

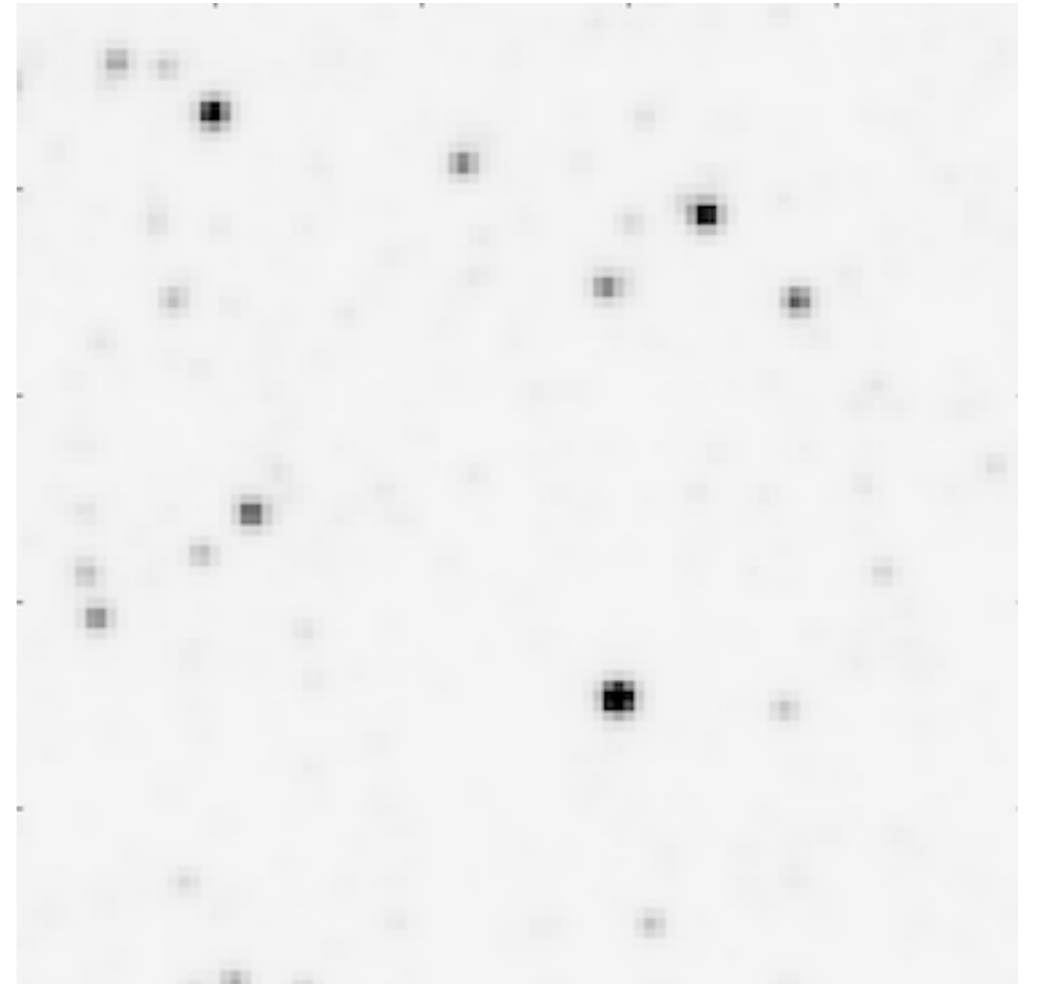


Probabilistic Catalogs
for photometry in
Extremely Crowded Fields

Douglas Finkbeiner
with Brendan Meade,
Stephen Portillo, Ben Lee, and Tansu Daylan

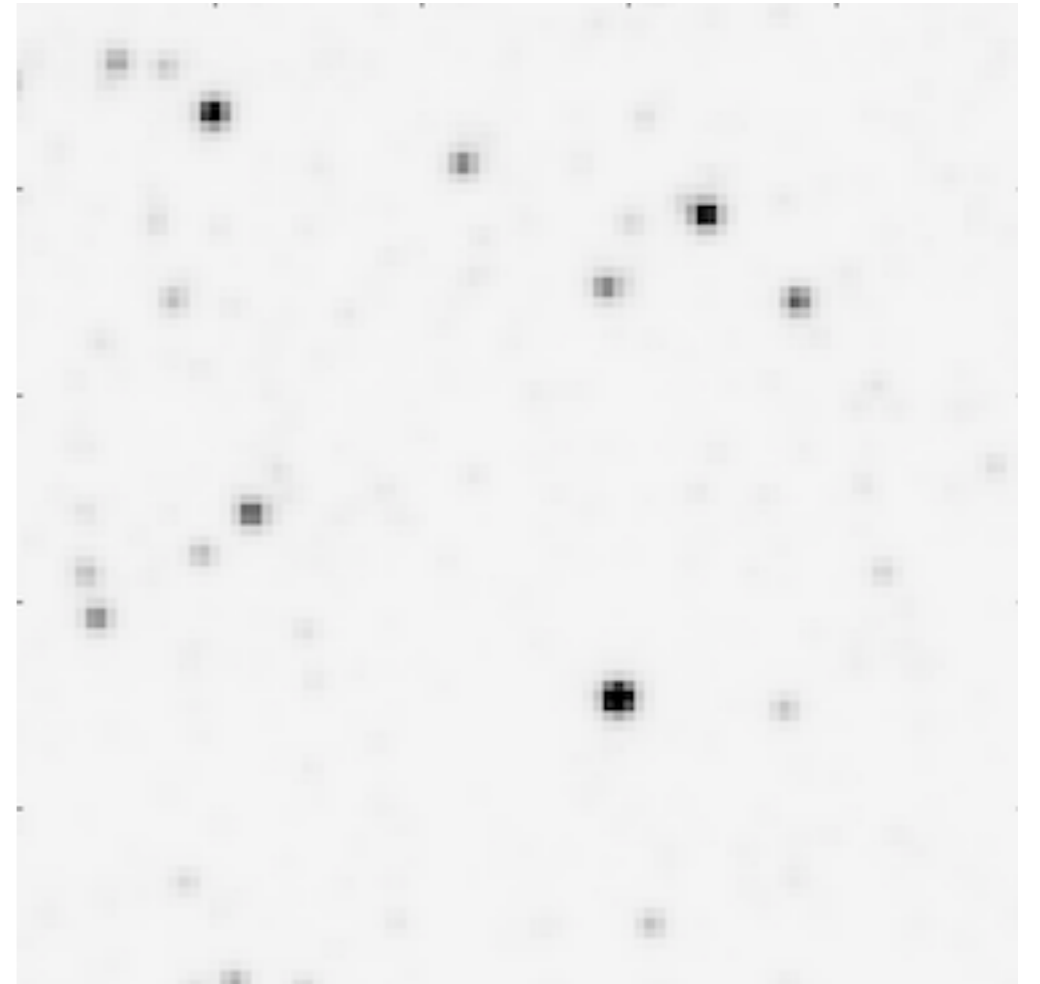
6 December, 2016

Stellar photometry:



Stellar photometry:

Identify objects

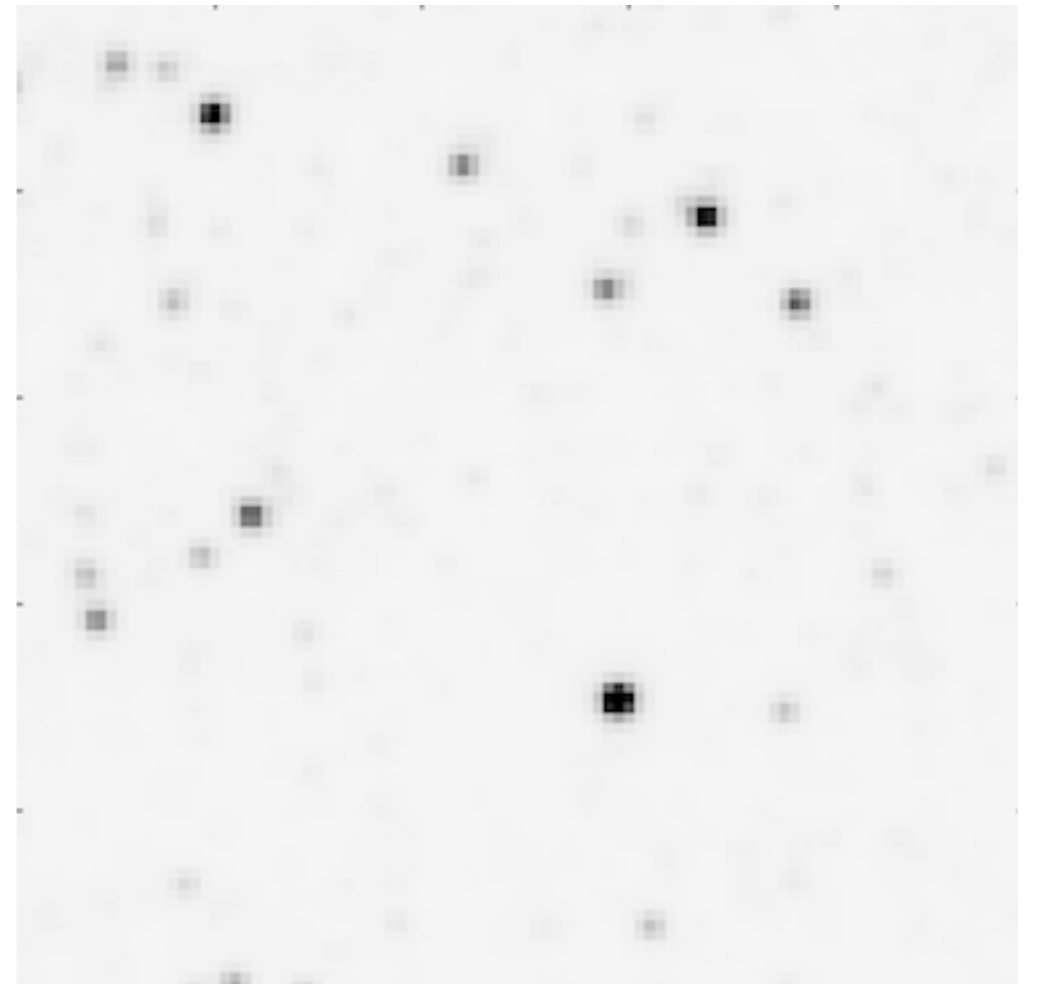


Stellar photometry:

Identify objects

Measure $\{x,y,\text{flux}\}$ of each
(and sky level, psf shape...)

Optimize those to maximize likelihood of
reconstructed image.
(Gaussian or Poisson)



Stellar photometry:

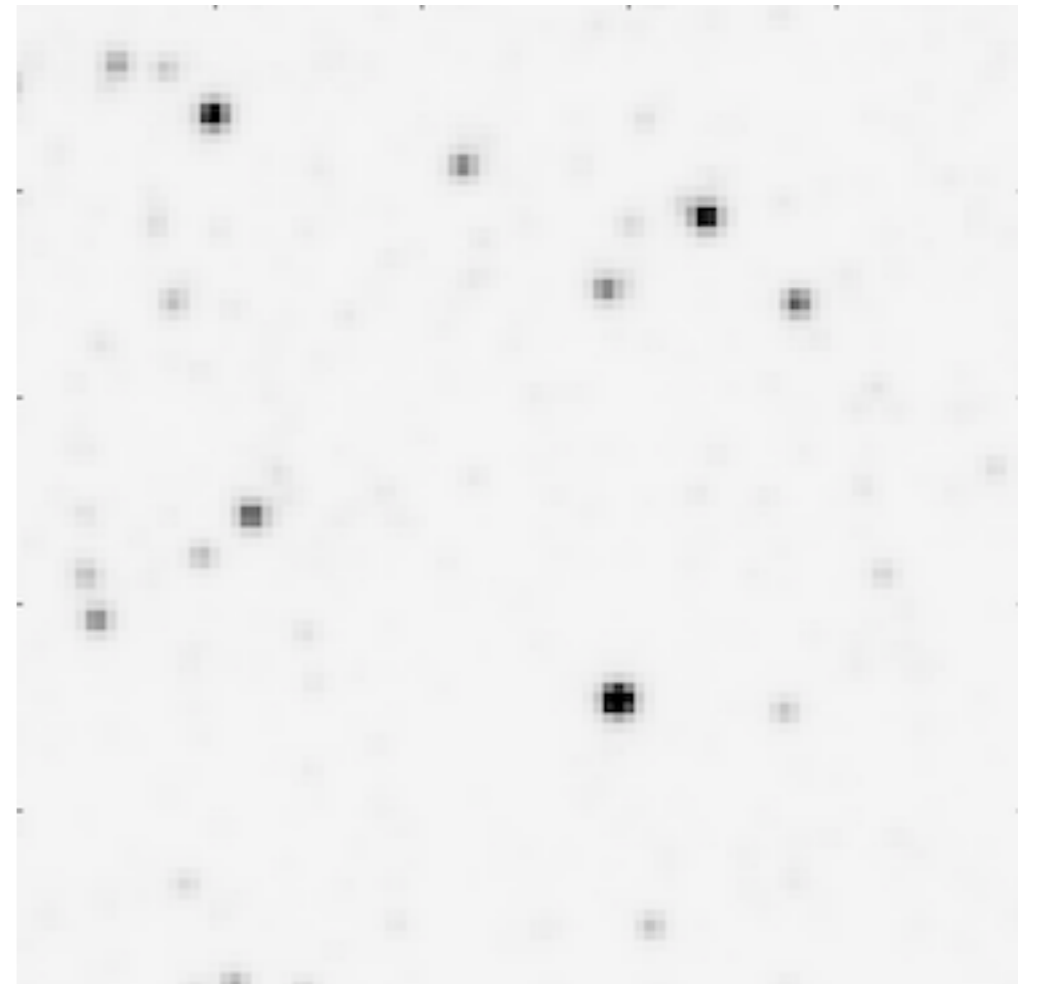
Identify objects

Measure $\{x, y, \text{flux}\}$ of each
(and sky level, psf shape...)

Optimize those to maximize likelihood of
reconstructed image.
(Gaussian or Poisson)

Inputs: astrometric / photometric cal,
prior on flux distribution.

(Difference between optimal
reconstruction of image and optimal
reconstruction of catalog!)



There are many algorithms for this:

DAOPhot

DoPhot

SExtractor

SDSS pipeline

Pan-STARRS pipeline

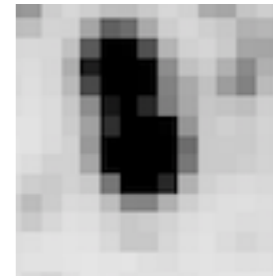
DECam / DES pipeline

etc, etc...

All make different assumptions, try different approaches (representation of PSF) but all are attempting ~ the same thing.

Crowded field photometry:

$\{x,y,\text{flux}\}$ of each source are covariant with those of the neighbors. Can we track that?

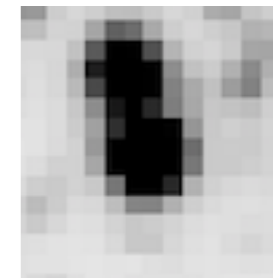


Crowded field photometry:

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Could linearize the problem and make an x,y,flux covariance matrix, then marginalize over uncertainties in neighboring sources.

Need to ID all the neighbors first.



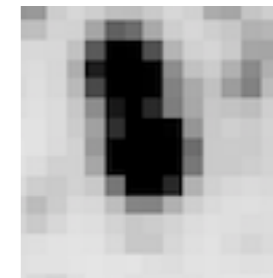
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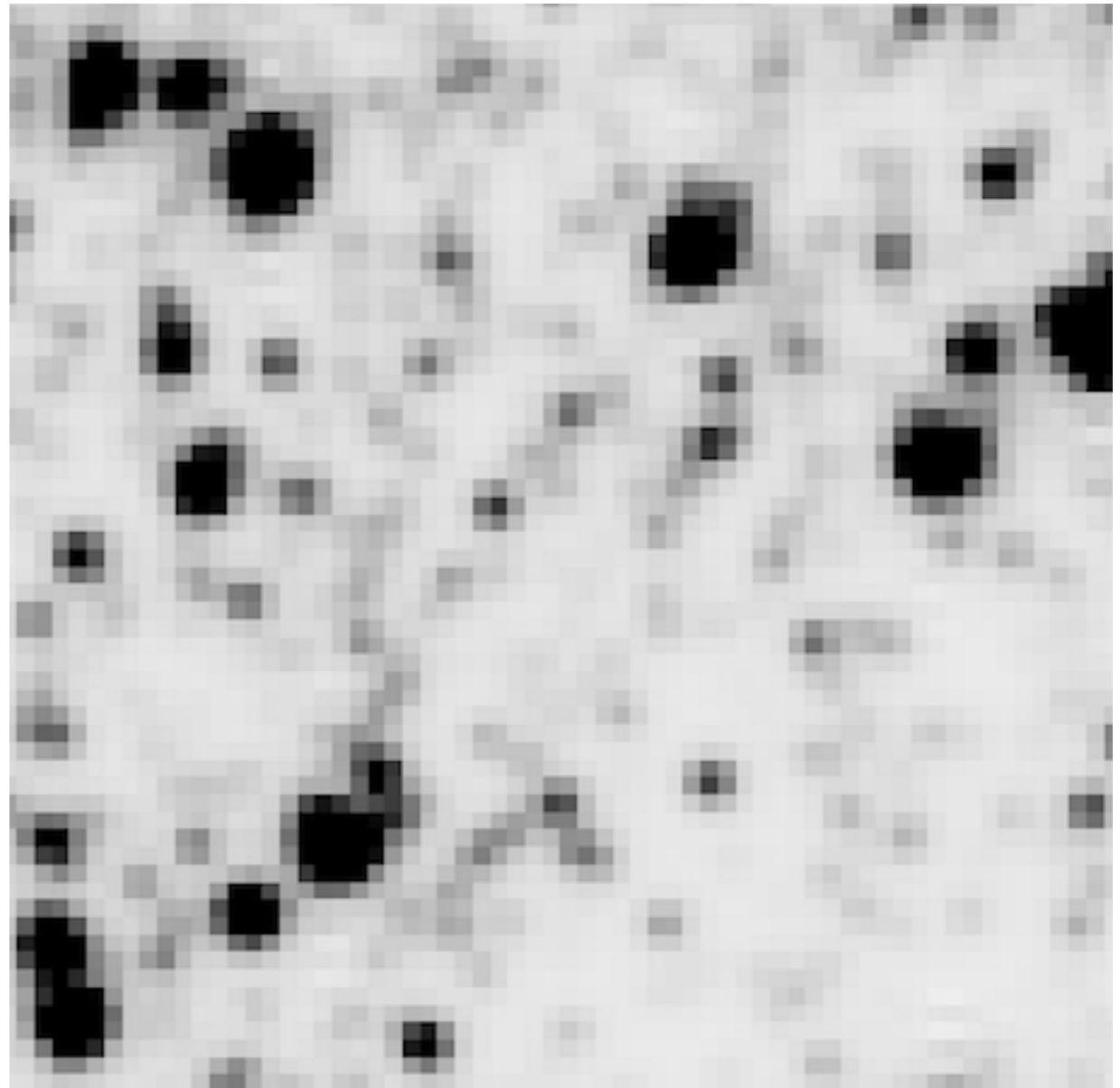
Could linearize the problem and make an x,y,flux covariance matrix, then marginalize over uncertainties in neighboring sources.

Need to ID all the neighbors first.

I.e. only max L (for a given source!) in the context of some parameterization.



But in general?



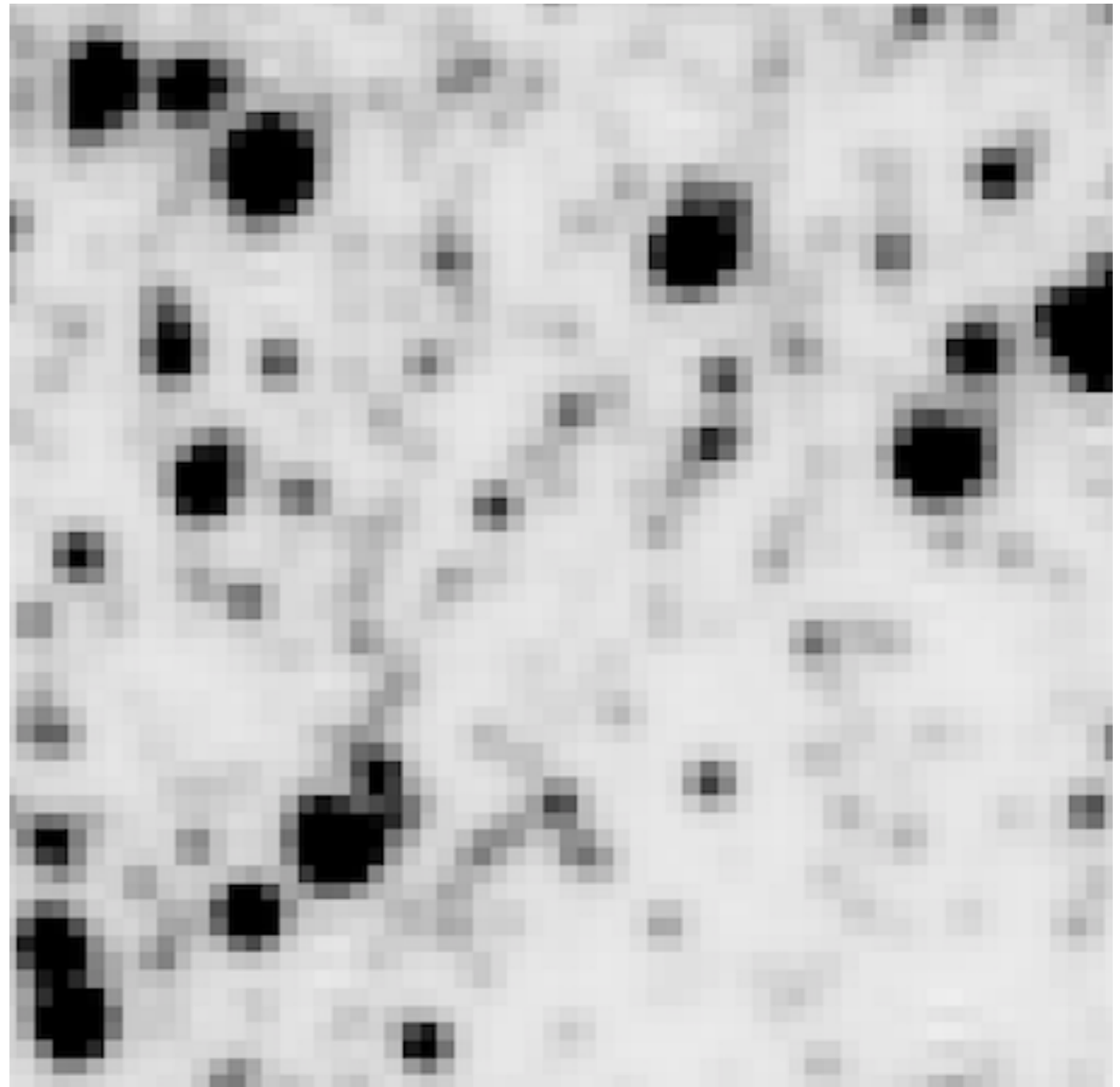
But in general?

Can keep “throwing sources at it”
but when to stop?

How to propose
births (and deaths)?

How to try all permutations
of possible neighbors?

Correct uncertainty estimate
must marginalize over all the
options.



This sounds like MCMC

in a variable-dimension parameter space!

This sounds like MCMC

in a variable-dimension parameter space!

Trans-dimensional search

Probabilistic Catalogs for Crowded Stellar Fields

Brendon J. Brewer, Daniel Foreman-Mackey, David W. Hogg

(Submitted on 25 Nov 2012 (v1), last revised 20 Apr 2013 (this version, v2))

We present and implement a probabilistic (Bayesian) method for producing catalogs from images of stellar fields. The method is capable of inferring the number of sources N in the image and can also handle the challenges introduced by noise, overlapping sources, and an unknown point spread function (PSF). The luminosity function of the stars can also be inferred even when the precise luminosity of each star is uncertain, via the use of a hierarchical Bayesian model. The computational feasibility of the method is demonstrated on two simulated images with different numbers of stars. We find that our method successfully recovers the input parameter values along with principled uncertainties even when the field is crowded. We also compare our results with those obtained from the SExtractor software. While the two approaches largely agree about the fluxes of the bright stars, the Bayesian approach provides more accurate inferences about the faint stars and the number of stars, particularly in the crowded case.

Imagine the space of all possible (star) catalogs,
with

$N = \{0,1,2,3,\dots,N_{\max}\}$ sources. Define a likelihood function
(or posterior) in that space.

Sample from it.

Proposals to perturb
x,y,flux

but also

add stars

remove stars

split stars

merge stars

Every type of move must be reversible
-> detailed balance.

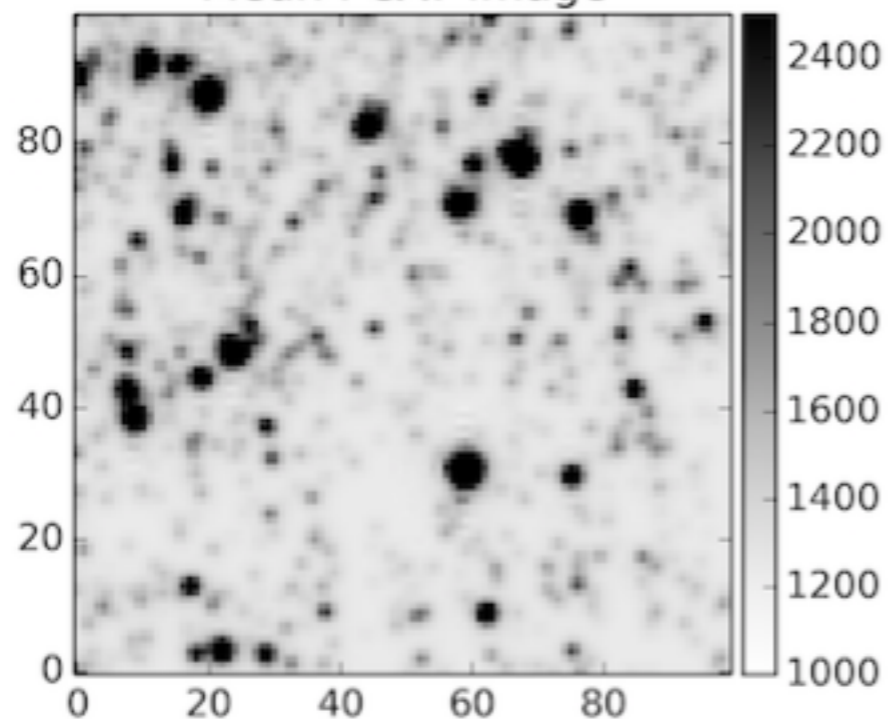
We do this with our code "PCAT" using
the DNEST3 sampler by Brendon Brewer

Test case:

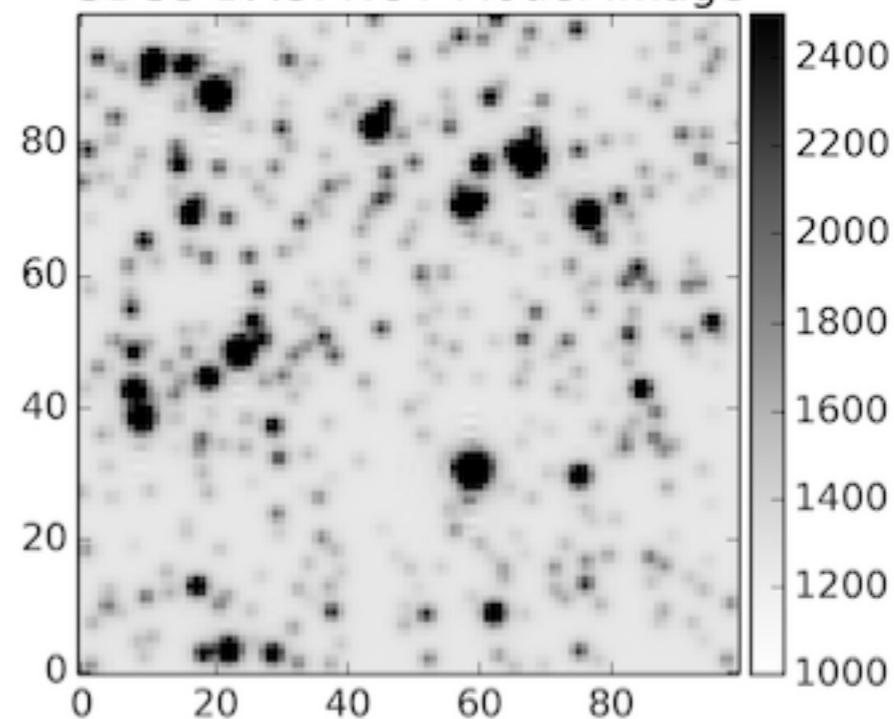
Messier 2 (globular cluster)
on SDSS Stripe 82 (lots of data)
Also HST data (for reality check)

SDSS pipeline failed, but
An et al. (2007) provide DAOPhot
catalogs in this field.

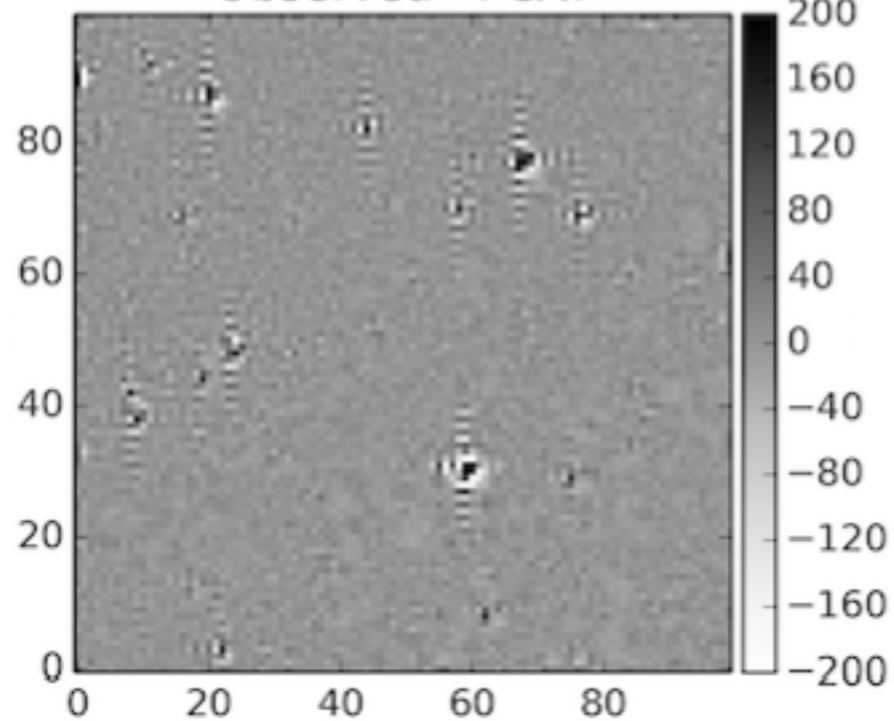
Mean PCAT Image



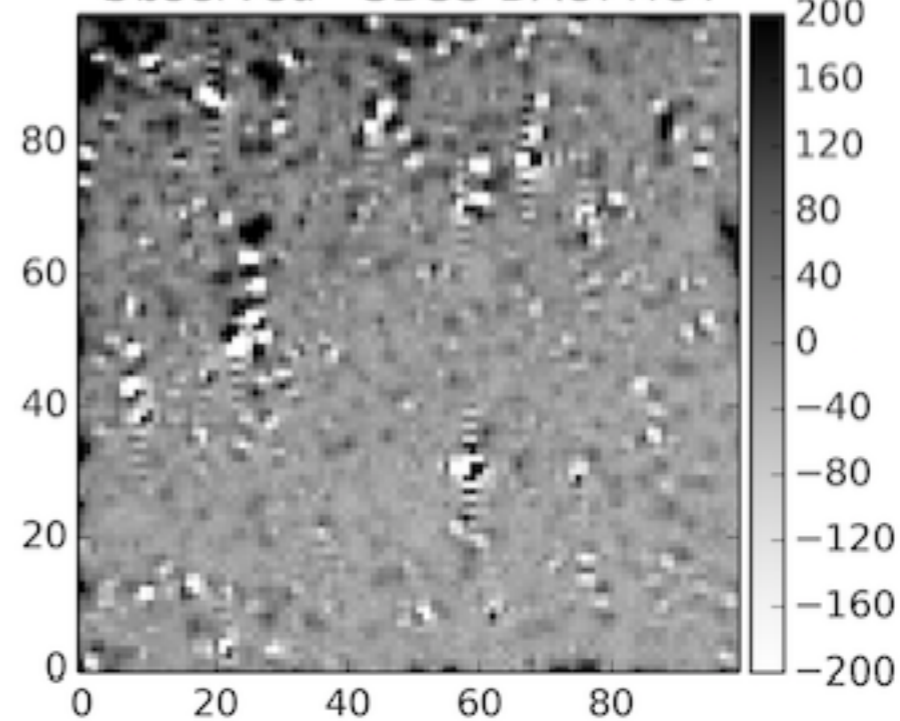
SDSS DAOPHOT Model Image



Observed - PCAT



Observed - SDSS DAOPHOT

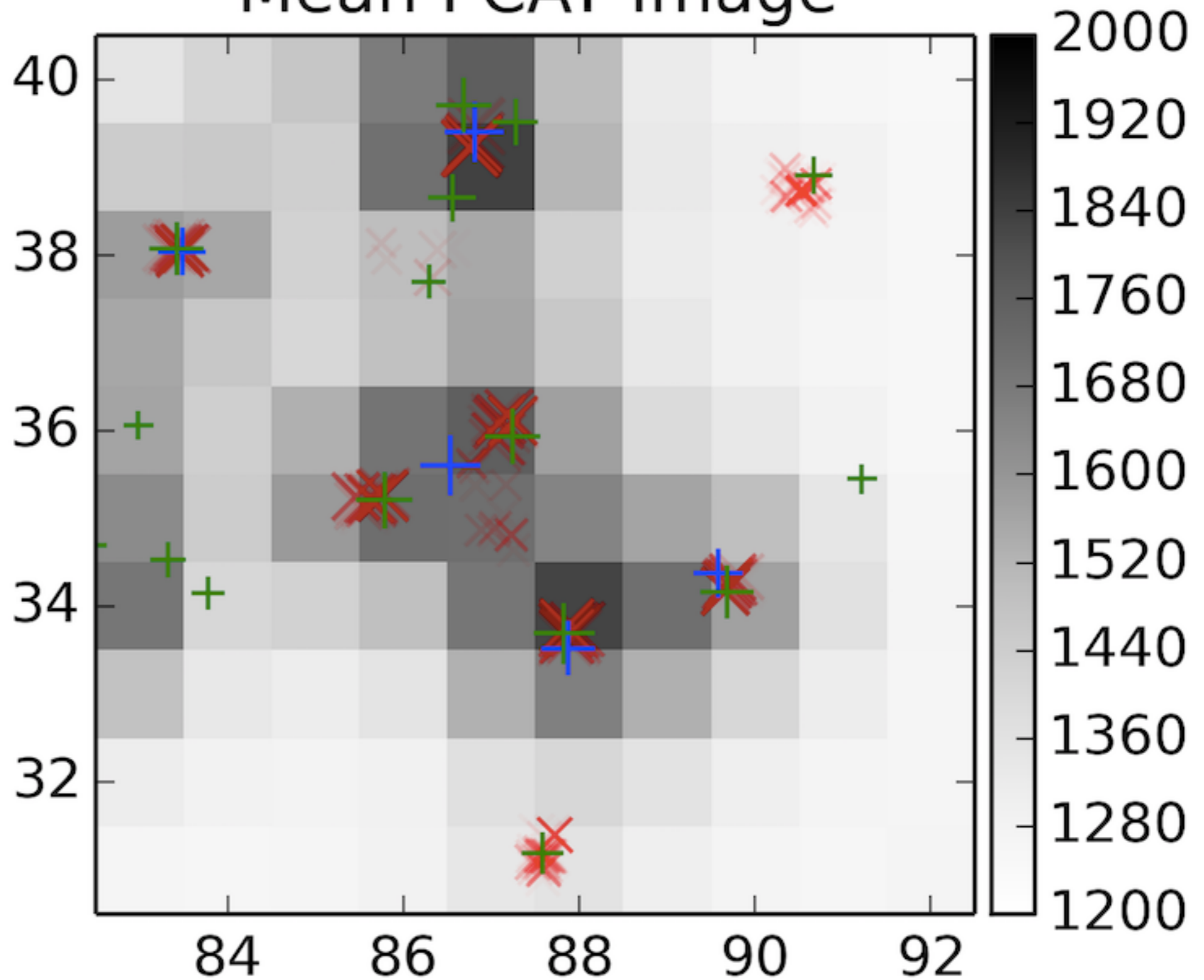


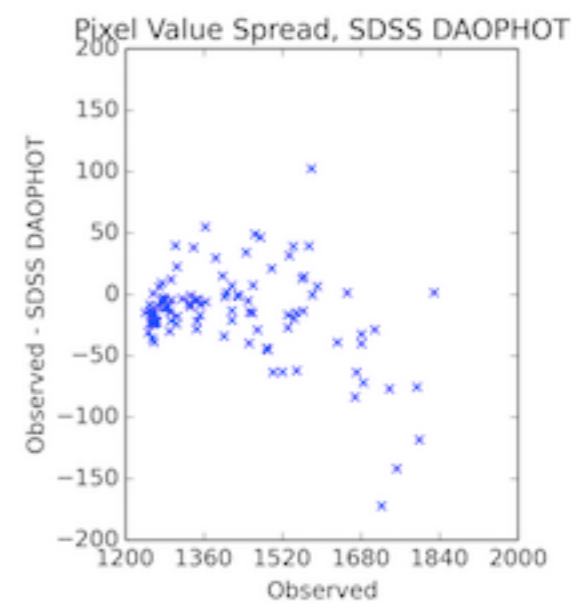
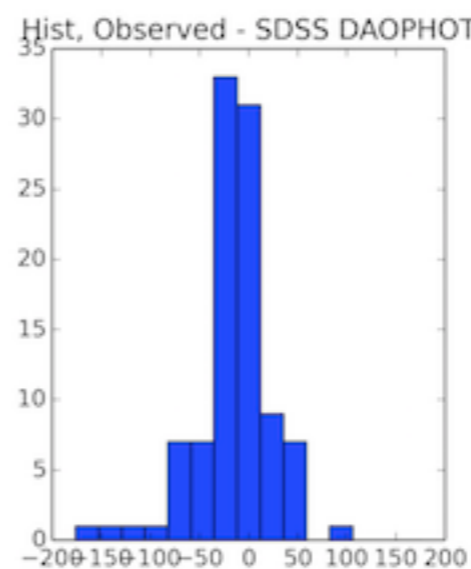
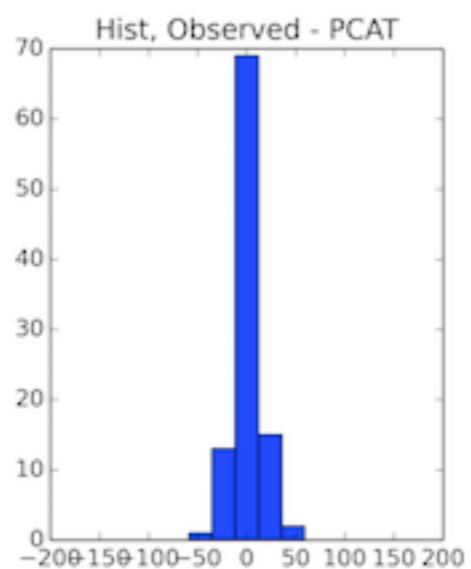
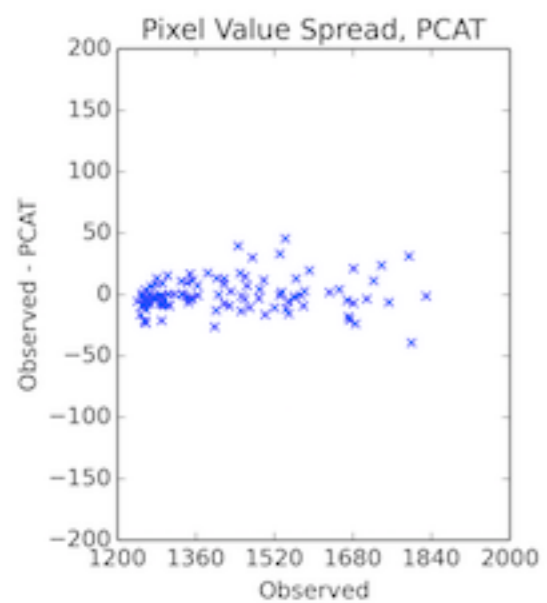
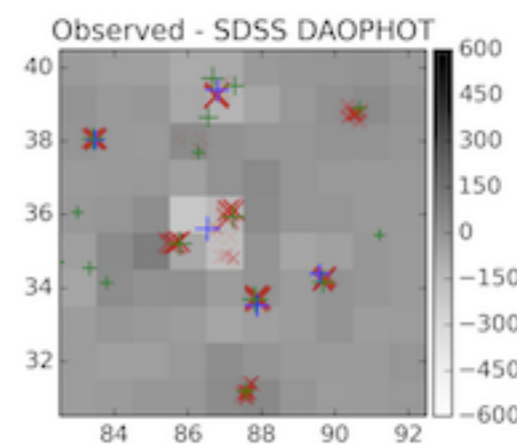
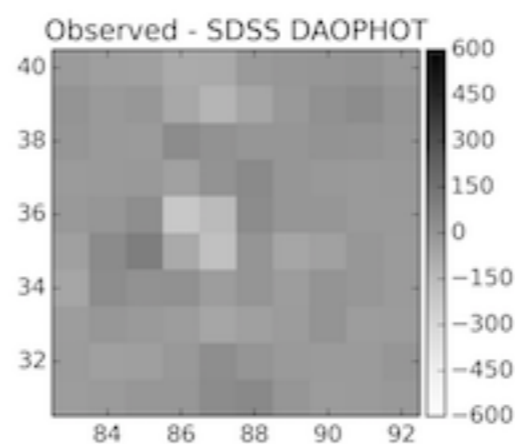
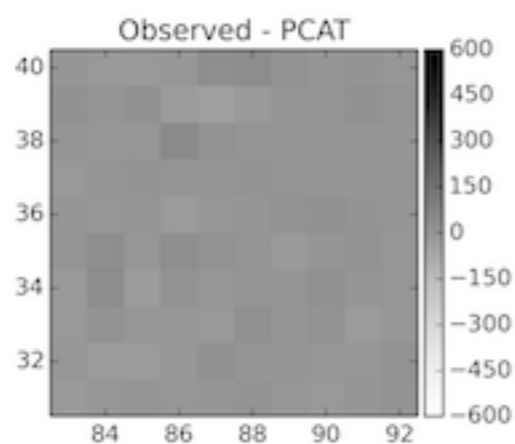
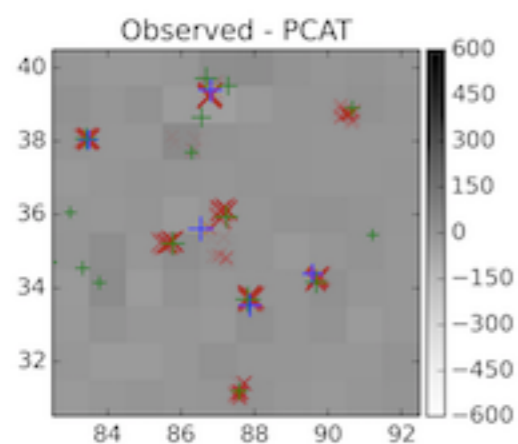
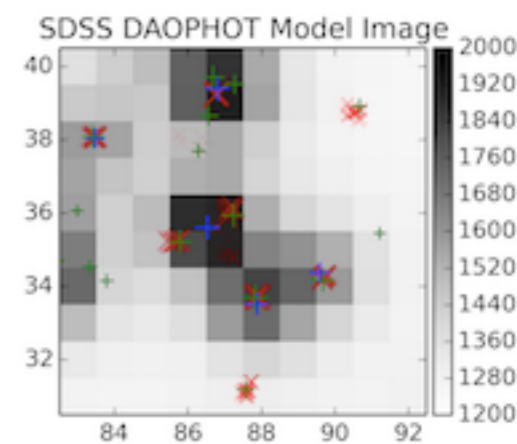
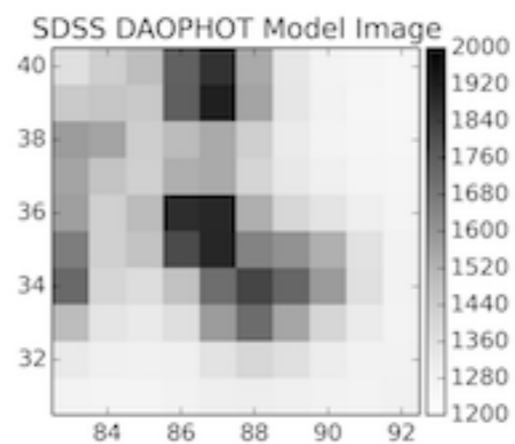
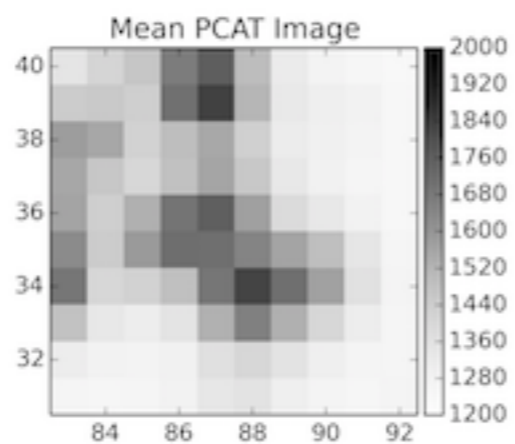
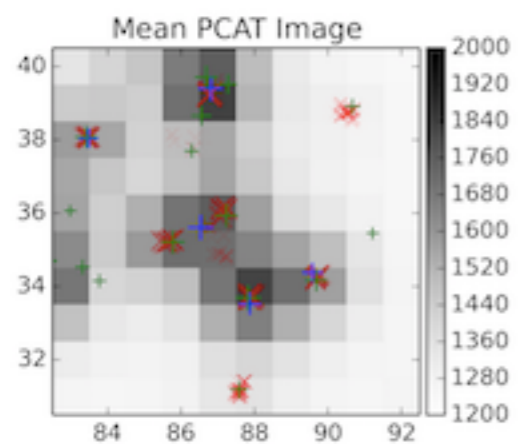
PCAT

DAOPhot

HST

Mean PCAT Image



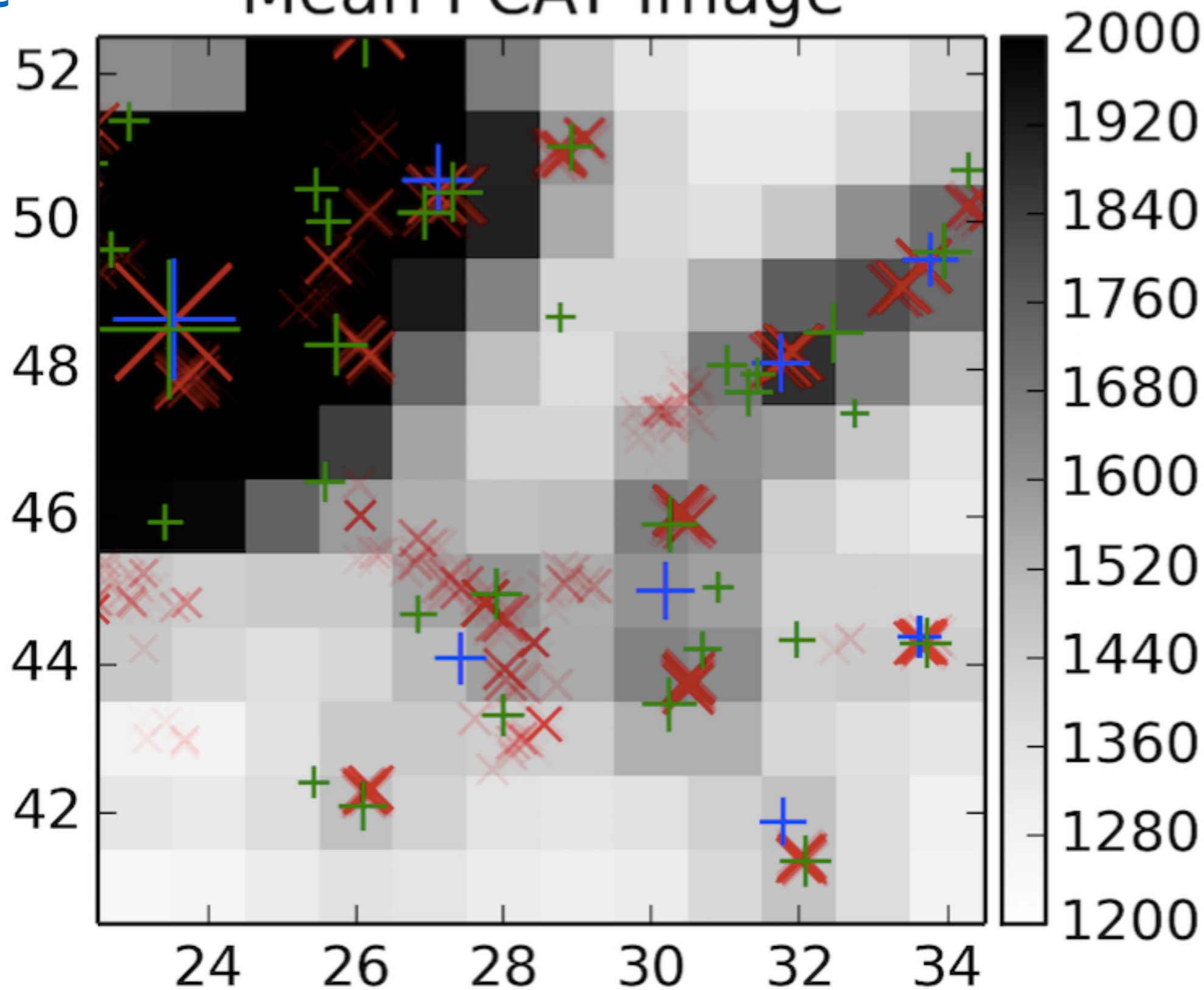


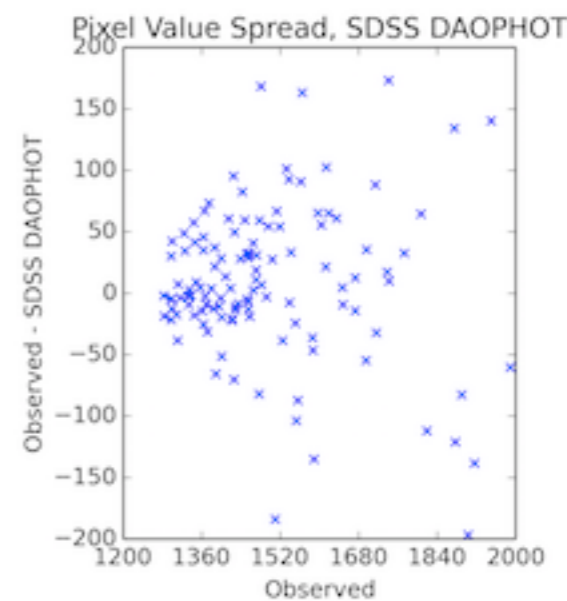
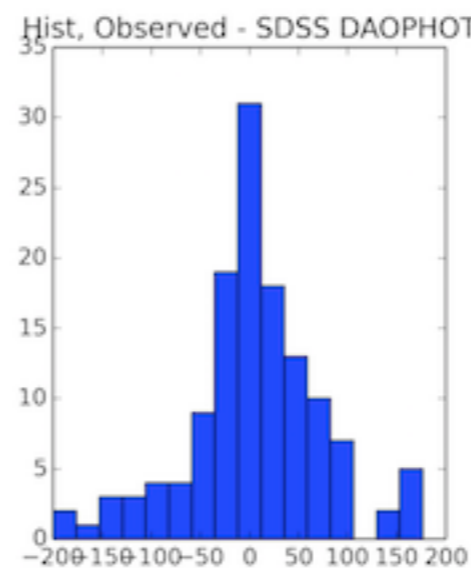
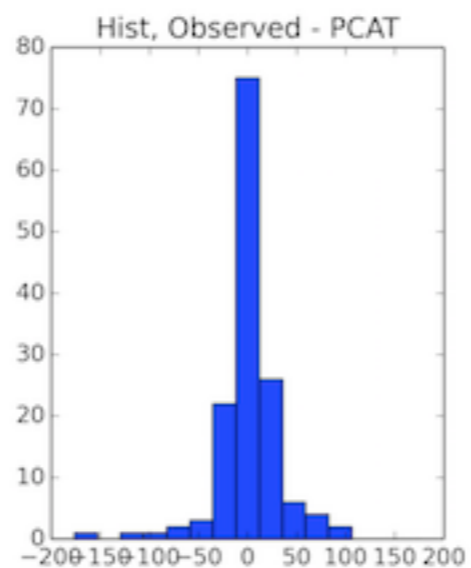
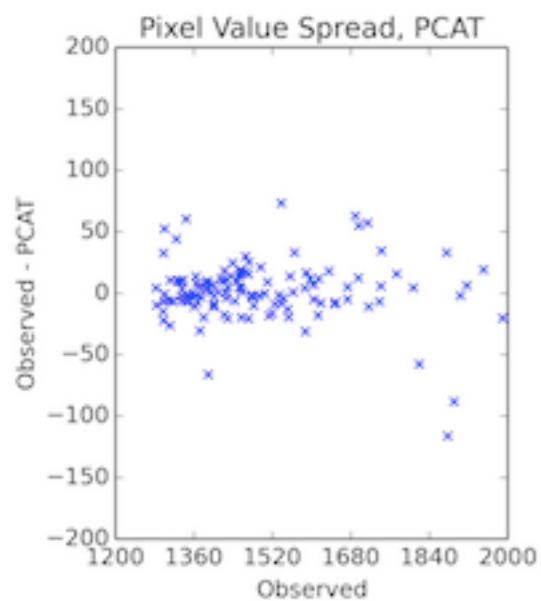
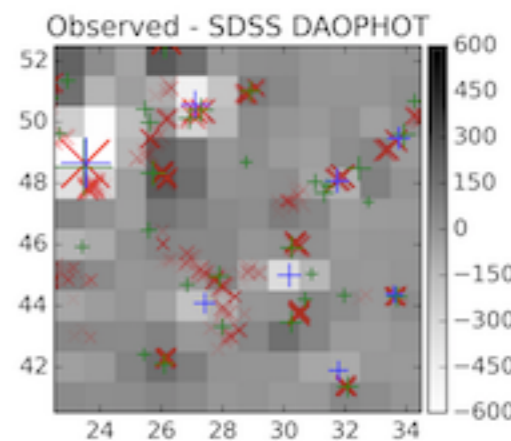
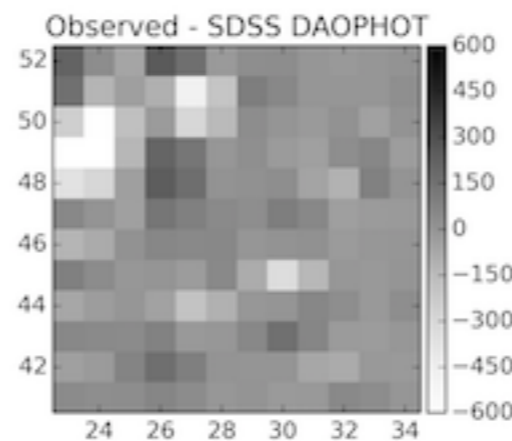
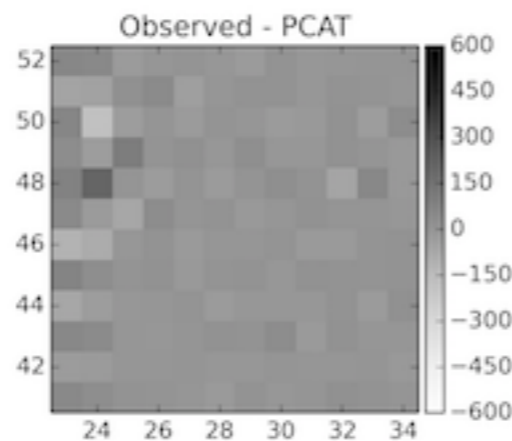
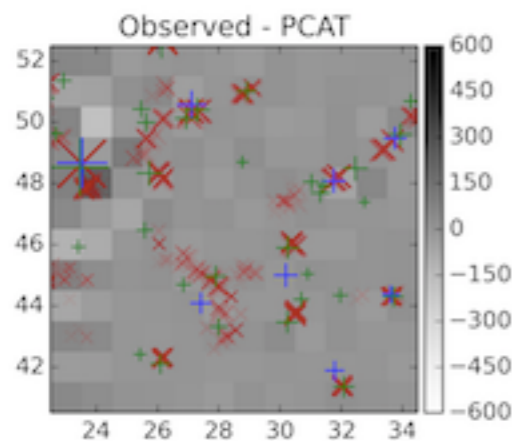
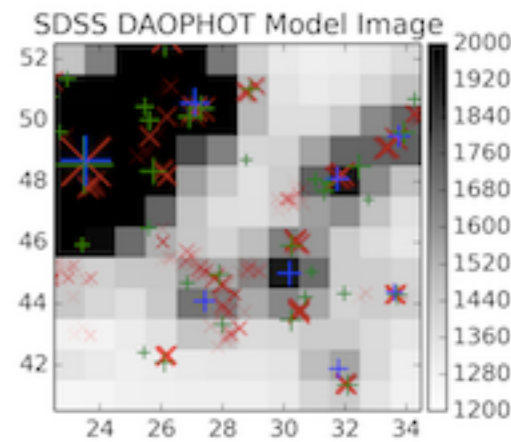
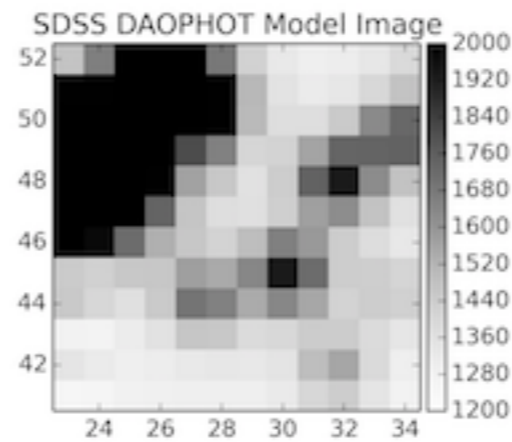
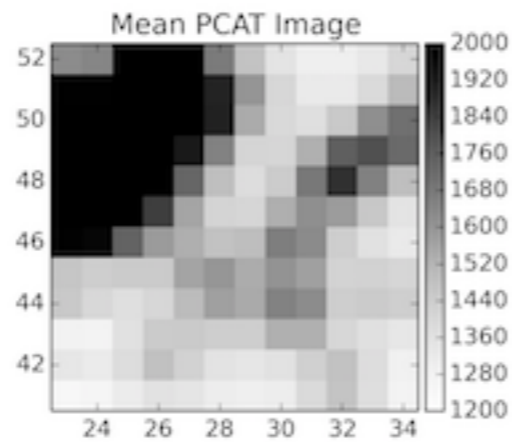
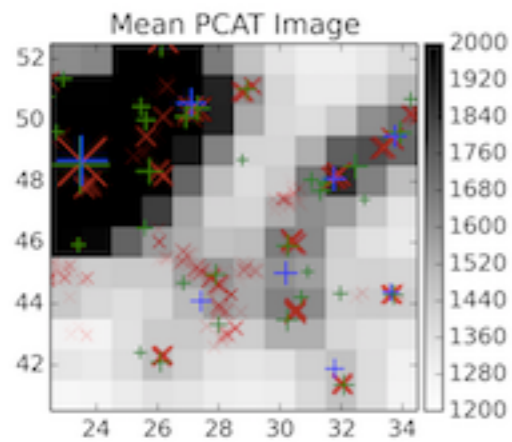
PCAT

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Mean PCAT Image



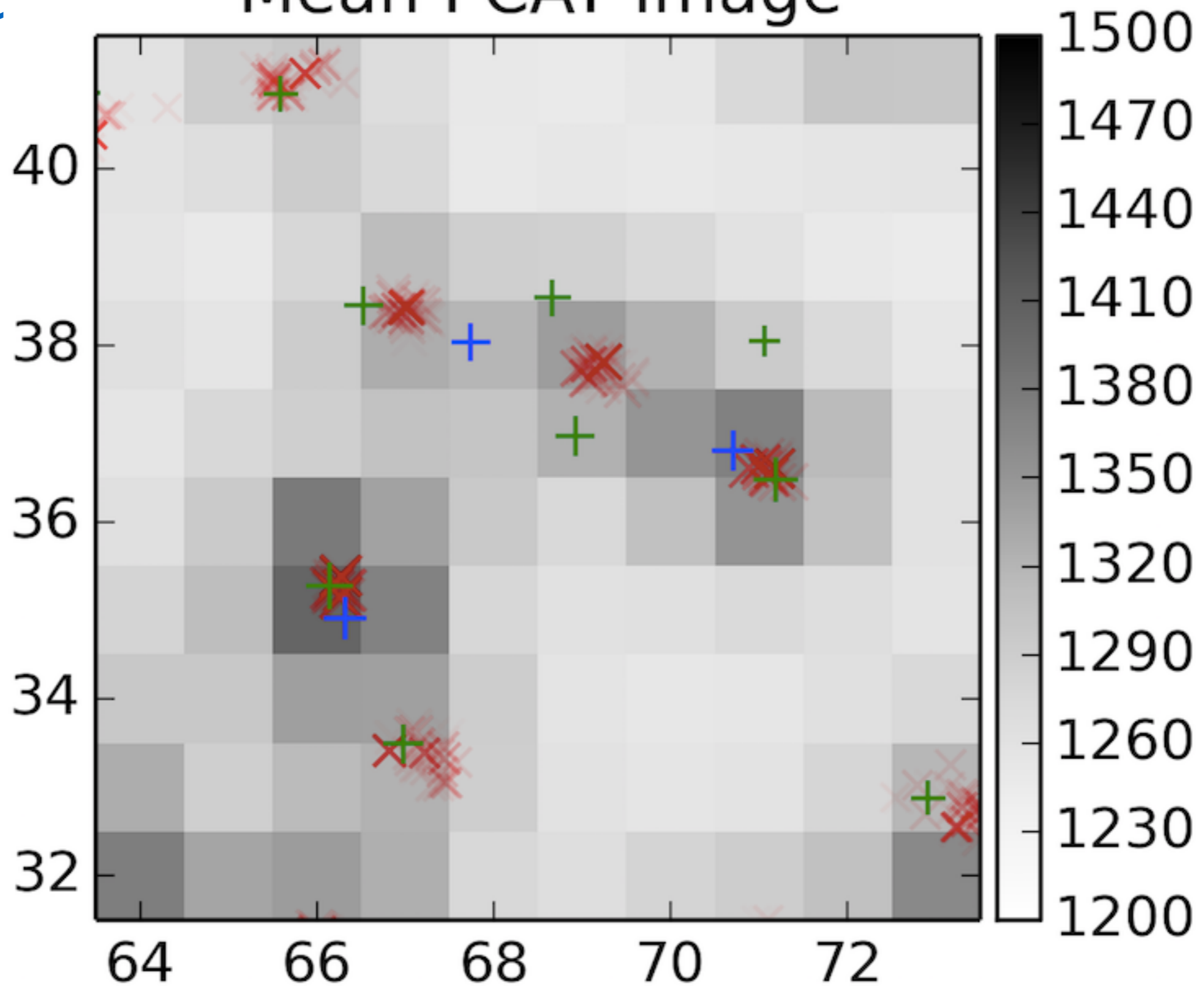


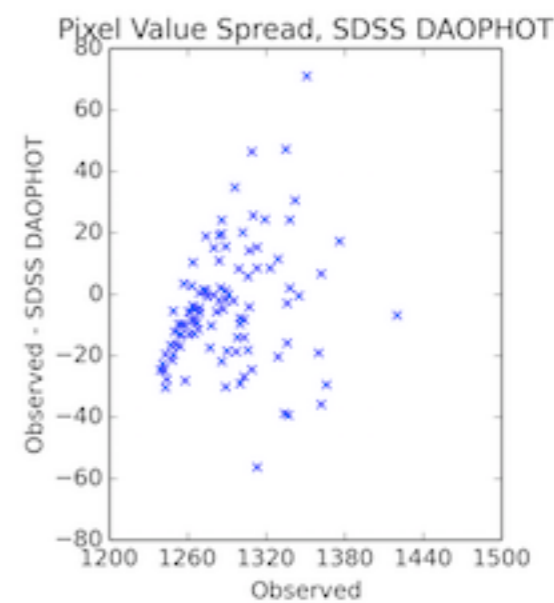
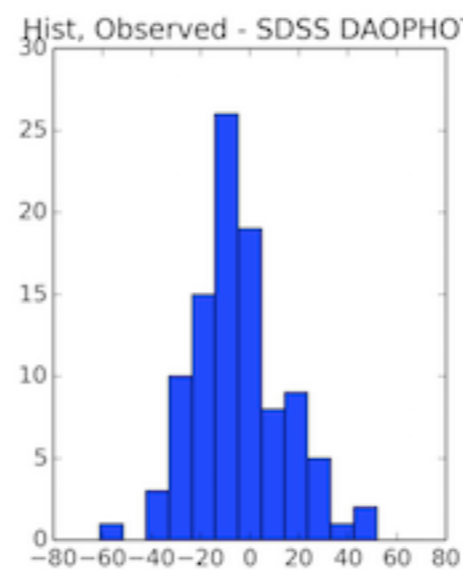
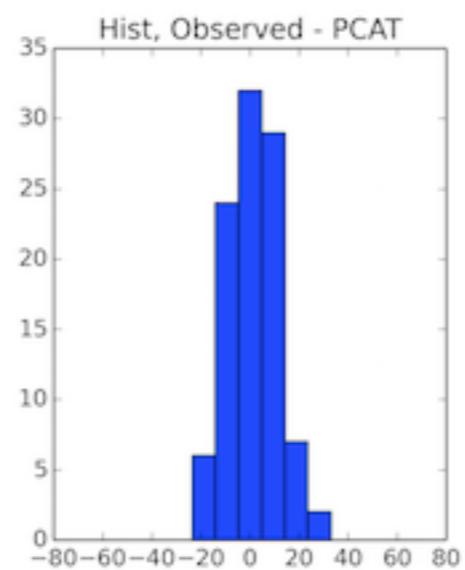
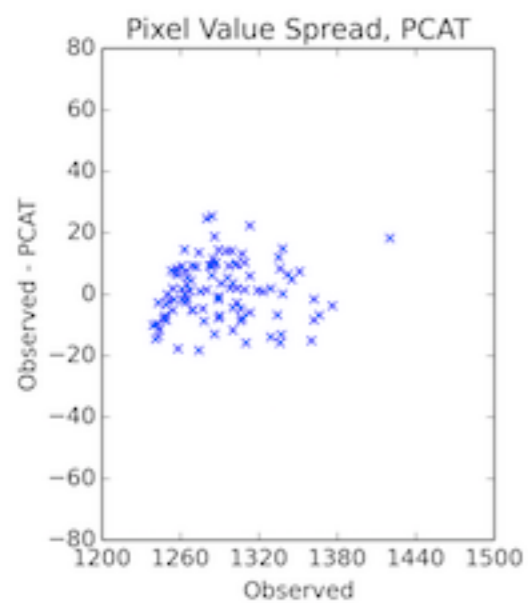
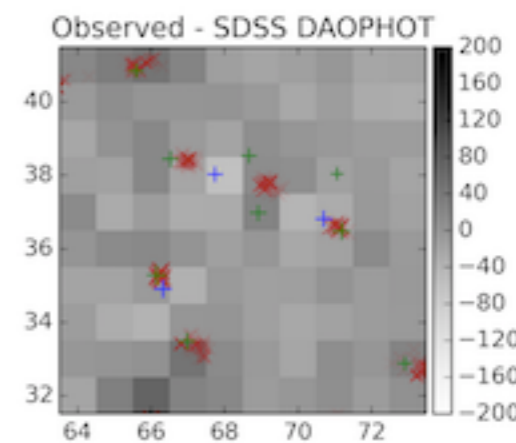
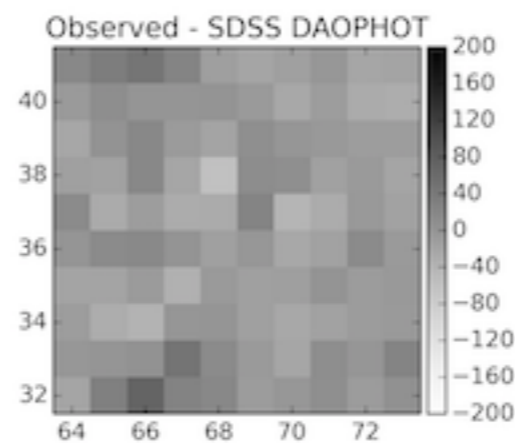
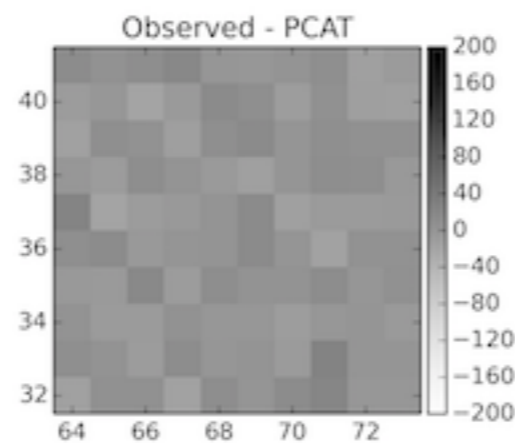
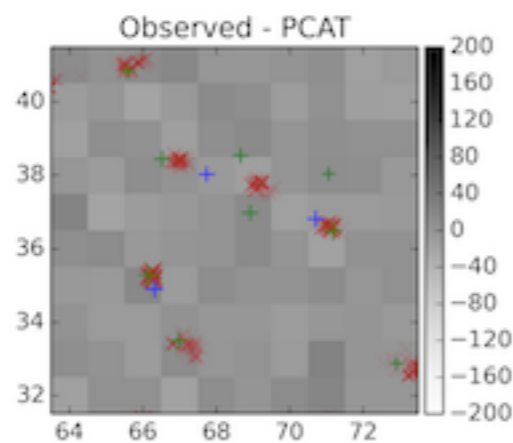
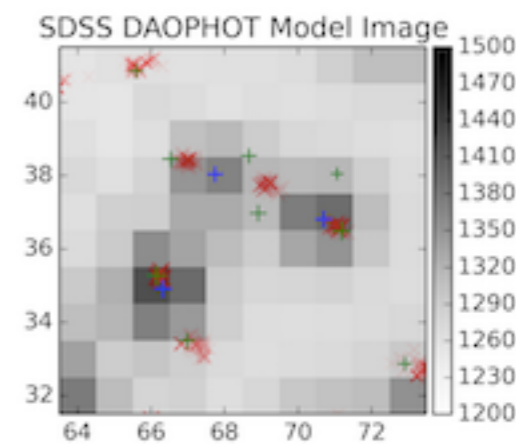
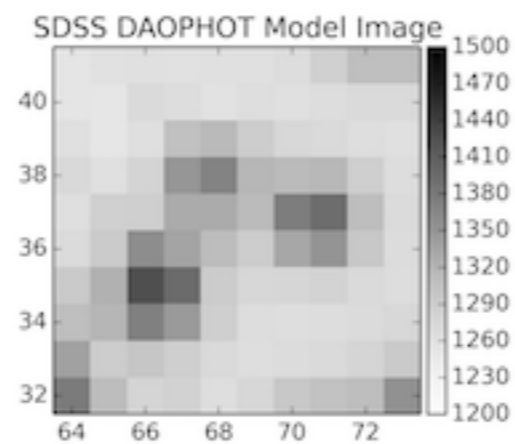
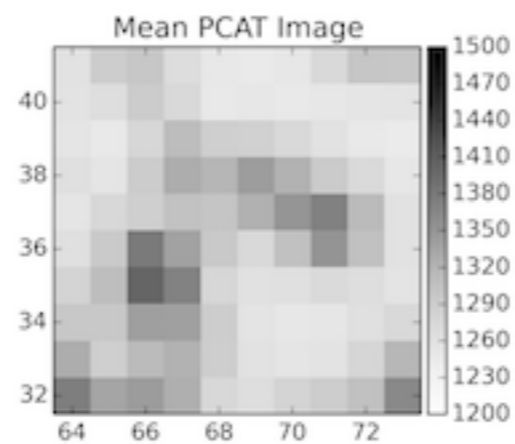
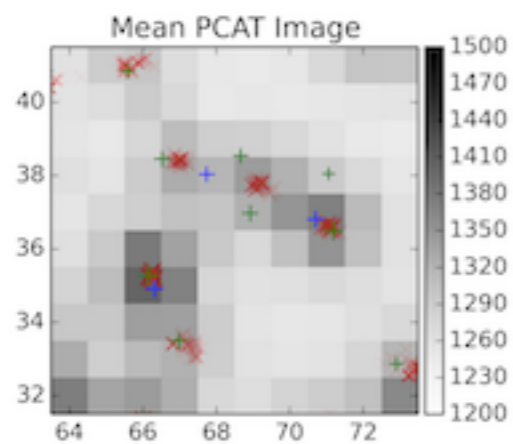
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Mean PCAT Image



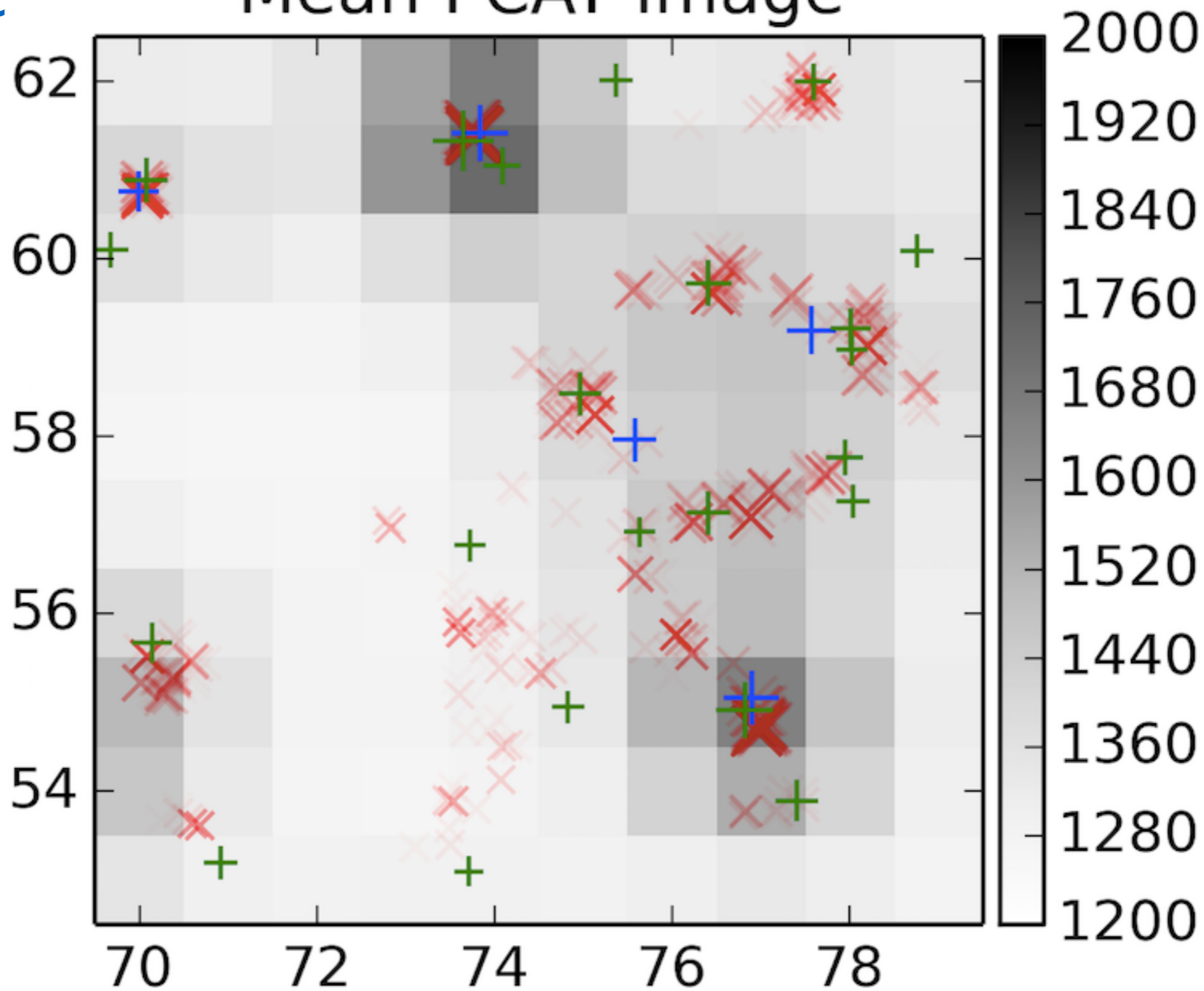


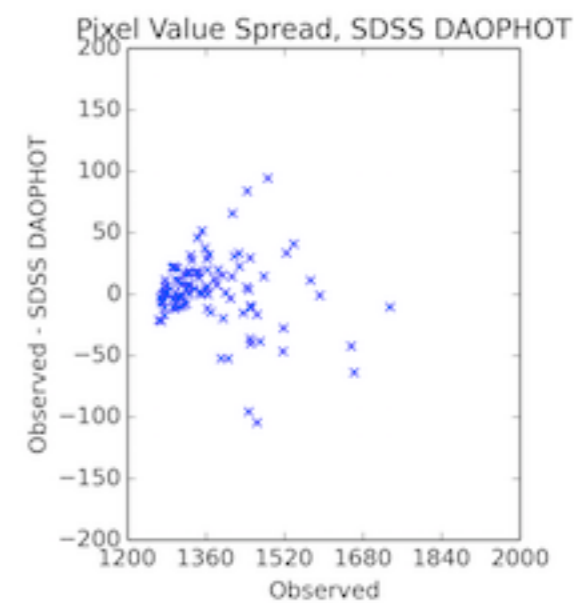
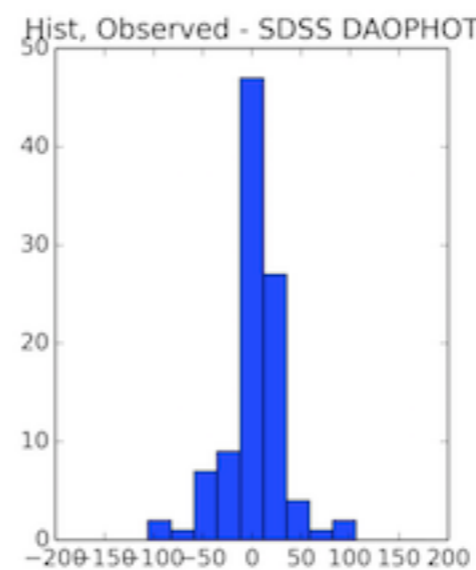
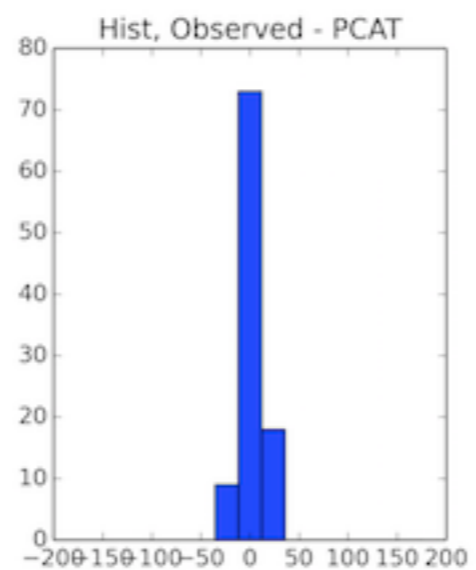
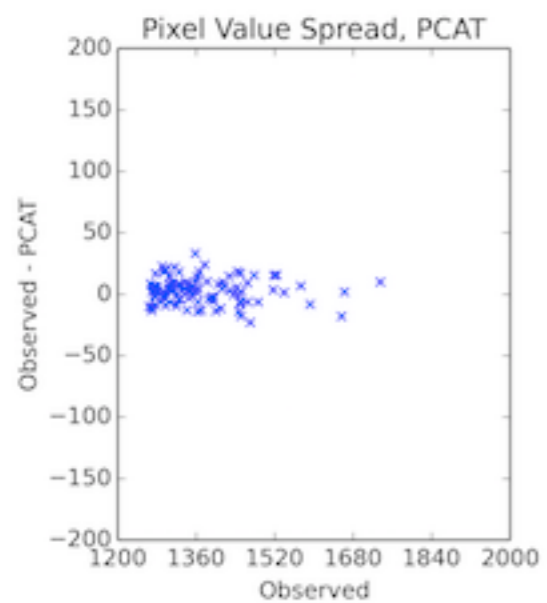
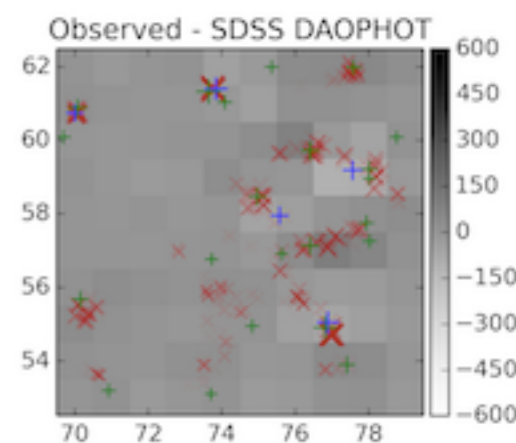
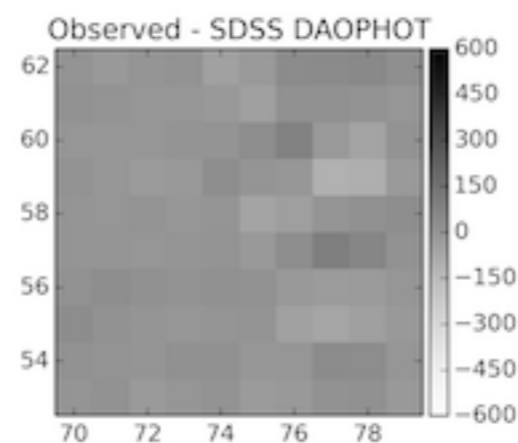
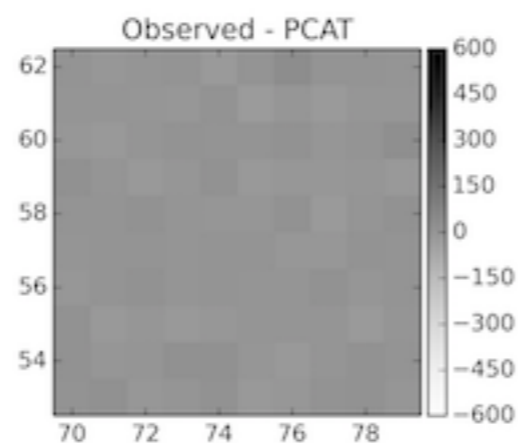
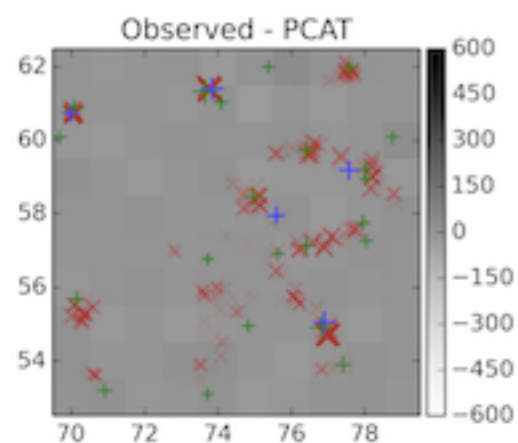
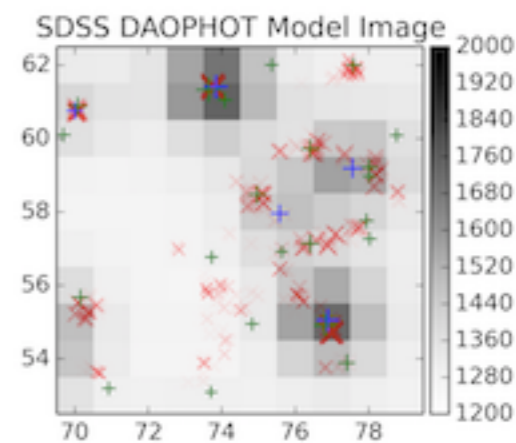
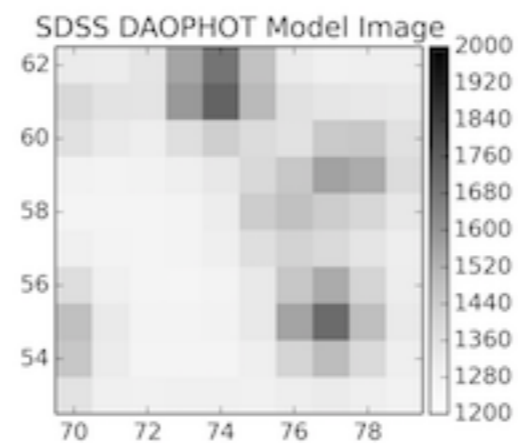
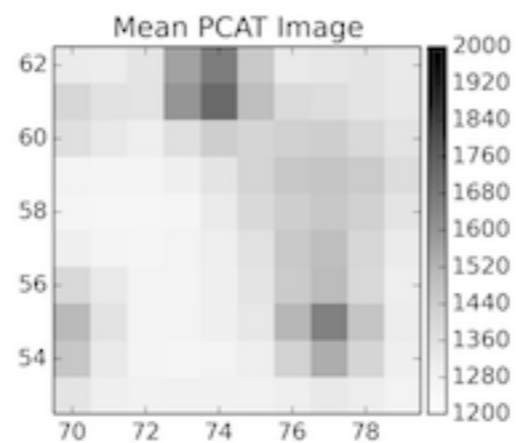
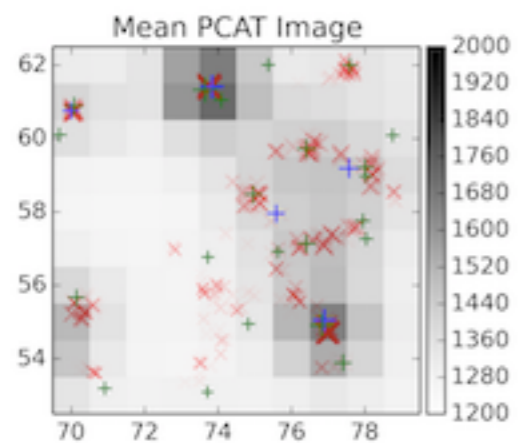
PCAT

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Mean PCAT Image

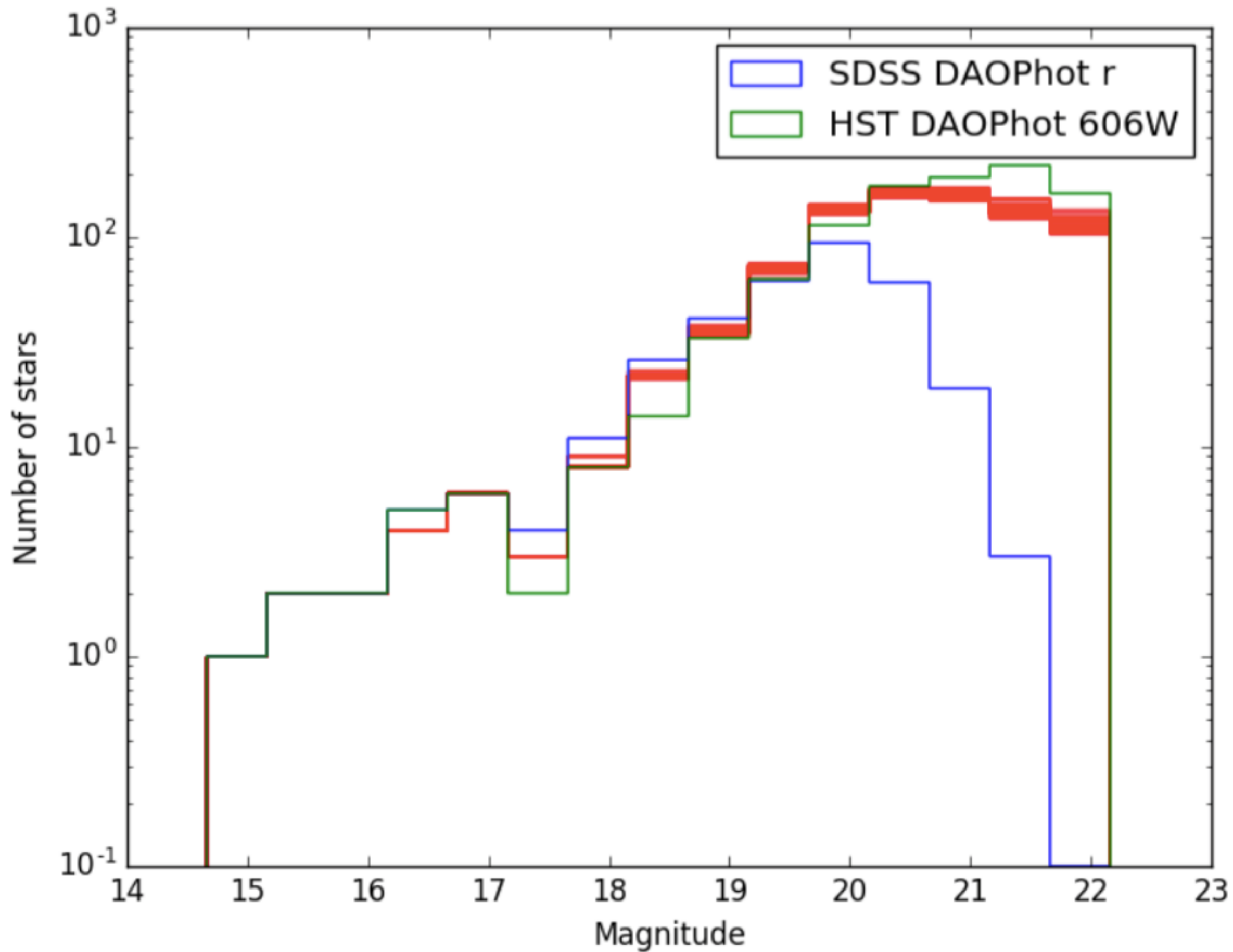




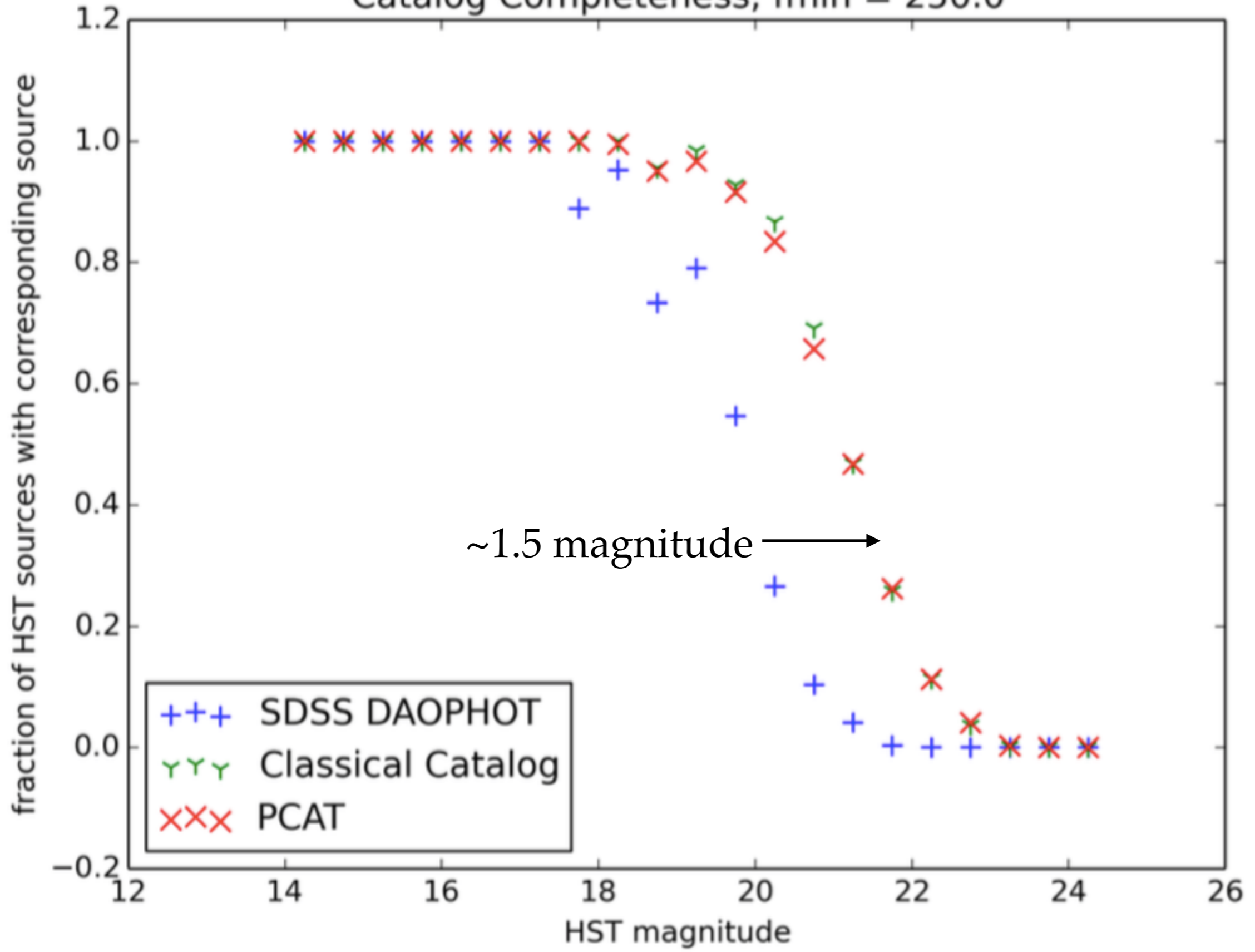
Can we recover a “classical” catalog from this?

- Confidence (% catalog samples with this object)
- {x, y, flux}
- {sigma_x, sigma_y, sigma_flux} (marginalized !)
- sigfac (by what factor is the flux error higher?)

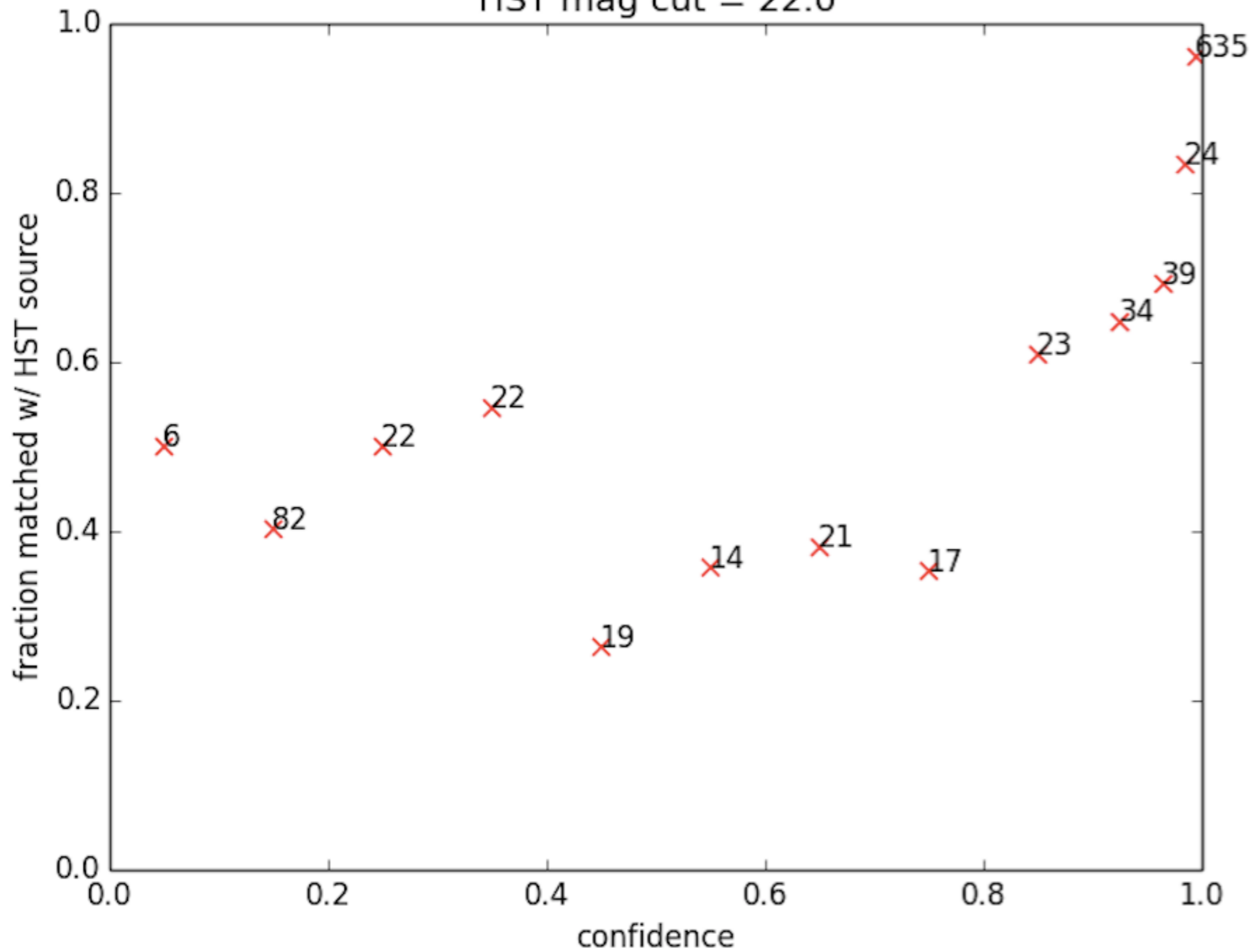
Can do this to compare to other catalogs, e.g. HST.



Catalog Completeness, fmin = 250.0



HST mag cut = 22.0



Is this too slow to ever use?

We aspire to have it be 1000x as much CPU (in core-seconds per pixel) as the SDSS pipeline. In 2025 or 2030, ~ as much a computational challenge as SDSS was in 2000. (in \$\$\$)

Advantages of a probabilistic (or ensemble) catalog:

- They are explicit about priors and hyper-priors.
- Covariances are embedded in the ensemble.
- Marginalizing over nuisance parameters is trivial.
- Propagation of errors to summary statistic is trivial.

Cons:

- More compute time / storage
- Difficult to interpret as an actual list of sources.

This might be how we will do things in 10 years.

The end