Multiple hypothesis testing and testing one hypothesis multiple times: two sides of the same coin?

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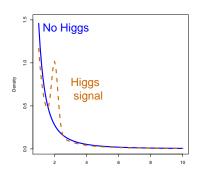
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General framework

Goal of statistical signal detection in physics

We would like to distinguish signals of new physics phenomena from the random fluctuations of the data.



- E.g., Higgs boson, quark, neutrino.
- We want to detect a bump (the signal of the new particle) on top of a background flux.

How does statistics tackle this problem?

• Approach 1:

Multiple hypotesis testing ⇒ Bonferroni's correction.

• Approach 2:

Simulations \Rightarrow Monte Carlo, Bootstrap.

• Approach 3:

Hypothesis testing when a nuisance parameter is present only under the alternative \Rightarrow Davies (1977, 1987), Gross and Vitells (2010).



We refer to this as **Testing one hypothesis multiple times**.

Note!

In High Energy Physics a discovery is claimed at 5σ significance \Rightarrow in Approach 2 we need to simulate $O(10^8)$, can we avoid that? Yes! Use (responsibly) Approach 1 and/or Approach 3.

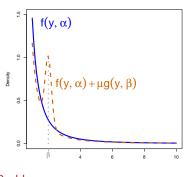
Questions I would like to address with this talk

- What does it mean exactly to "test one hypothesis multiple times", and in what sense is it equivalent to a testing problem when a nuisance parameter is present only under the alternative?
- ② Can we tackle both nested and non-nested models with this approach?
- What is the difference between testing one hypothesis multiple times and multiple hypothesis testing?
- When do multiple hypothesis testing and testing one hypothesis multiple times coincide in some sense?
- What else can we do, and what is the potential of working in this direction?

Outline

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A statistical framework for a physics problem



The model of interest is proportional to

$$\underbrace{f(y,\alpha)}_{\text{background}} + \underbrace{\mu}_{\substack{\text{signal} \\ \text{signal} \\ \text{strength}}} \underbrace{g(y,\overbrace{\beta})}_{\text{bump}} \tag{1}$$

and we test

$$H_0: \mu = 0$$
 vs. $\mu > 0$. (2)

Problems

 μ is on the boundary of its parameter space $+\beta$ is not defined under H_0 .

Solutions

Chernoff, 1954 + Davies, 1987, Gross and Vitells, 2010.

Theoretical solutions

Practical solution

Testing on the boundary of the parameter space

Model:

$$\propto f(y,\alpha) + \mu g(y,\beta) \qquad \mu \ge 0$$
 (3)

For now, let β be fixed, the model in (3) is identifiable.

Test

$$H_0: \mu = 0$$
 versus $H_1: \mu > 0$

Test statistics*:

$$LRT = -2\log[\underbrace{L(0, \hat{\alpha}_{0}, -)}_{\text{Likelihood under } H_{0}} - \underbrace{L(\hat{\mu}, \hat{\alpha}, \beta)}_{\text{Likelihood under } H_{1}}] \tag{4}$$

ullet η is on the boundary \Rightarrow WE CAN USE Chernoff, 1954 i.e.:

$$LRT = \xrightarrow[n \to \infty]{d} \frac{1}{2}\chi_1^2 + \frac{1}{2}\delta(0) \quad \text{under } H_0$$
 (5)

^{*} for the specific case of β be fixed.

Testing one hypothesis multiple times (1)

- If β fixed, under H_0 the LRT is asymptotically $\frac{1}{2}\chi_1^2 + \frac{1}{2}\delta(0)$.
- If we let β vary \Rightarrow Under H_0 , $\{LRT(\beta), \beta \in \mathbf{B}\}$ is asymptotically a $\frac{1}{2}\chi_1^2 + \frac{1}{2}\delta(0)$ random process indexed by β .
- In practice:
 - Define a grid \mathbf{B}_R of R β_r values over the energy spectrum \mathbf{B} .
 - $\forall \beta_r \in \mathbf{B}_R$ calculate $LRT(\beta_r)$.

Many "sub"-alternatives...

It is like if we had many alternative hypothesis $H_{11}, \ldots, H_{1r}, \ldots, H_{1R}$, one for each value $\beta_r \in \mathbf{B}_R$, and for each of them we have one value $LRT(\beta_r)$.

...but yet just one test statistic...

We finally combine the R $LRT(\beta_r)$ values in a unique test statistics $\max_{\beta_r \in \mathbf{B}_R} LRT(\beta_r)$

Testing one hypothesis multiple times (2)

... and one global p-value...

The **p-value** of our test H_0 : $\eta = 0$ versus H_a : $\eta > 0$ is in the form

$$P(\sup_{\beta \in \mathbf{B}} LRT(\beta) > c) \tag{6}$$

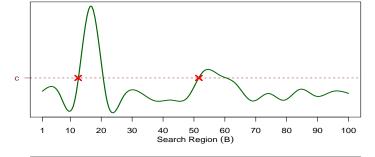
with $c = \max_{\beta_r \in \mathbf{B}_R} LRT(\beta)$.

...which we must calculate/approximate somehow!

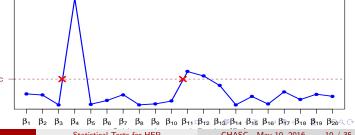
To do so, we first need to introduce the concept of **upcrossings** of the LRT-process { $LRT(\beta), \beta \in \mathbf{B}$ }.

What do we mean by "upcrossings"?

True LRT-process under H_0



Discretized version we deal with in practice



Approximation of $P(\sup_{\beta \in \mathbf{B}} LRT(\beta) > c)$

• From **Davies, 1987** we have that if $\{LRT(\beta), \beta \in \mathbf{B}\}$ is a "regular" χ_1^2 process, then as $c \to +\infty$

$$P(\sup LRT(\beta) > c) \approx \frac{P(\chi_1^2 > c)}{2} + \underbrace{\frac{e^{\frac{c}{2}}}{\sqrt{2\pi}} \int_L^U \kappa(\beta) d\beta}_{\text{over } c \text{ of the LRT process under } H_0}^{\text{Expected } \#}$$
 (7)

- if $c \not\to +\infty \Rightarrow$ we have an upper bound for $P(\sup LRT(\beta) > c)$.
- $\kappa(\beta)$ is complicated \Rightarrow use the "empirical" version of (7) proposed in **Gross and Vitells, 2010**

$$P(\sup LRT(\beta) > c) \approx \frac{P(\chi_1^2 > c)}{2} + \underbrace{e^{-\frac{c-c_0}{2}}E[N(c_0)|H_0]}_{=E[N(c)|H_0]} \xrightarrow{\substack{\text{Expected } \# \text{ of upcrossings over } c_0 \text{ of the LRT process under } H_0}}_{(8)}$$

• where $c_0 << c$ and $E[N(c_0)|H_0]$ is estimated using (few) Bootstrap simulations.

For more details and an alternative approach to the problem, check out:

Algeri S., van Dyk D.A., Conrad J., Brandon, A. Looking for a Needle in a Haystack? Look Elsewhere!
 A statistical comparison of approximate global p-values. Submitted: 2016.

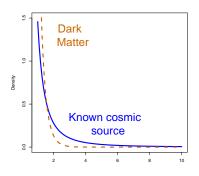
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Non-nested models comparison in physics

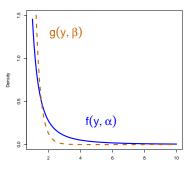
Goal

We would like to distinguish known astrophysics from new signals.



- E.g., Dark Matter.
- We wish to distinguish a dark matter signal from a "fake" signal that mimics it.

The statistical problem



- The model for the know cosmic source is f(y, α);
- The model for the new source is $g(y, \beta)$;
- $f \not\equiv g$ for any α and β .

Is f sufficient to explain the data, or does g provide a better fit?

Problem

f and g are non-nested.

Solutions

Cox, 1961-1962, Atkinson, 1970; etc., Bootstrap, next two slides.

Theoretical solutions

Practical solutions

Formulation of the problem

- Consider a comprehensive model which includes $f(y, \alpha)$ and $g(y, \beta)$ as special cases. We have two possibilities:
 - Multiplicative form

$$\propto \{f(y,\alpha)\}^{1-\eta}\{g(y,\beta)\}^{\eta} \tag{9}$$

Additive form

$$(1-\eta)f(y,\alpha)+\eta g(y,\beta) \tag{10}$$

• We prefer (10), it avoids the need to deal with the normalizing constant.

Thus, considering the model in (10) we test

$$H_0: \eta = 0$$
 versus $H_1: \eta > 0$

 \bullet To exclude intermediate values of η we can interchange the roles of the hypotheses and test

$$H_0: \eta = 1$$
 versus $H_1: \eta < 1$.

From a new formulation to a well known problem

Model:

$$(1 - \underbrace{\eta}_{\text{Tested on the boundary}}) f(y, \alpha) + \eta g(y, \underbrace{\beta}_{\text{Not defined under } H_0}) \quad \text{with} \quad 0 \le \eta \le 1$$

Test:

$$H_0: \eta=0$$
 versus $H_1: \eta>0$ similar argument for $H_0: \eta=1$ versus $H_1: \eta<1$

Notel

These are precisely the same issues we encounter when detecting new particles, i.e., when testing one hypothesis multiple times ⇒ we already have a solution!

For more details, check out:

- Algeri S., Conrad J., van Dyk D.A. A method for comparing non-nested models with application to astrophysical searches for new physics. MNRAS: Letters, 2016.
- Algeri S., R package 'NONnest', 2015.

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Multiple hypothesis testing - Framework

Also in this case:

- We define a grid \mathbf{B}_R of R β_r values over the energy spectrum \mathbf{B} .
- $\forall \beta_r \in \mathbf{B}_R$ calculate $LRT(\beta_r)$.

However, now we have:

Many sub-alternatives...

We have many alternative hypothesis $H_{11},\ldots,H_{1r},\ldots,H_{1R}$, one for each value $\beta_r\in \mathbf{B}_R$.

...many test statistics...

 $\forall \beta_r \in \mathbf{B}_R$ we have one test statistics $LRT(\beta_r)$, and such that $LRT(\beta_r) \sim \frac{1}{2}\chi_1^2 + \frac{1}{2}\delta(0)$ asymptotically.

...many p-values!

$$\forall \beta_r \in \mathbf{B}_R$$
 we have $p_r = \frac{P(\chi_1^2 > LRT(\beta_r))}{2}$.

Local p-values and type I error

- We have an ensemble of R local p-values $p_1, \ldots, p_r, \ldots, p_R$.
- The smallest, names $p_{\rm L}$ is then compared with the target probability of type I error $\alpha_{\rm L}$.
- But what is $\alpha_{\rm L}$ if we want to claim a discovery at 5σ ?

Global and local probability of false detection

 $\alpha_{\mathrm{L}} = \mathrm{specific}$ probability of false detection for each of the R \neq

 $\alpha_{\rm G}=$ probability of having at least one false detection over the whole ensemble of R tests.

 \Rightarrow we must correct p_{L} accordingly



Local p-values corrections

If the R tests were independent

$$\alpha_{\rm G} = 1 - (1 - \alpha_{\rm L})^R \quad \Rightarrow \quad p_{\rm G} = 1 - (1 - p_{\rm L})^R$$
 (12)

E.g.: Suppose we are conducting R = 50 simultaneous test, each of them at 5σ

$$\alpha_{\rm L} = 1 - \Phi(5) \quad \Rightarrow \ \, {\rm by} \,\, (11): \quad \alpha_{\rm G} = 1 - \Phi(4.18)$$

i.e., $\frac{\alpha_{\rm G}}{\alpha_{\rm I}} \approx 50$.

• If the R tests were dependent (which is generally the case)

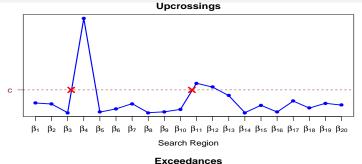
$$\alpha_{\rm G} \le R\alpha_{\rm L} \quad \Rightarrow \quad p_{\rm BF} = Rp_{\rm L} \quad \begin{array}{c} \text{Bonferroni's} \\ \text{correction} \end{array}$$
(13)

Outline

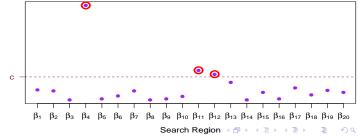
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Upcrossings and Exceedances





Multiple LRTs under H_0



Why are we interested in the Exceedances?

We can identify situations where the average number of exceedances under H_0 , namely $E[N_c^*|H_0]$, and the average number of upcrossings under H_0 , $E[N_c|H_0]$ are approximately equal.

- We will soon see two conditions we need for this to happen.
- For now let's focus on $E[N_c^*|H_0]$:

$$\begin{split} E[\textit{N}_c^{\star}|\textit{H}_0] &= \sum_{r=1}^{R} 1 \cdot P(\textit{LRT}(\beta_r) > c) \\ &\quad \text{under } \textit{H}_0, \ \forall \beta_r \in \mathbf{B}_R, \\ &\quad \textit{LRT}(\beta_r) \sim \frac{1}{2}\chi_1^2 + \frac{1}{2}\delta(0) \text{ asymptotically} \\ &= \sum_{r=1}^{R} \frac{P(\chi_1^2 > c)}{2} = R\frac{P(\chi_1^2 > c)}{2} = Rp_{\rm L} = p_{\rm BF} \quad \begin{array}{c} \text{Bonferroni's correction!} \end{array} \end{split}$$

Two sides of the same coin

What the previous slide is telling us is that, if

$$\underbrace{E[N_c|H_0]}_{\text{Expected}} \approx \underbrace{E[N_c^*|H_0]}_{\text{Expected ded upcrossings under }H_0} \approx \underbrace{E[N_c^*|H_0]}_{\text{Expected ded exceedances under }H_0} = \underbrace{p_{BF}}_{\text{Bonferroni's correction}} \tag{14}$$

and $\exists \lambda$ s.t as $c \to +\infty$ $(p_{\rm L} \to 0)$ and $R \to +\infty$

$$E[N_c|H_0] \approx E[N_c^{\star}|H_0] = p_{\mathrm{BF}} \to \lambda$$

then, for R and c large we have

$$\underbrace{\frac{P(\sup LRT(\beta) > c)}{\text{Global p-value}}} \approx \underbrace{\frac{P(\chi_1^2 > c)}{2}}_{\text{as } c \to +\infty} + E[N_c | H_0]$$

$$\approx E[N_c | H_0] \approx E[N_c^* | H_0]$$

$$\approx \underbrace{P(\chi_1^2 > c)}_{\text{as } c \to +\infty} + E[N_c | H_0]$$

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This means that if $E[N_c|H_0] \approx E[N_c^*|H_0]$, then testing one hypothesis multiple times and multiple hypothesis testing will lead to approximately the same inference. (But, since the latter is much quicker than the former, I might gain in computing time.)

When do we have $E[N_c|H_0] \approx E[N_c^*|H_0]$?

To guarantee $E[N_c|H_0] \approx E[N_c^{\star}|H_0]$ (as $c \to +\infty$), we need the following two conditions to be satisfied:

Long range independence

$$|F_{1,\dots,r,r+1,\dots,r+k} - F_{1,\dots,r}F_{r+1,\dots,r+k}| \le q(r)$$
 (16)

where $F(\cdot)$ is the cdf of $LRT(\beta_r), \forall \beta_r \in \mathbf{B}_R$, and q(r) is a function such that $q(r) \to 0$ as $r \to \infty$.

This condition implies that independence is achieved for distant points β_r of the (discretized) energy/mass spectrum.

2 Local dependence

$$\limsup_{r \to 2} R \sum_{r=2}^{\lfloor R/J \rfloor} P(LRT(\beta_1) > c, LRT(\beta_r) > c) \to 0 \quad \text{as} \quad I \to +\infty$$
 (17)

where $F(\cdot)$ be the cdf of $LRT(\beta_r), \forall \beta_r \in \mathbf{B}_R$,

This condition excludes the chance of clustering of the upcrossings of the LRT-process.

How to assess if these two conditions hold?

- Let the model of reference be $(1-\eta)f(y,\alpha) + \eta g(y,\beta_r)$, and let $I(\eta|\alpha,\beta_r,y)$ be its log-likelihood.
- $\forall \beta_r$ the score function evaluated at H_0 is $S(\beta_r) = \frac{\partial l(\eta | \alpha, \beta_r, y)}{\partial \eta} \Big|_{\eta=0}$ \Rightarrow the score process under H_0 is $\{S(\beta_r), \beta_r \in \mathbf{B}_r\}$
- with covariance function is $cov(S(\beta_r), S(\beta_t)) = \int \frac{g(y, \beta_r)g(y, \beta_t)}{f(y, \alpha)} \partial y 1$

$$S^{\star}(\beta_r) = \frac{S(\beta_r)}{\sqrt{cov(S(\beta_r), S(\beta_r))}}$$
 (18)

A sufficient condition on $S^*(\beta_r)$ (Berman's condition)

If the covariance function of $S^*(\beta_r)$ satisfies

$$\sup_{|\beta_r - \beta_t| > \tau} |cov(S^*(\beta_r), S^*(\beta_t))| \log(\tau) \to 0 \quad \text{as} \quad \tau \to +\infty$$
 (19)

then **long range independence** and **local independence** hold on both the normalized score <u>and the LRT</u> processes.

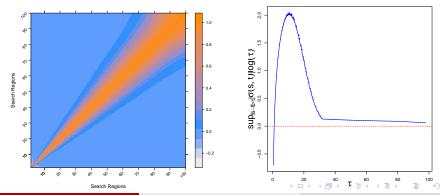
Example

Consider a power-law distributed background with index ψ and a Gaussian signal with dispersion proportional to the signal location.

The full model is

$$(1-\eta)\frac{1}{k_{\psi}y^{\psi+1}} + \frac{\eta}{k_{M_{\chi}}} \exp\left\{-\frac{(y-M_{\chi})^2}{0.02M_{\chi}^2}\right\}$$
 (20)

with k_{ψ} and $k_{M_{\chi}}$ normalizing constants, $y \in [1; 100]$, $\psi = 1.4$ and $M_{\chi} \in [1; 100]$.



Realistic data analysis

We simulated observation of monochromatic feature by the Fermi Large Area Telescope (LAT).

- 2391 events from an astrophysical background corresponding to isotropic emission following a spectral power-law with index 2.4, i.e., $\psi=1.4$.
- 64 events from a Gaussian signal with mass of 35 GeV.
- 80 energy bins, spaced equally from 10-350 GeV.

Method	Signal Location	Signal Strength	Sig.
Unadjusted local	35.82	0.042	5.920σ
Bonferroni adj. local	35.82	0.042	5.152σ
Gross & Vitells	35.82	0.042	5.192σ

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What can we do more?

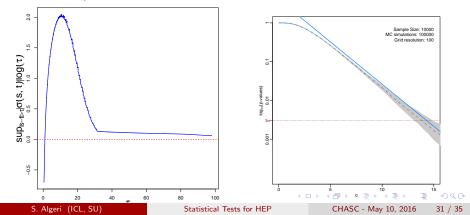
- Berman's condition is not only a sufficient condition to guarantee asymptotic equivalence between testing one hypothesis multiple times and multiple hypothesis testing.
- Indeed, it can be used as diagnostic tool to assess the validity of the Davies (1987) and Gross and Vitells (2010) approximations for the global p-value $P(\sup LRT(\beta) > c)$.
- Several cases can be identified and additional conditions, in addition to long range independence and local independence, are needed.
- But we still have to refine the details...
- ...however, we already can take a look at some examples.

A case where everything works nicely

Considering again the Power Law background + Gaussian signal example:

$$(1-\eta)\frac{1}{k_{\psi}y^{\psi+1}} + \frac{\eta}{k_{M_{\chi}}} \exp\left\{-\frac{(y-M_{\chi})^2}{0.02M_{\chi}^2}\right\}$$
 (21)

with k_{ψ} and $k_{M_{\chi}}$ normalizing constants, $y \in [1; 100]$, $\psi = 1.4$ and $M_{\chi} \in [1; 100]$.

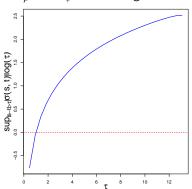


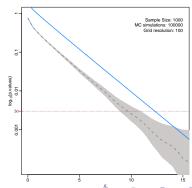
A non-ideal case

Suppose we want to distinguish between Pulsar Spectrum and Dark Matter. The full model is:

$$(1 - \eta) \frac{\exp\{-y^2\}}{k_{\rho} y^{\rho}} + \frac{\eta \exp\{-7.8 \frac{y}{\phi}\}}{k_{\phi} y^{1.5}}$$
 (22)

with k_{ρ} and k_{ϕ} normalizing constants, $y \in [1; 15]$, $\rho = 4/3$ and $\phi \in [1; 15]$.



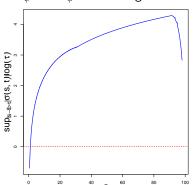


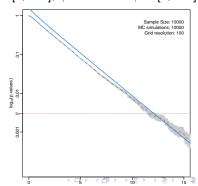
A case somewhere in between

Suppose we want to distinguish between a Power Law distributed cosmic source and and Dark Matter. The full model is:

$$(1-\eta)\frac{1}{k_{\psi}y^{\psi+1}} + \frac{\eta \exp\{-7.8\frac{\nu}{\phi}\}}{k_{\phi}y^{1.5}}$$
 (23)

with k_{ψ} and k_{ϕ} normalizing constants, $y \in [1; 100]$, $\psi = 1.4$ and $\phi \in [1; 100]$.





...in the "next episode" ...

Work in progress and (immediate) future goals:

- We would like to provide a formal explanation of cases where the global p-value approximations do and do not work.
- We would like to provide precise indications on how to spot these cases.
- We would like to exploit the information on the dependence structure of the underlying processes to improve, if possible, the global p-value approximations discussed in this talk.

All this will be discussed in:

Algeri S., van Dyk D.A., Conrad J. *Testing one hypothesis multiple times*. In preparation, 2016. (Hopefully, available on ArXiv by the end of the summer.)

Thank you for listening!

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