



# Lossless, Scalable IUI for Cosmological Fields

<https://arxiv.org/abs/2107.07405>

T. Lucas Makinen, *Imperial College  
London + Sorbonne University*

With Tom Charnock (IAP), Justin Alsing (U Stockholm), and Ben Wandelt (IAP)



# how to compress a universe into a few numbers (and what to do with them)

<https://arxiv.org/abs/2107.07405>

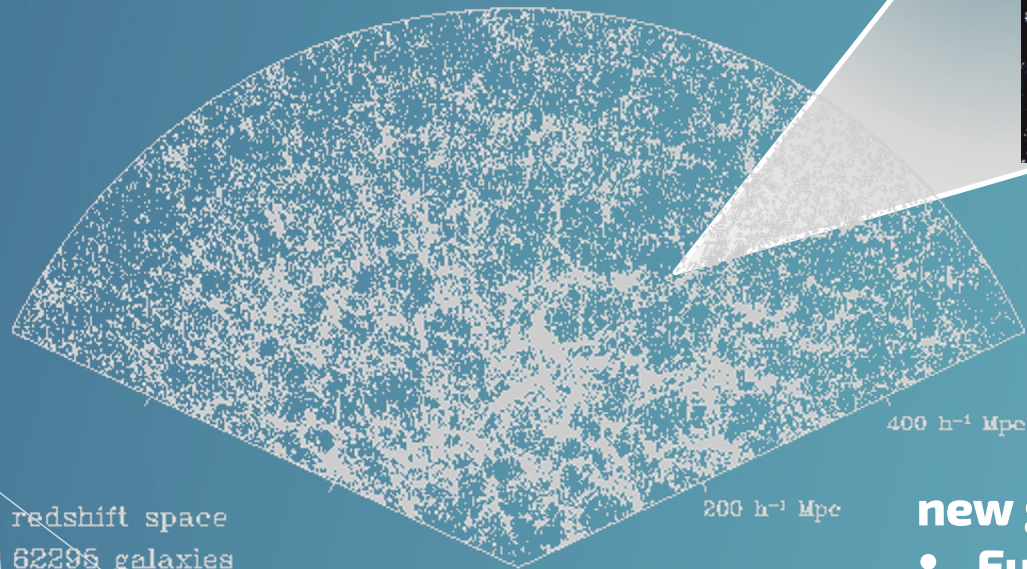
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# Cosmological Inference from large-scale structure

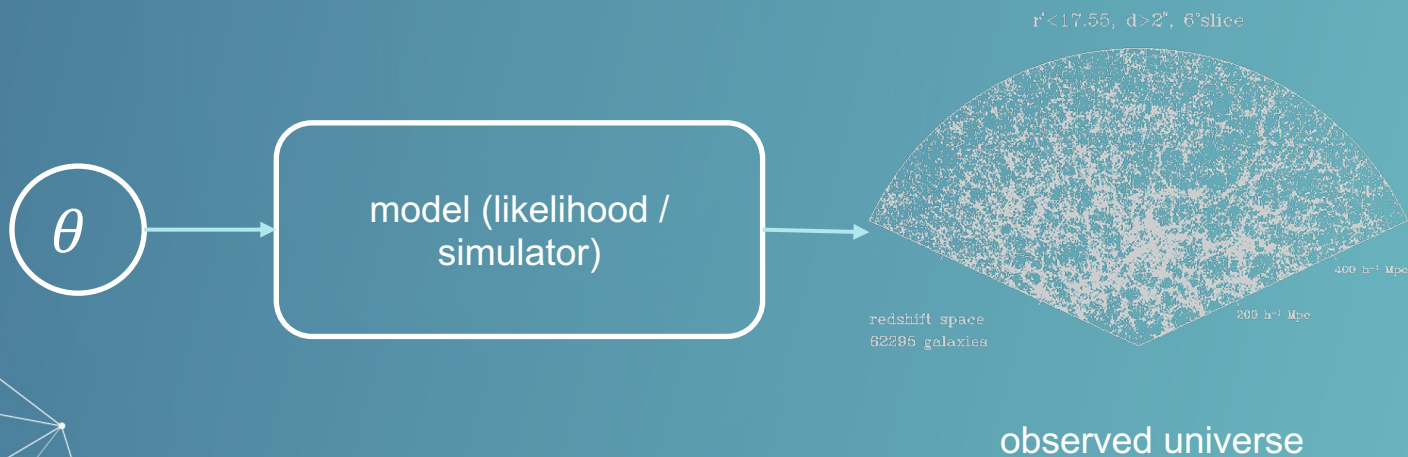
$r' < 17.55$ ,  $d > 2''$ ,  $6^\circ$  slice



- new galaxy / redshift surveys:**
- **Euclid + SKA ~1 billion galaxies each**

# Cosmological Inference from large-scale structure

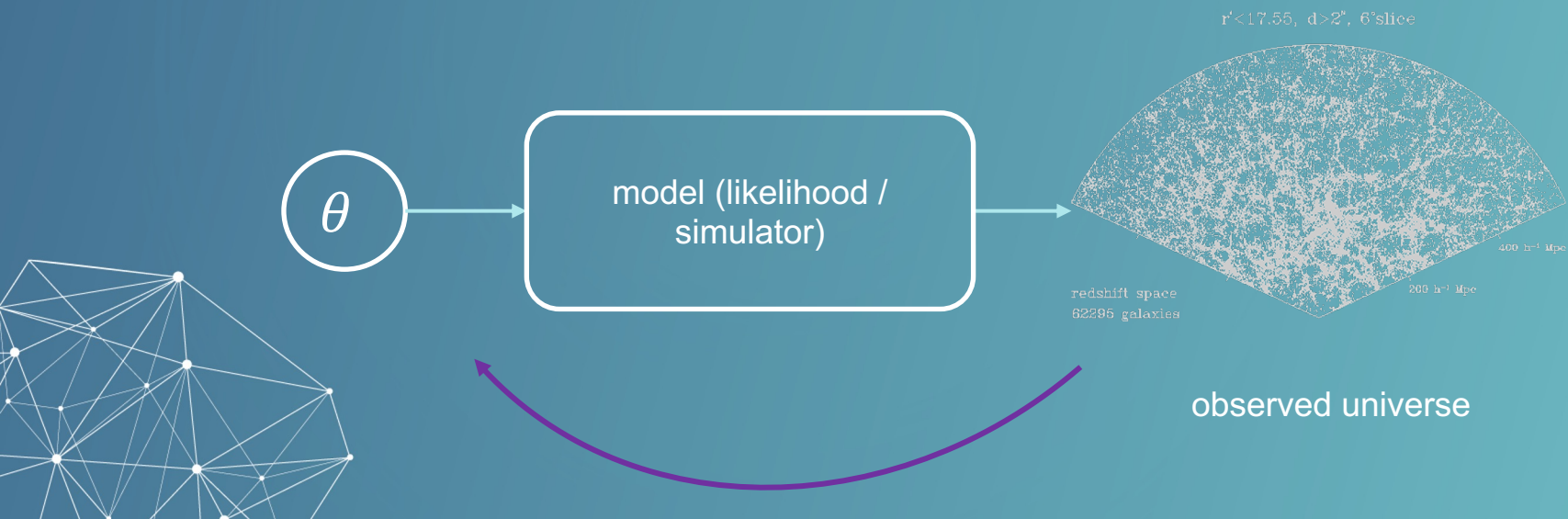
What is the probability of a given parameter,  $\theta$ , being a good descriptor of observed large scale structure ?





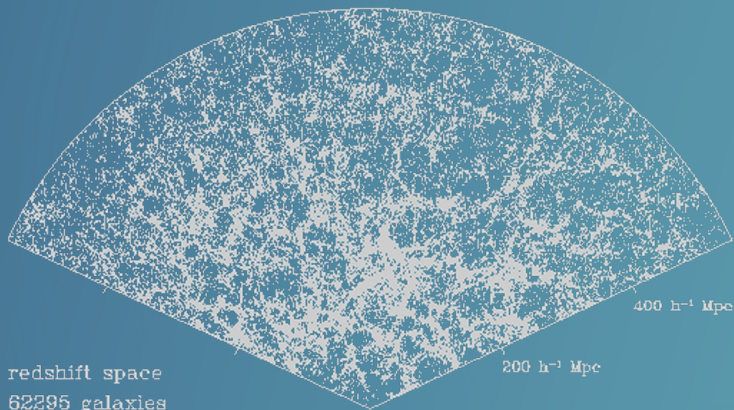
# Cosmological Inference from large-scale structure

**Inverse problem:** What is the probability of a given parameter,  $\theta$ , being a good descriptor of observed large scale structure ?



# Cosmological Inference from large-scale structure

$r' < 17.55$ ,  $d > 2''$ ,  $6^\circ$  slice

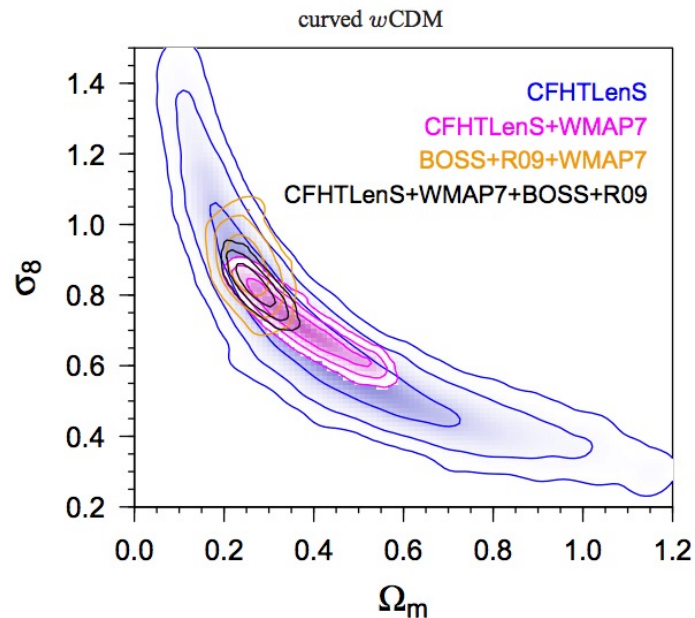
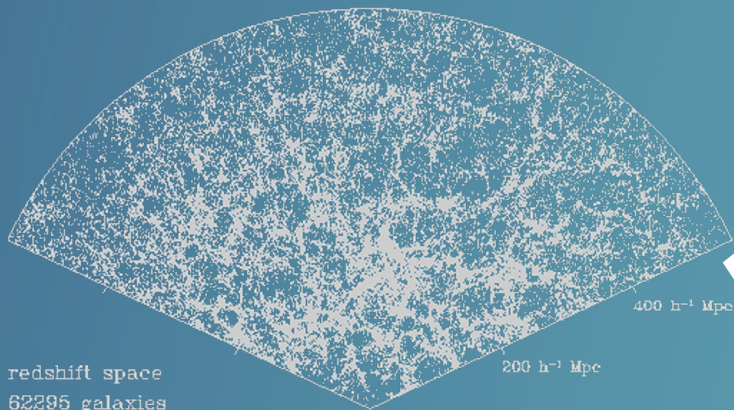


Questions:

- 1) Can we estimate distributions for cosmological parameters using the full overdensity field ?
- 2) Can we quantify the information content of the field ?

# Cosmological Inference from large-scale structure ?

$r' < 17.55$ ,  $d > 2''$ ,  $6^\circ$  slice



# ILI: Implicit Likelihood Inference

$$p(\theta|\mathbf{d}) \propto p(\mathbf{d}|\theta)p(\theta)$$

$\mathcal{L}(\mathbf{d}|\theta) = p(\mathbf{d}|\theta)$ : **likelihood** (simulator)

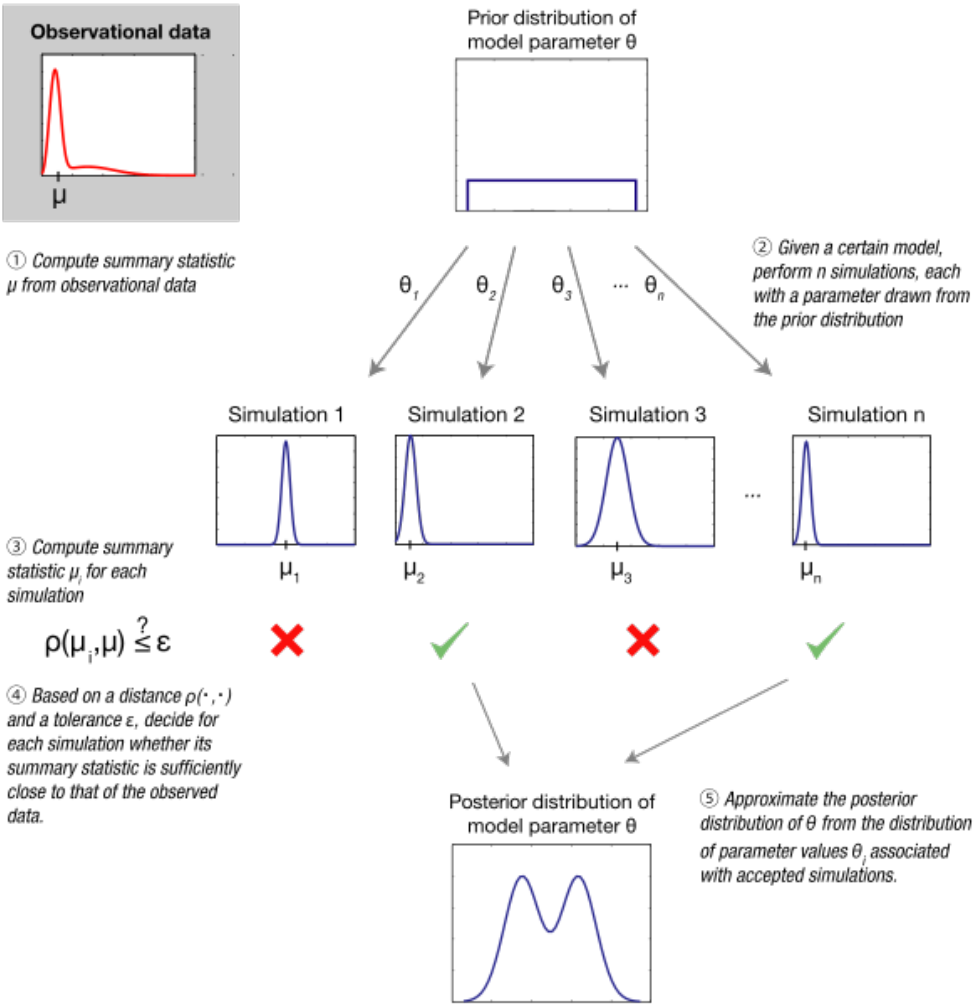
$p(\theta)$ : prior

○ Pros	○ Cons
<ul style="list-style-type: none"><li>○ Can forward-simulate everything ! Universe + dust + telescope effects ...</li><li>○ No analytic description needed</li></ul>	<ul style="list-style-type: none"><li>○ Sims are huge ! How do we compare the distance from one simulation to a target observation ?</li></ul>





# Approximate Bayesian Computation

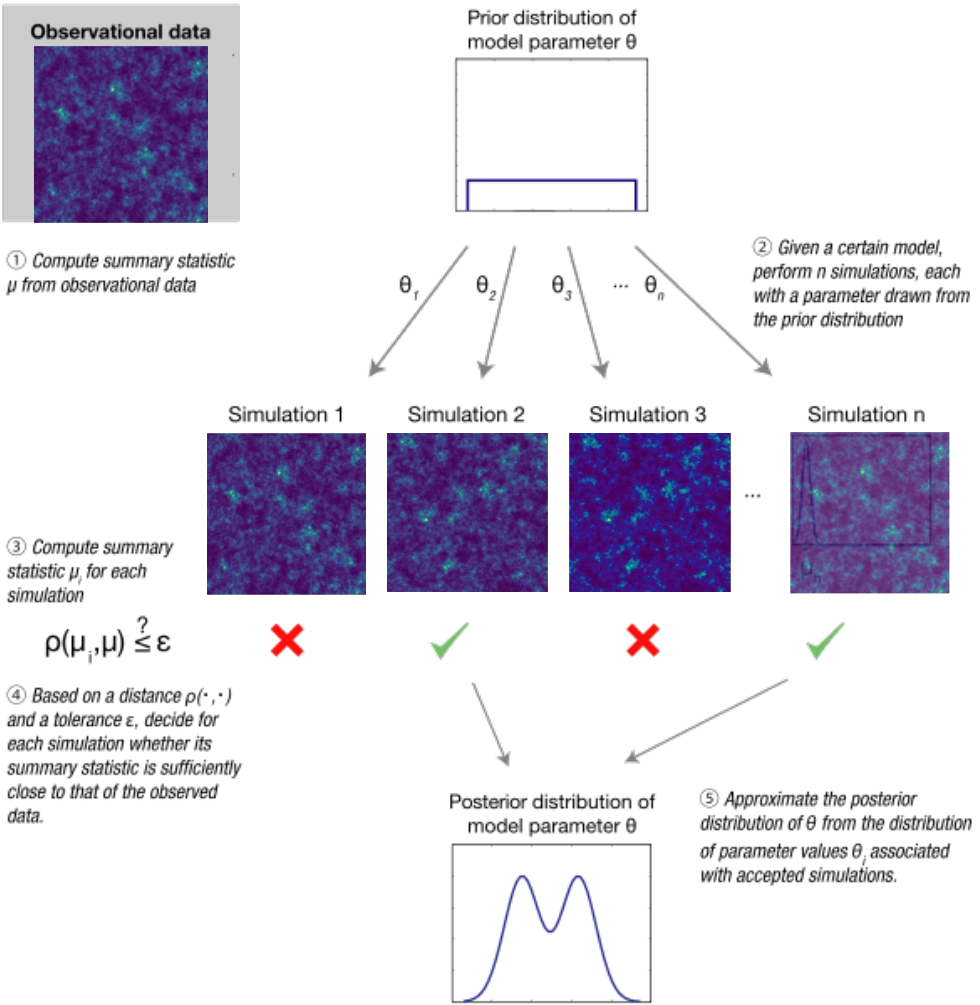


- 1) Compress observed  $d$  to  $\mu$
  - 2) For  $i$  simulation, compute distance  $\rho(\mu, \hat{\mu})$
- if  $\rho < \epsilon$ , keep simulation.

PRO: can sample arbitrary distributions

CON: very expensive for large simulations and wide prior ranges

# Approximate Bayesian Computation



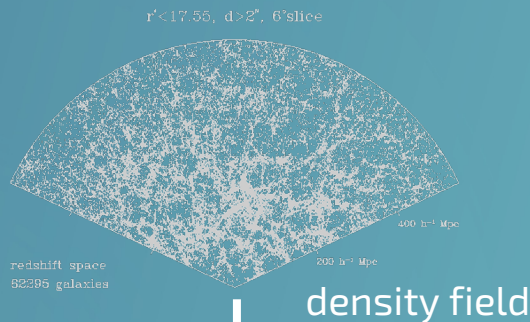
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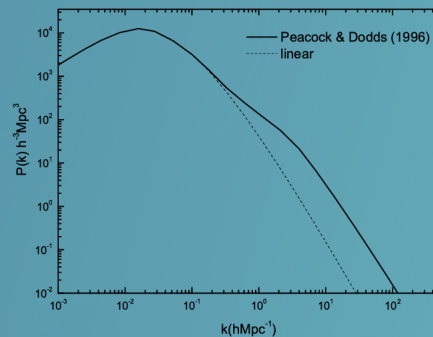
CON: very expensive for large simulations and wide prior ranges

HOW DO WE DEFINE OUR SUMMARY STATISTIC FOR LARGE SCALE STRUCTURE ?

# Large Scale Structure Compression ?



+ noise  
+ survey effects ?

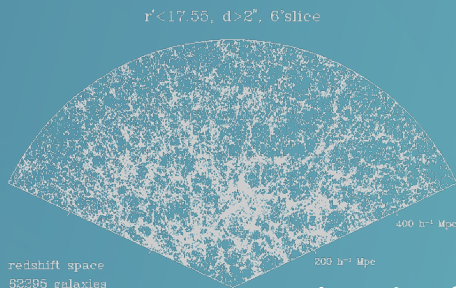


power spectrum



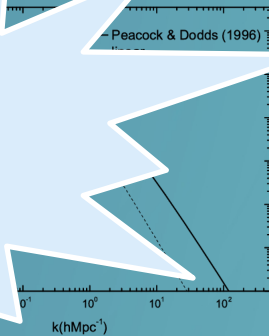
# Large Scale Structure Compression ?

d



+ noise  
+ survey effects ?

DOES THIS  
CAPTURE ALL THE  
INFORMATION ?  
(NO)

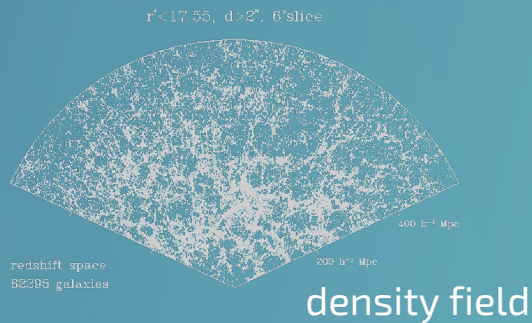


power spectrum

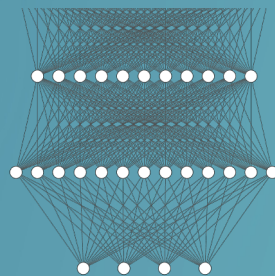




# Large Scale Structure Compression ?



+ noise  
+ survey effects ?



neural compression to summaries



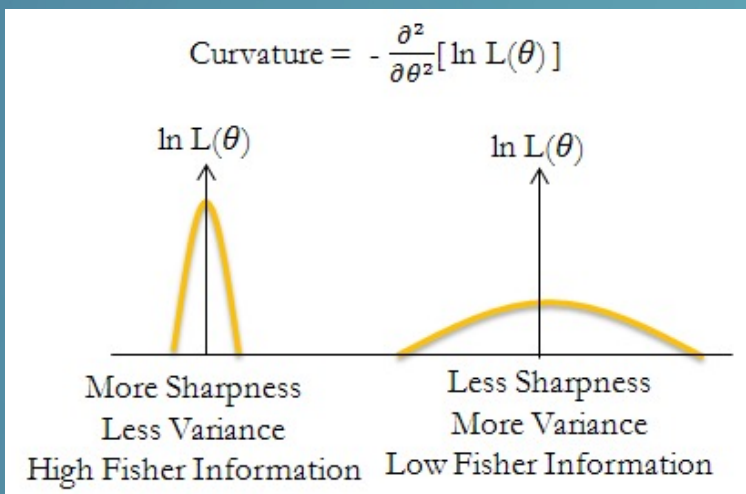
**Fisher information:** tells us (on average) how informative some data  $\mathbf{d}$  is about a parameter  $\theta$  of a distribution,  $\mathcal{L}(\mathbf{d}|\theta)$  that models  $\mathbf{d}$

$$\mathbf{F}_{\alpha\beta} = - \left\langle \frac{\partial^2 \ln \mathcal{L}}{\partial \theta_\alpha \partial \theta_\beta} \right\rangle_{\theta = \theta_{\text{fid}}}$$

Think of this as the *curvature* of the log-likelihood,  $\ln \mathcal{L}$  at  $\theta_{\text{fid}}$



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**Example:** draw  $n_d$  independent datapoints from a normal distribution,  $\mathcal{N}(\mu, \sigma)$ . Then the likelihood is:

$$\mathcal{L}(\mathbf{d}|\mu, \sigma) = \prod_{i=1}^{n_d} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2} \frac{(d_i - \mu)^2}{\sigma^2}\right)$$

And the Fisher matrix is:

$$F = - \left\langle \frac{\partial^2 \ln \mathcal{L}}{\partial \theta_\alpha \partial \theta_\beta} \right\rangle_{\theta_{\text{fid}}} = \begin{pmatrix} \frac{-n_d}{\sigma} & 0 \\ 0 & \frac{-n_d}{2\sigma^2} \end{pmatrix}_{\sigma_{\text{fid}}}$$





**Fisher information:** tells us (on average) how informative some data  $\mathbf{d}$  is about a parameter  $\theta$  of a distribution,  $\mathcal{L}(\mathbf{d}|\theta)$  that models  $\mathbf{d}$

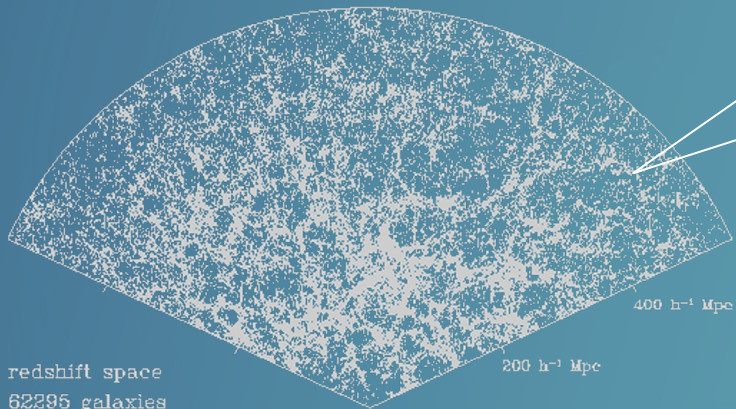
Cramer-Rao bound:

$$\langle (\theta_\alpha - \langle \theta_\alpha \rangle)(\theta_\beta - \langle \theta_\beta \rangle) \rangle \geq \mathbf{F}_{\alpha\beta}^{-1}$$

Gives us a lower bound for the (average) variance of a parameter estimate



$r' < 17.55$ ,  $d > 2''$ ,  $6^\circ$  slice



redshift space  
62295 galaxies

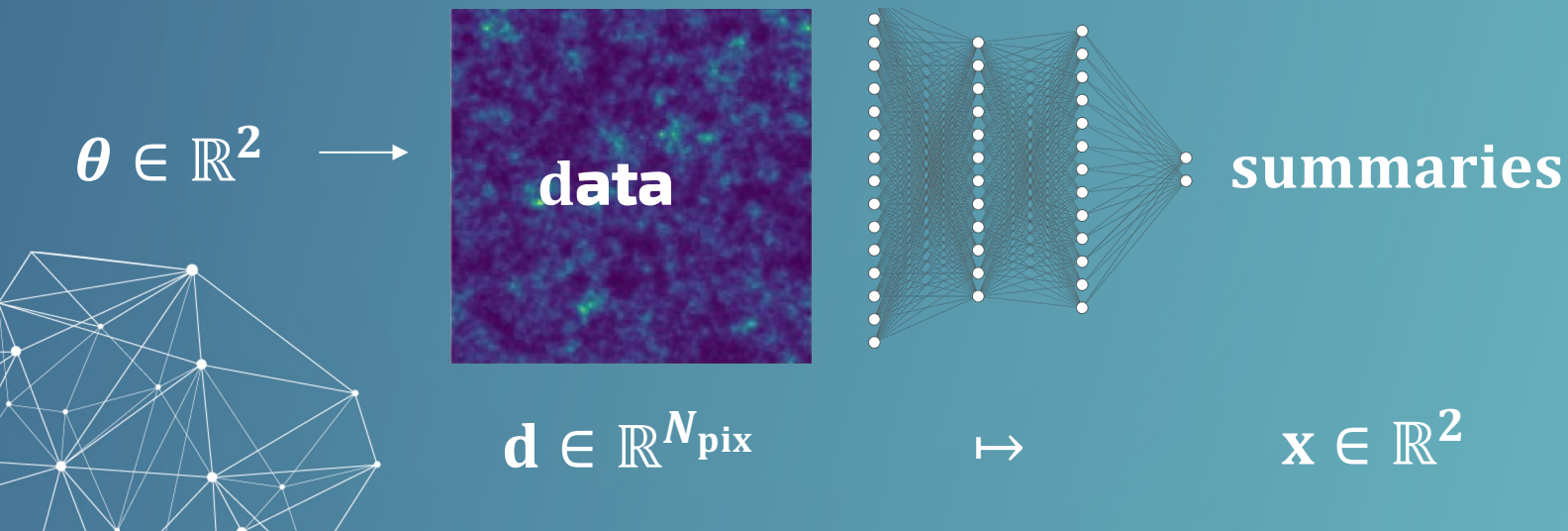
What if we could compress the universe  
down to a handful of numbers *with the  
same information content as the full  
field* ?



# Information Maximising Neural Networks

Can we train a neural network to compress a universe simulation down to a couple of numbers ?

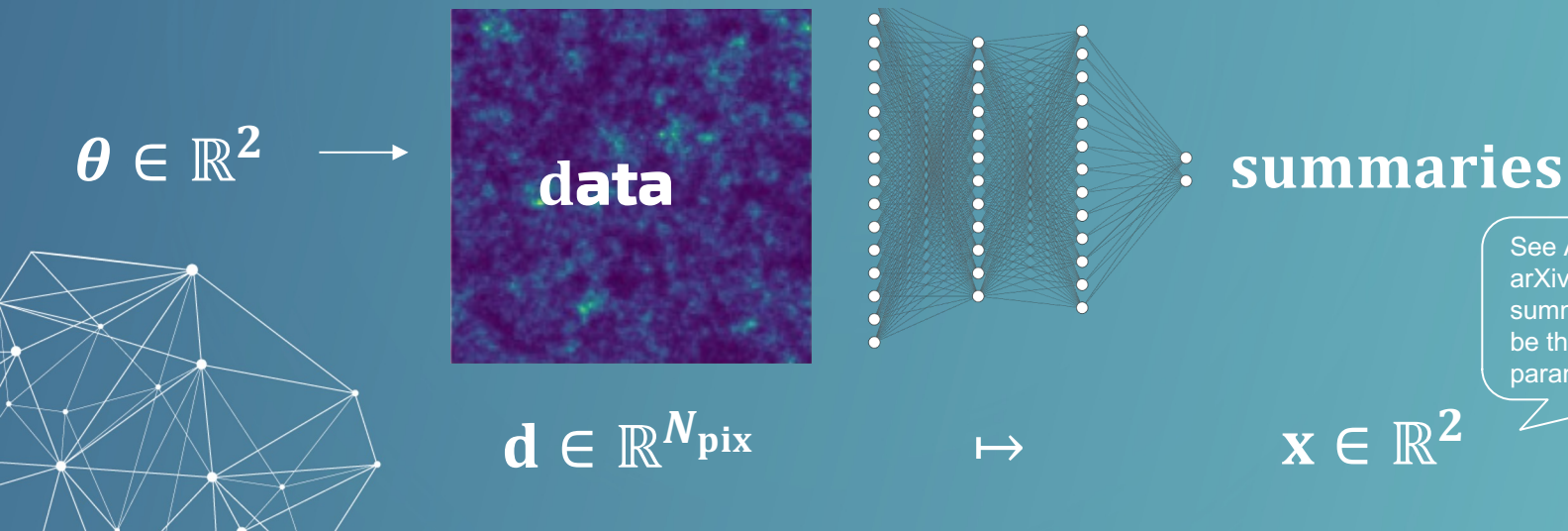
$$f: \mathbf{d} \mapsto \mathbf{x}$$



# Information Maximising Neural Networks

Can we train a neural network to compress a universe simulation down to a couple of numbers ?

$$f: \mathbf{d} \mapsto \mathbf{x}$$



See Alsing & Wandelt (2018)  
arXiv:1712.00012 for why  
summary space is taken to  
be the same dimension as  
parameter space



# Information Maximising Neural Networks

1) adopt a Gaussian likelihood form to compute our Fisher information:

$$-2 \ln \mathcal{L}(\mathbf{x}|\mathbf{d}) = \left( \mathbf{x} - \boldsymbol{\mu}_f(\boldsymbol{\theta}) \right)^T \mathbf{C}_f^{-1} \left( \mathbf{x} - \boldsymbol{\mu}_f(\boldsymbol{\theta}) \right)$$

Mean and covariance of network outputs



# Information Maximising Neural Networks

1) adopt a Gaussian likelihood form to compute our Fisher information:

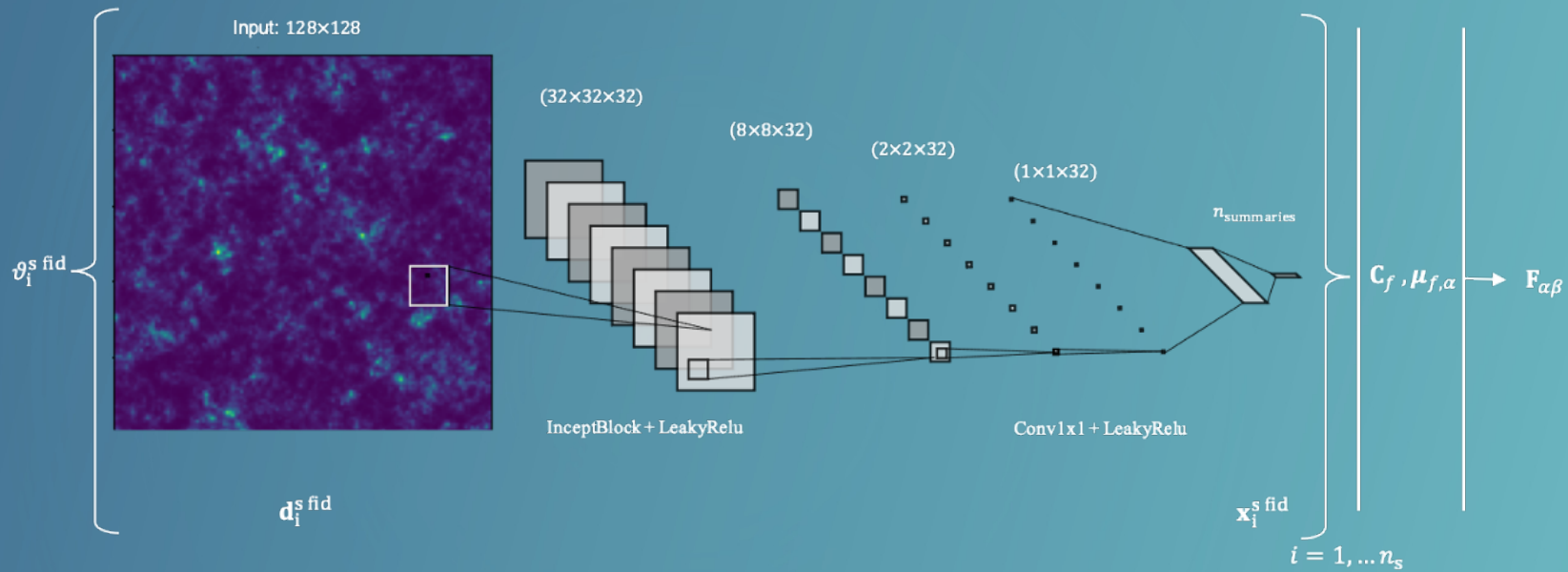
$$-2 \ln \mathcal{L}(\mathbf{x}|\mathbf{d}) = (\mathbf{x} - \boldsymbol{\mu}_f(\boldsymbol{\theta}))^T \mathbf{C}_f^{-1} (\mathbf{x} - \boldsymbol{\mu}_f(\boldsymbol{\theta}))$$

2) Compute IMNN Fisher:

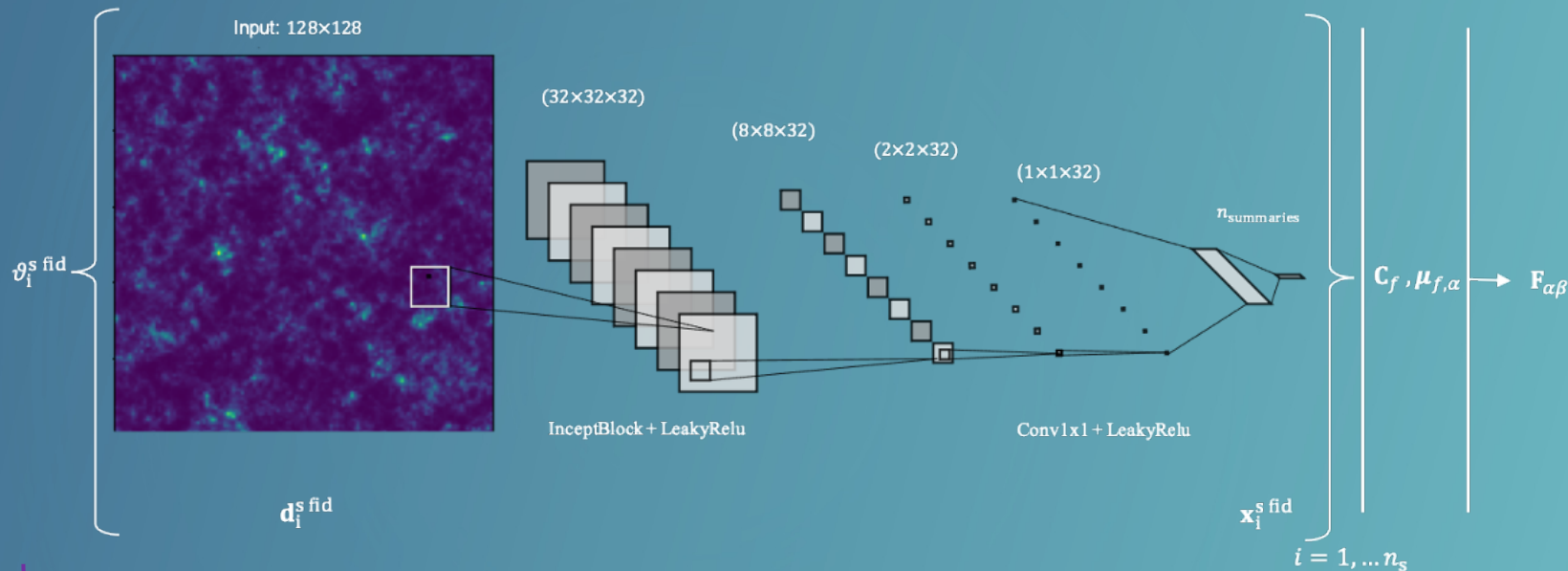
$$\mathbf{F}_{\alpha\beta} = \text{tr}[\boldsymbol{\mu}_{f,\alpha}^T \mathbf{C}_f^{-1} \boldsymbol{\mu}_{f,\beta}]$$

3) train until Fisher information is maximised *at a fiducial model*

# Main IMNN Scheme



# Main IMNN Scheme



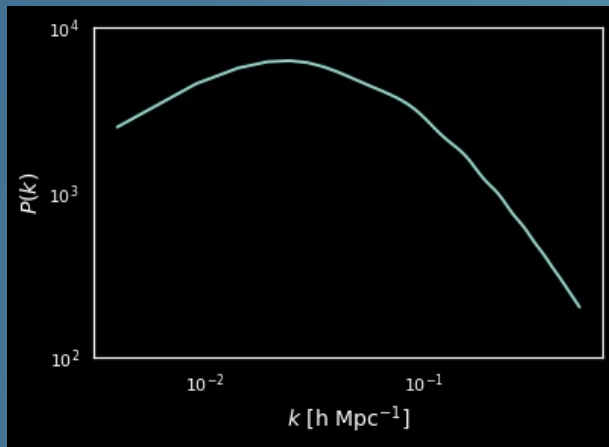
Completely differentiable in Jax !

# Inference for Mock Dark Matter fields

1. Train IMNN compression on simulations of a fiducial universe with parameters  $\theta_{\text{fid}}$
2. Observe + compress observed universe to get estimates for  $\theta_{\text{target}}$
3. Using compression, simulate universes over prior distribution  $p(\theta)$  to obtain posterior  $p(\theta | \mathbf{d})$



# Inference for Mock Dark Matter fields



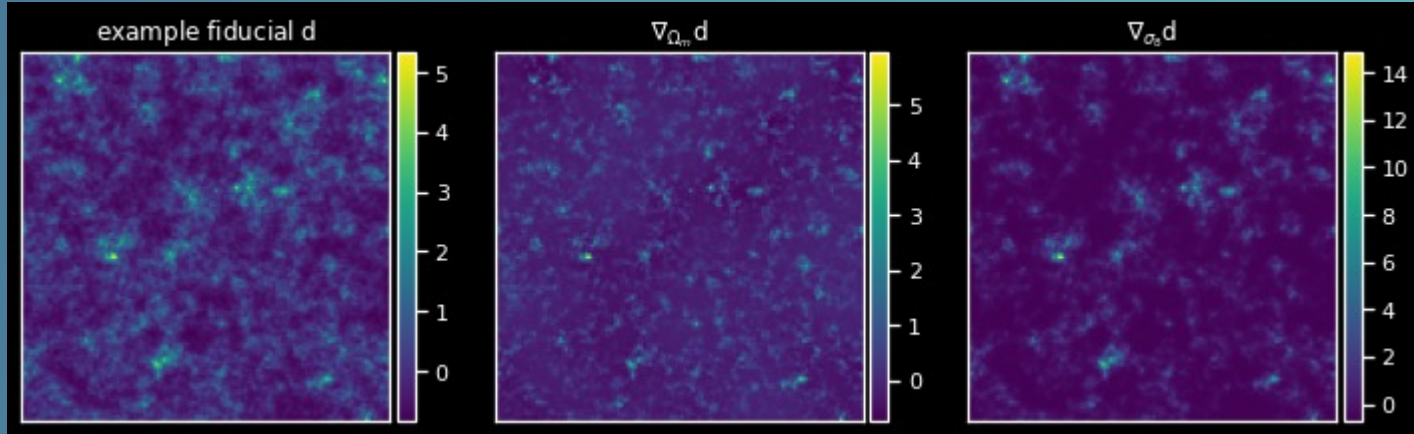
Train compression on 128x128  
fiducial lognormal field simulations  
generated from Eisenstein-Hu  $P(k)$ ,  
with fiducial parameters:

$$\theta_{\text{fid}} = (\Omega_c, \sigma_8) = (0.6, 0.6)$$



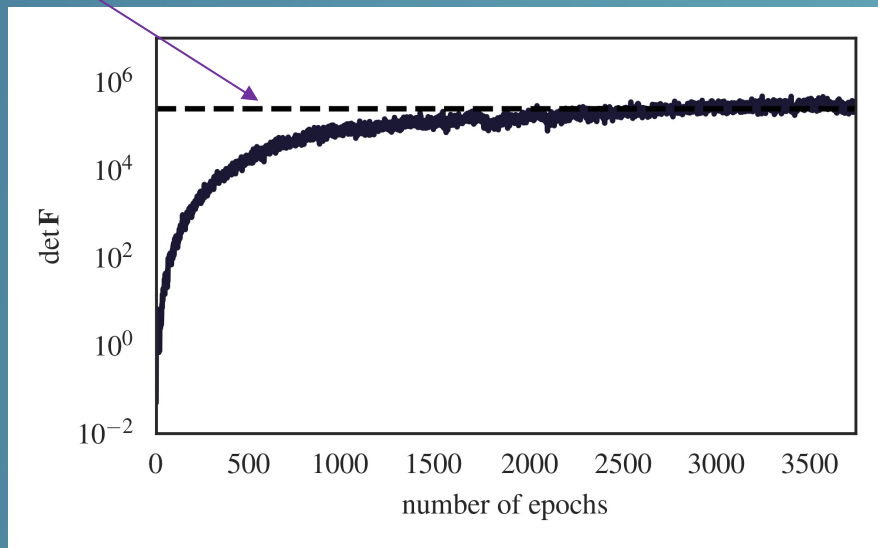


# Simulate a differentiable universe !

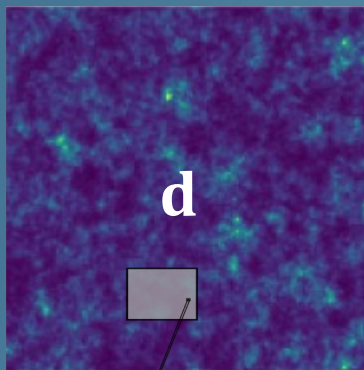


# IMNN training: saturate known information content

(known) theoretical field information content (all pixels) !



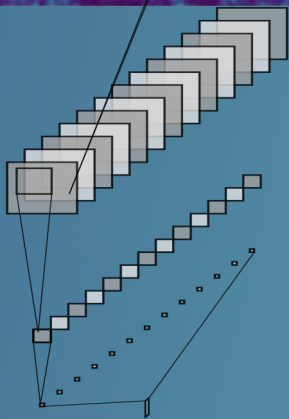
## Compress observed universe



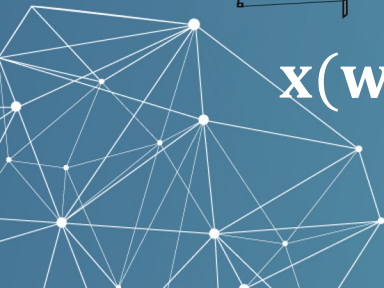
Next: observe universe + compress

Make *score estimates* of the parameters:

$$\hat{\theta}_{\alpha} = \theta_{\alpha}^{\text{fid}} + F_{\alpha\beta}^{-1} \frac{\partial \mu_i}{\partial \theta_{\beta}} \mathbf{C}_{ij}^{-1} (\mathbf{x}(\mathbf{w}; \mathbf{d}) - \mu)_j$$



$\mathbf{x}(\mathbf{w}; \mathbf{d})$

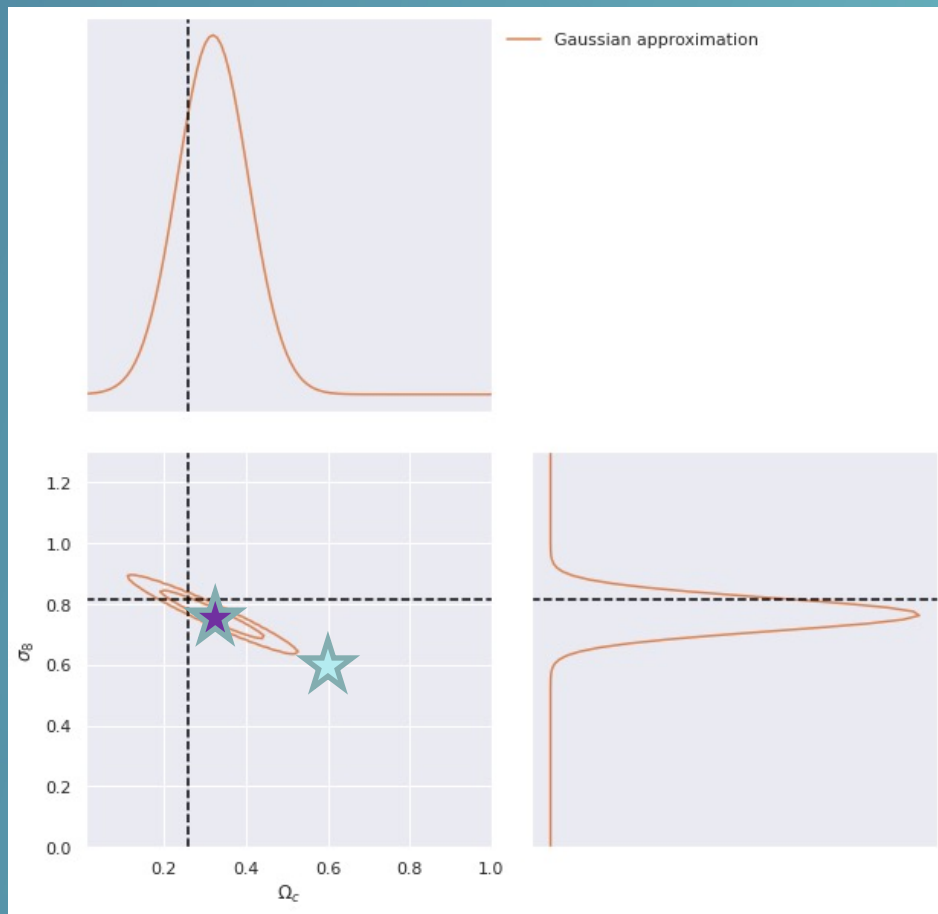


# Score Estimates + Fisher Contours

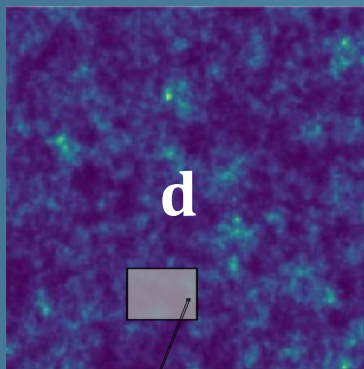
★ Fiducial (poor)

★ Score estimates

— Fisher  
Gaussian  
Approximation

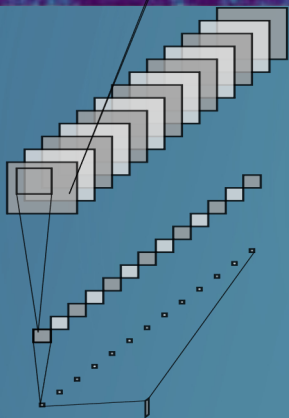


## Step 2: Make estimates + Re-train

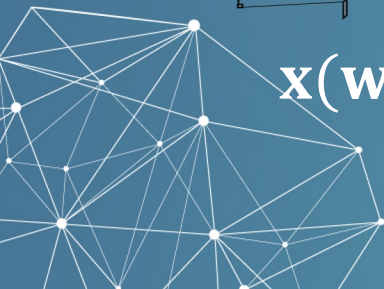


retrain compression on IMNN score estimates: new fiducial model parameters

$$\theta_{\text{fid},2} = (\Omega_c, \sigma_8) = (0.28, 0.73)$$



$\mathbf{x}(\mathbf{w}; \mathbf{d})$



## Step 3: Neural Density Estimation

**Goal:** parameterize the posterior  $p(\boldsymbol{\theta}|\mathbf{x}) \propto p(\mathbf{x}|\boldsymbol{\theta})p(\boldsymbol{\theta})$  for  $\Omega_c, \sigma_8$  with compressed simulations

Q: How do we parameterize  $p(\mathbf{x}|\boldsymbol{\theta})$  whilst *minimizing* the number of simulations needed ?



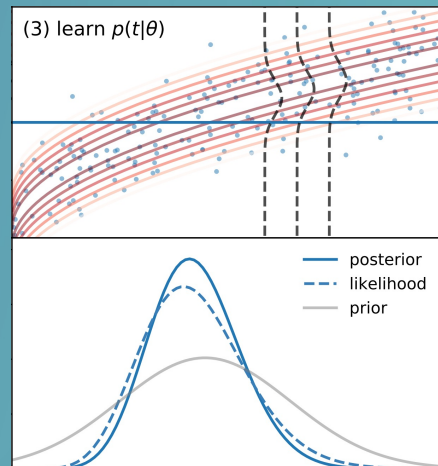


# Neural Density Estimation

**Goal:** parameterize the posterior  $p(\theta|\mathbf{x}) \propto p(\mathbf{x}|\theta)p(\theta)$

**A:** Using Conditional Masked Autoregressive Flows

summaries



parameters

# Conditional Masked Autoregressive Flows

Parameterize the *summary data likelihood* with a neural network with weights  $\mathbf{w}$  :

$$p(\mathbf{x} | \boldsymbol{\theta}) = \prod_{i=1}^{\dim(\mathbf{x})} p(x_i | \mathbf{x}_{1:i-1}, \boldsymbol{\theta}; \mathbf{w})$$



# Conditional Masked Autoregressive Flows

Parameterize the *summary data likelihood* with a neural network with weights  $\mathbf{w}$  :

$$p(\mathbf{x} | \boldsymbol{\theta}) = \prod_{i=1}^{\dim(\mathbf{x})} p(x_i | \mathbf{x}_{1:i-1}, \boldsymbol{\theta}; \mathbf{w})$$

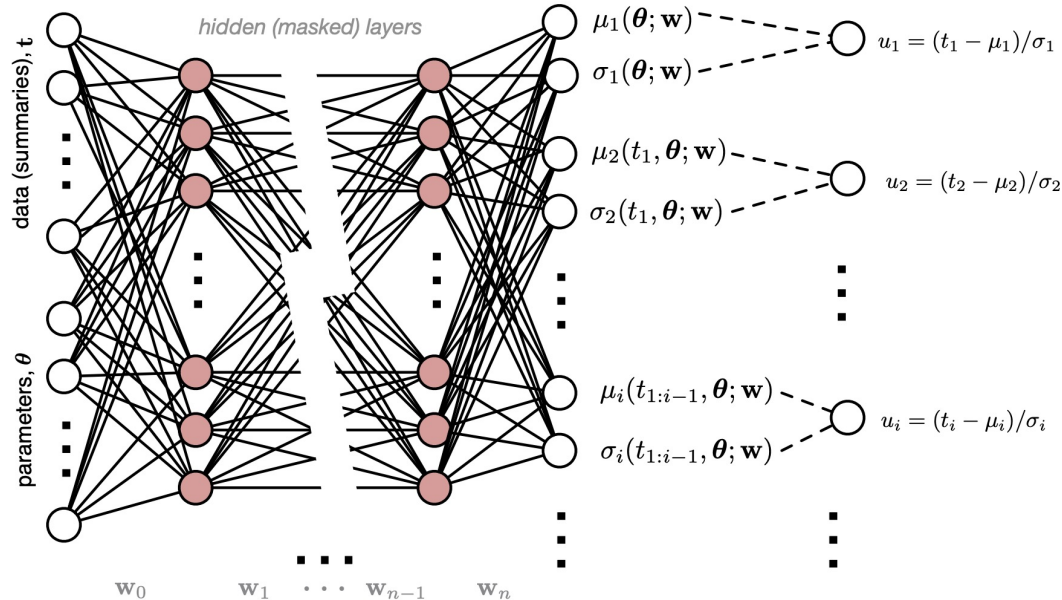
Minimize log-loss:  $-\ln U = -\sum_i \ln p(x_i | \mathbf{x}_{1:i-1}, \boldsymbol{\theta}; \mathbf{w})$



# Conditional Masked Autoregressive Flows

Minimize log-loss:  $-\ln U = \sum_i \ln p(x_i | x_{1:i-1}, \theta; \mathbf{w})$

Masked Autoencoder for Density Estimation (MADE)



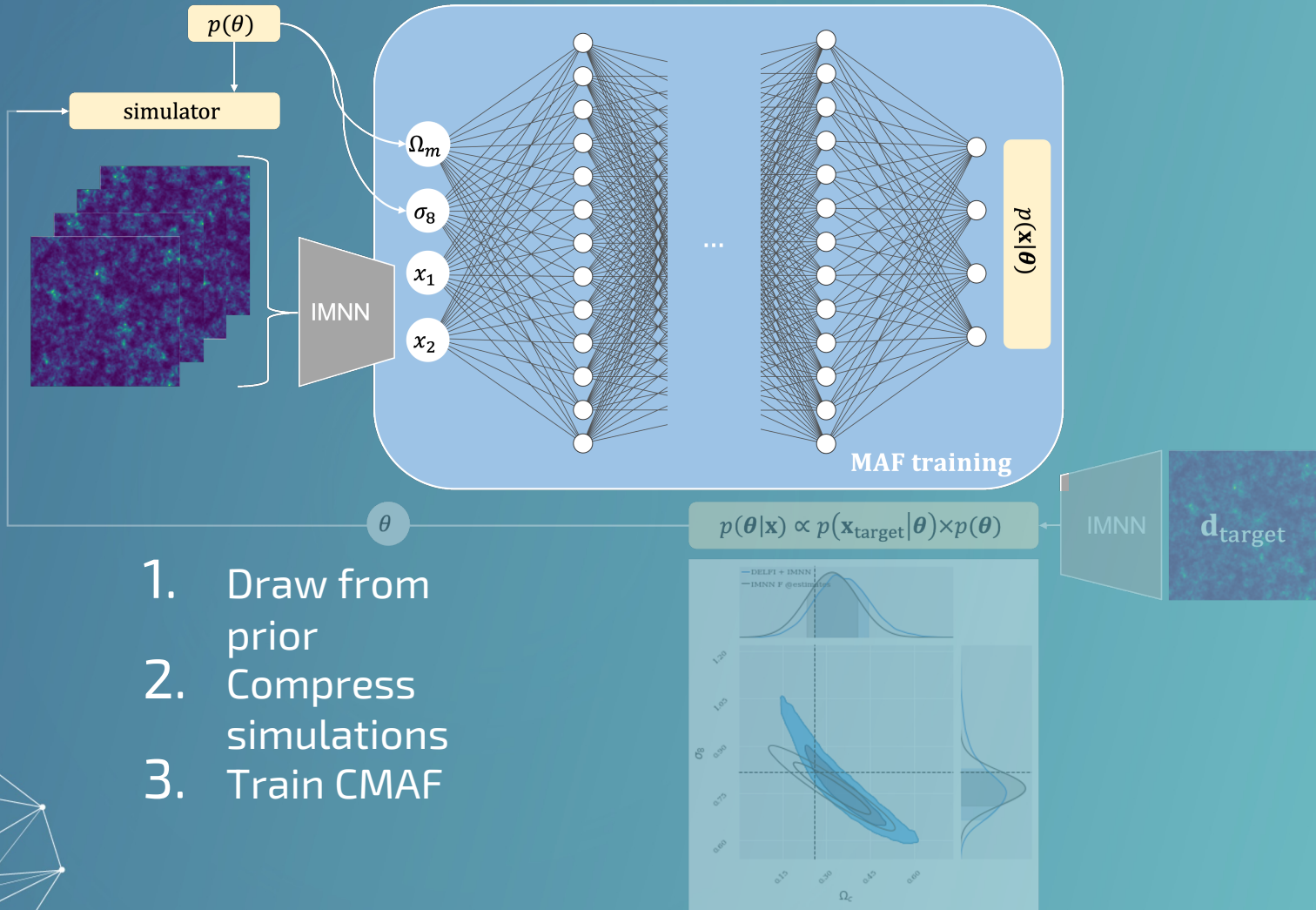
Autoregressive conditionals

$$p(t_1 | \theta; \mathbf{w}) = \mathcal{N}[\mu_1(\theta; \mathbf{w}), \sigma_1(\theta; \mathbf{w})]$$

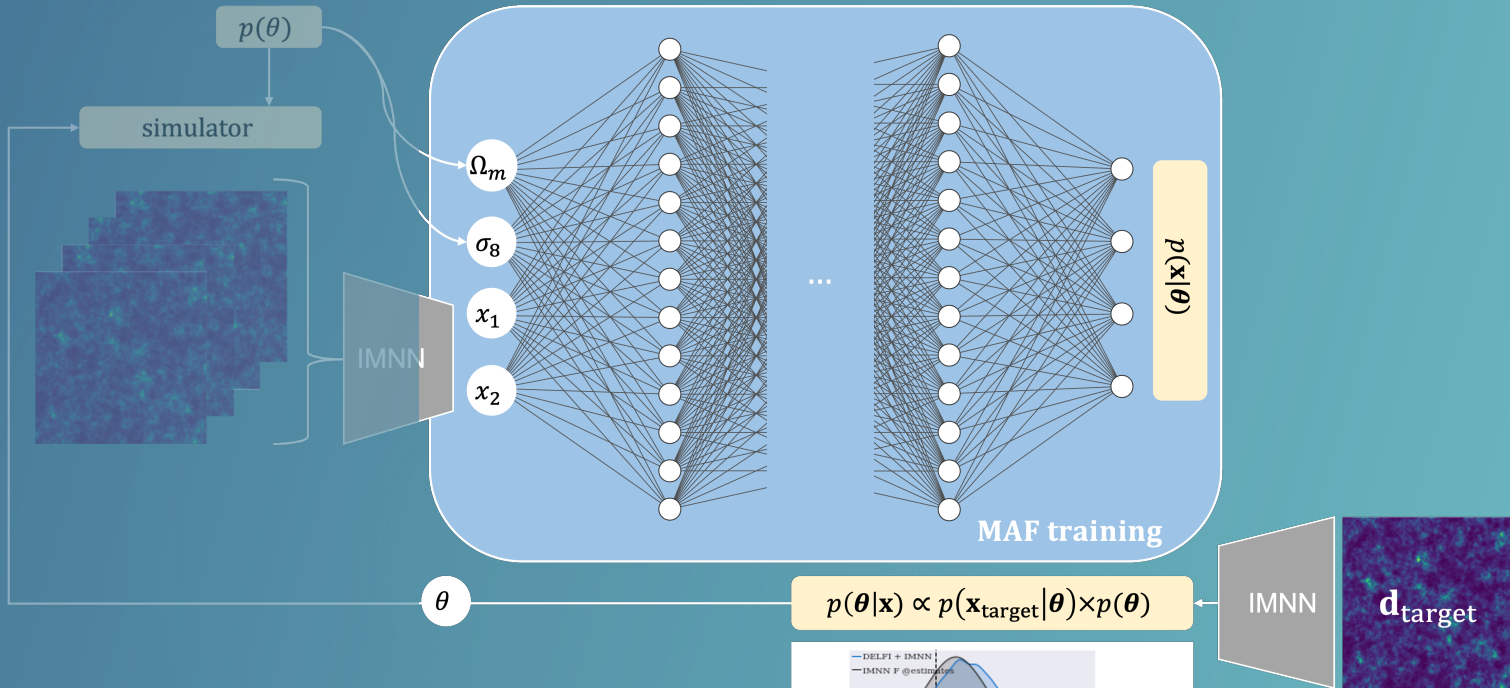
$$p(t_2 | t_1, \theta; \mathbf{w}) = \mathcal{N}[\mu_2(t_1, \theta; \mathbf{w}), \sigma_2(t_1, \theta; \mathbf{w})]$$

$$p(t_i | t_{1:i-1}, \theta; \mathbf{w}) = \mathcal{N}[\mu_i(t_{1:i-1}, \theta; \mathbf{w}), \sigma_i(t_{1:i-1}, \theta; \mathbf{w})]$$

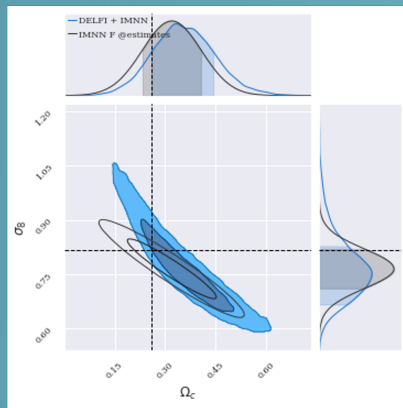
# Neural Density Estimation



# Neural Density Estimation

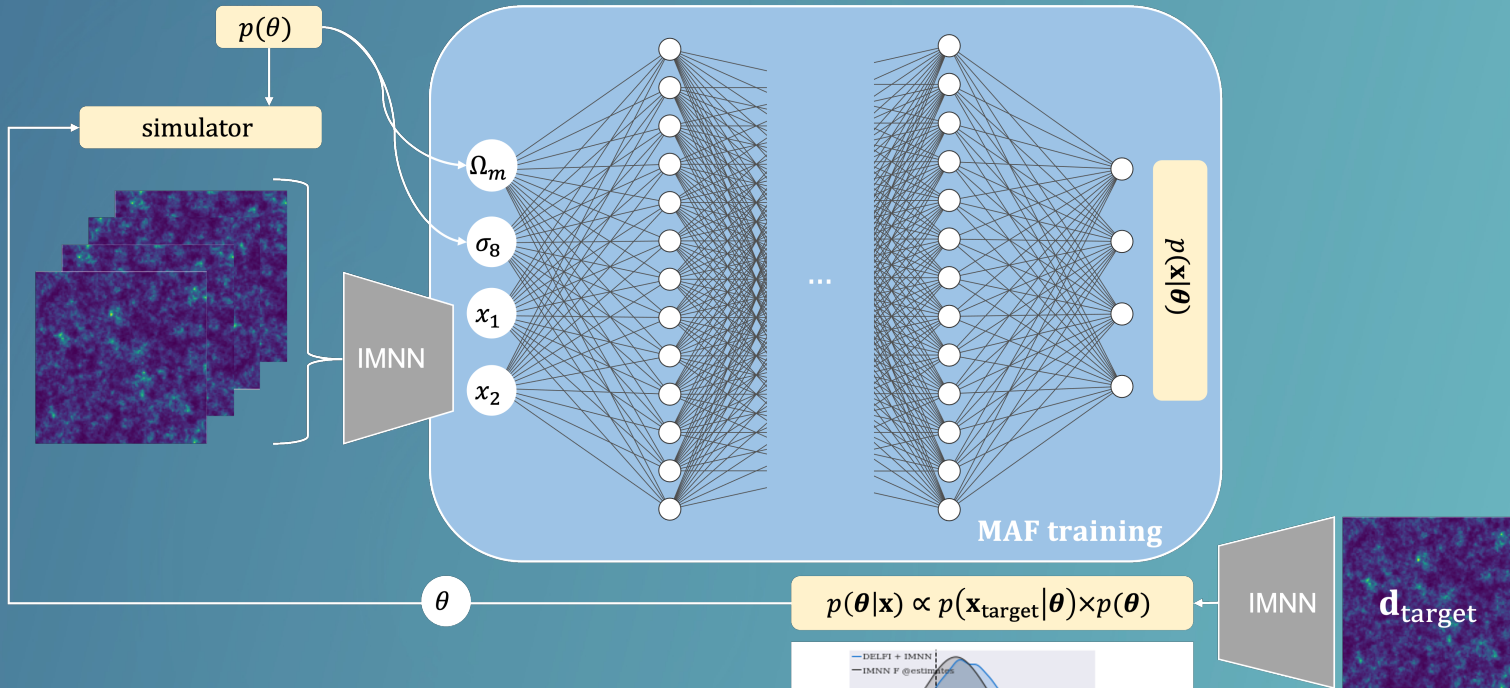


- 5. Compress target data
- 6. Evaluate posterior

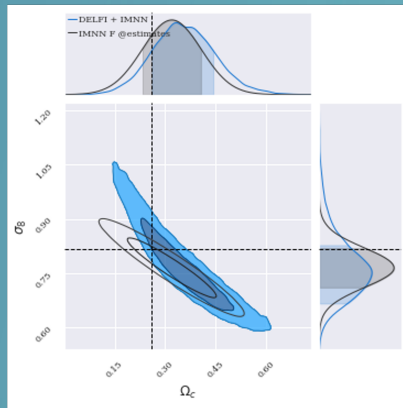




# Neural Density Estimation



7. Draw parameters from posterior, simulate, compress
8. Append new  $(\theta, \mathbf{x})$  to training data & continue training



# Final inference



Fiducial (poor)



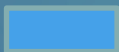
Score estimates



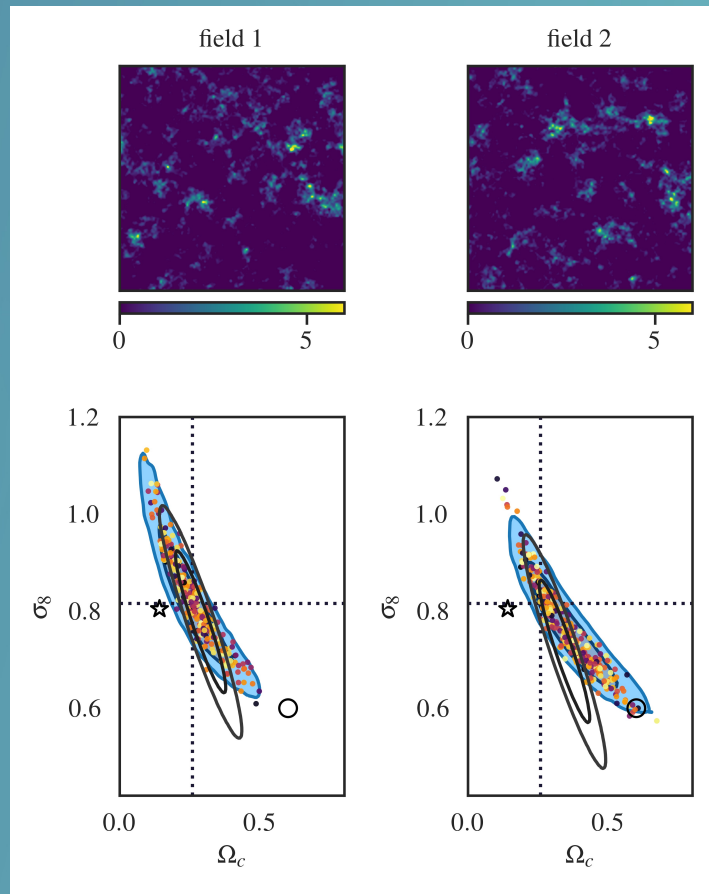
Fisher Gaussian  
Approximation



Approximate  
Bayesian  
Computation



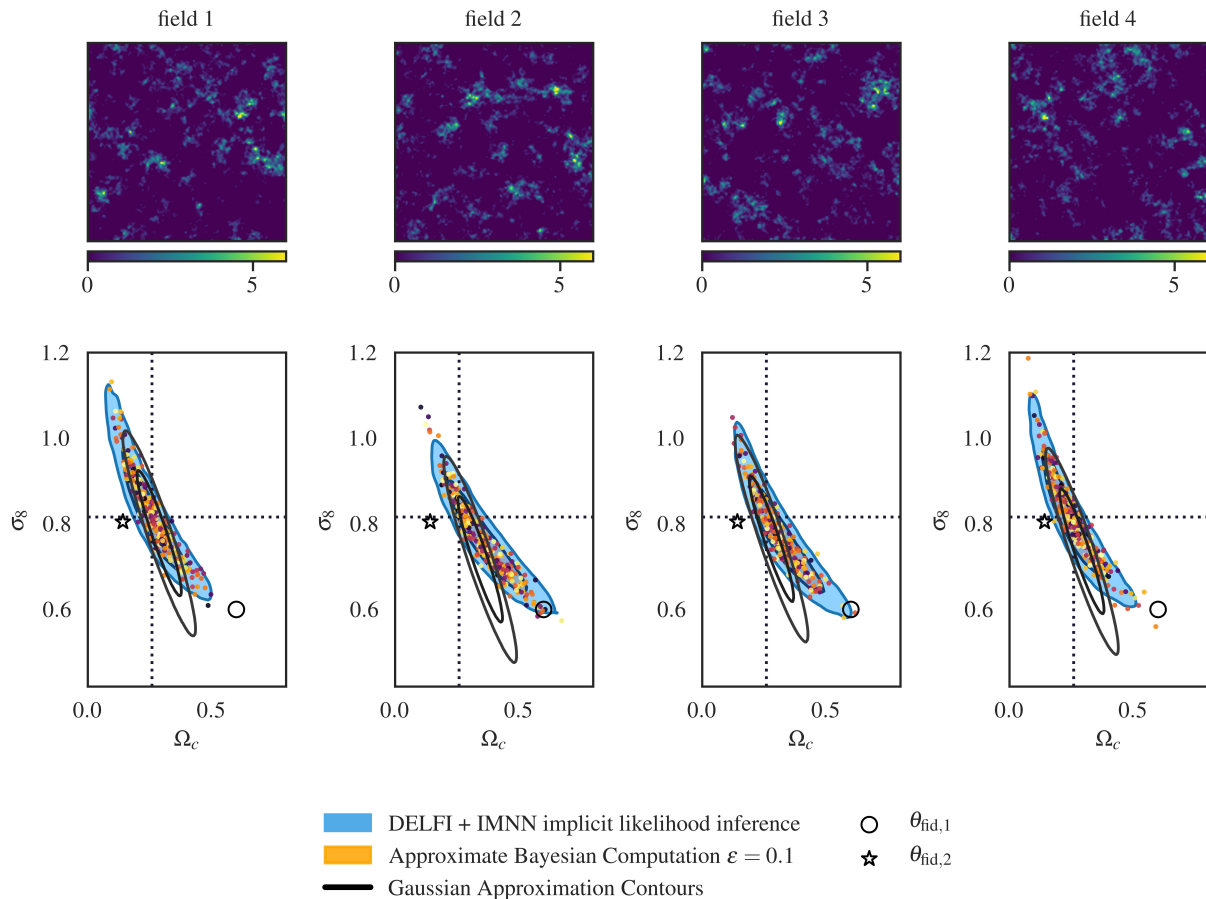
DELFI + IMNN



# Final inference

-ABC requires 12,000 simulations over prior to obtain 350 accepted points

-DELFI requires 4000 simulations sampled in batches of 1000 from posterior



# Takeaways

- Optimal nonlinear compression means we can represent (losslessly) massive simulations with a handful of numbers
- Density estimation massively reduces the number of simulations needed for inference (only  $\mathcal{O}(1000)$  versus  $\mathcal{O}(10,000)$  for Approximate Bayesian Computation)



# get the code !

Browser-based tutorial: <https://bit.ly/imnn-cosmo>

Github: <https://github.com/tlmakinen/FieldIMNNs>

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# THANK YOU !

(Stay tuned for questions)

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<https://github.com/tlmakinen>



@LucasMakinen

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# Verifying the pipeline

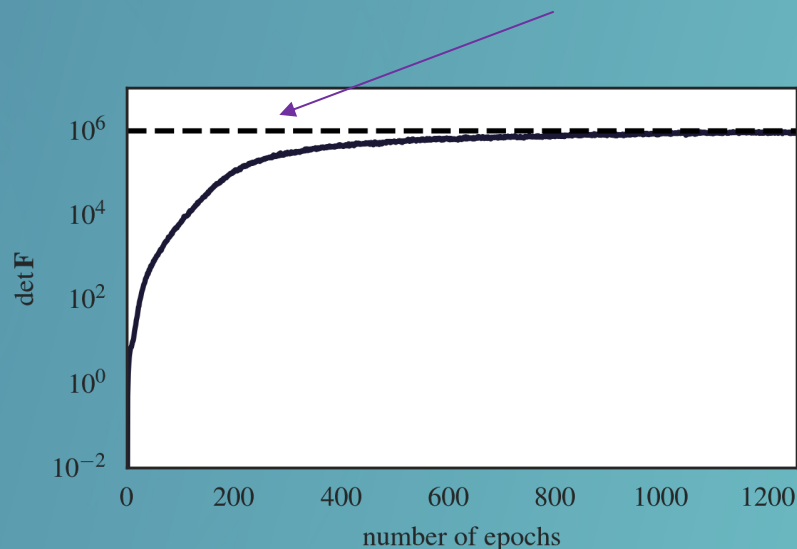
Want to learn “cosmological” parameters  $(A, B)$  from Gaussian fields generated by power spectrum

$$P(k) = Ak^{-B}$$

Train until Fisher information is maximised at a fiducial model,

$$\theta_{\text{fid}} = (1.0, 0.5)$$

Theoretical field information content !



# Verifying the pipeline

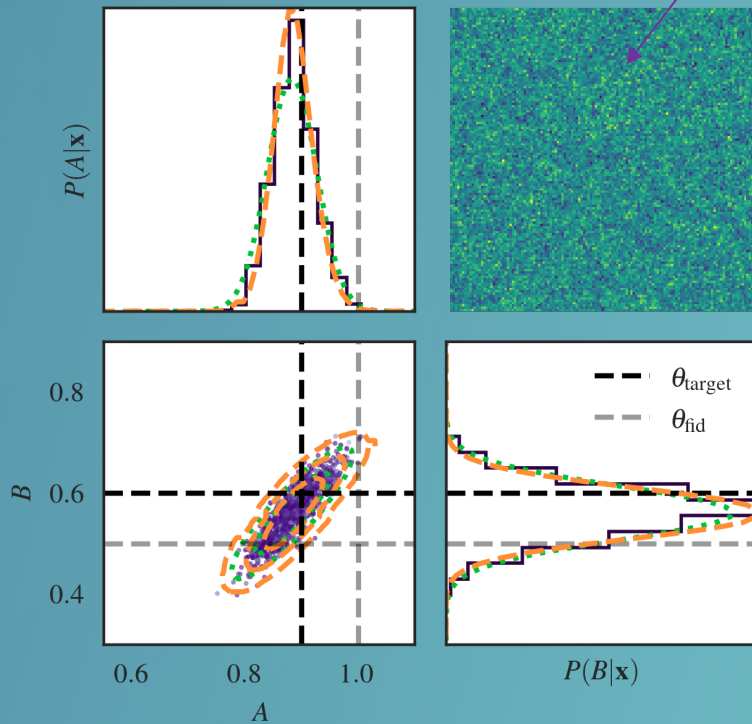
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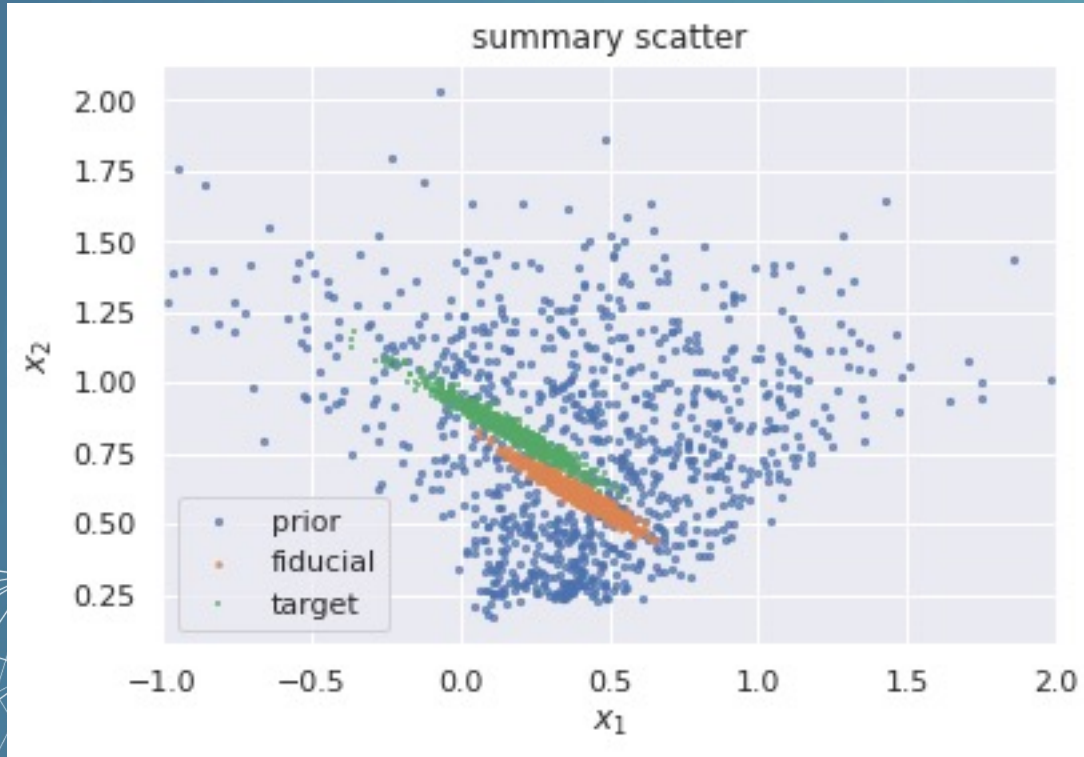
Run Approximate Bayesian Computation (ABC) on target data with  $\theta_{\text{target}} = (0.9, 0.6)$

- ABC
- - - Gaussian Approximation
- - - Analytic Likelihood

The piece of data we're running inference on



# What do IMNN outputs look like ?



Here we're actually plotting the *score estimates* of parameters computed from the network outputs. Score estimates for a simulation's parameters should be easier for the CMAF to learn than raw neural network outputs

# Approximate Bayesian Computation for IMNN summaries

for every  $i$  simulation, compute:

$$\rho = \sqrt{(\mathbf{x}_i - \mathbf{x}_{\text{target}})^T \mathbf{F}_{\text{IMNN}} (\mathbf{x}_i - \mathbf{x}_{\text{target}})}$$

if  $\rho < \epsilon$ , keep simulation.

