low (bottom image, ‘+’). Orange arrows roughly indicate burn-in range for high starting values.



**LIRA Results, after burn-in.** Left: Mean Images from Data (top) vs. Simulated Nulls (bottom). Right: Distributions of Data (dark colors) vs Simulated Nulls (bright colors).



**LIRA Results, limits on shape.** Data (top) vs Simulated Null (bottom): Left: lower 5% limit; Middle: Mean; Right: upper 95% limits