

# TIME DELAY LENS MODELING CHALLENGE

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# STRONG GRAVITATIONAL LENSING

Video source: <https://www.youtube.com/watch?v=iE8x9kDHCFo>

**Strong gravitational lensing effect:** The strong gravitational field of the lensing galaxy splits light into multiple images, and we see these multiple images of the same quasar in the sky.

# STRONG LENS TIME DELAY

Credit: NASA's Goddard Space Flight Center

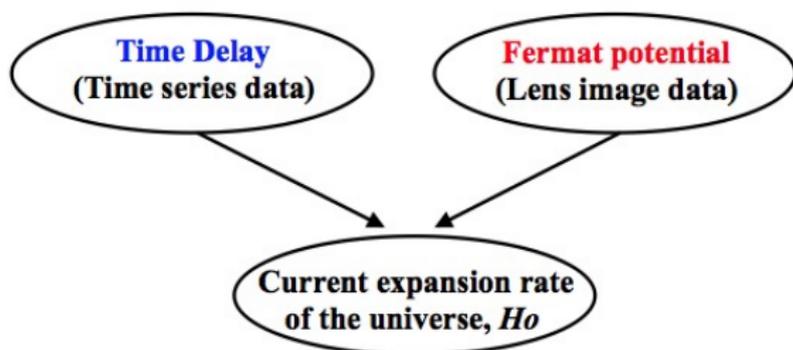
**Time delay:** Light rays take **different routes** and travel through **different gravitational potential**, and thus their arrival times can differ.

# STRONG LENS COSMOGRAPHY

One way to infer the current expansion rate of the universe ( $H_0$ ) is to model **time delay** and **lensing galaxy** (Schneider+, 2006).

$$\text{Time delay } (\Delta t_{ij}) = \frac{\text{Time delay distance } ( D_{\Delta t}(H_0, z, \Omega) )}{\text{Speed of light } (c)}$$

× Fermat potential difference ( $\Delta\phi_{ij}$ )



# TIME DELAY CHALLENGE

Time delay challenge (Dobler+, 2015; Liao+, 2016; Tak+, 2017; Hu+,?):  
A blind competition to improve existing time delay estimation methods.

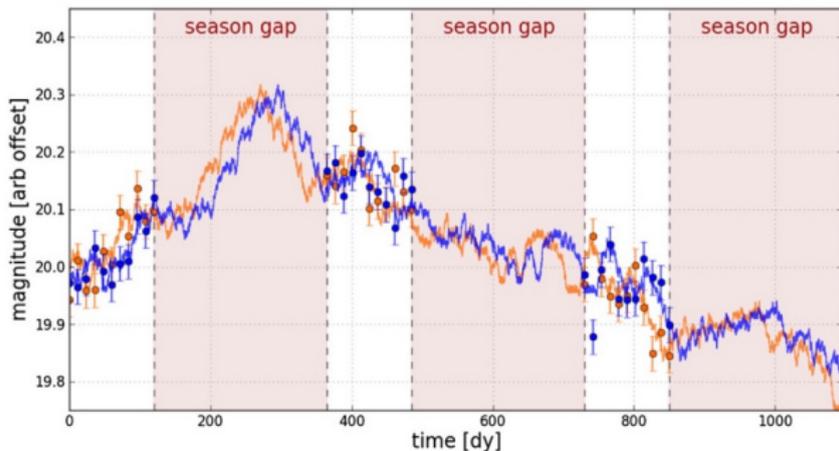


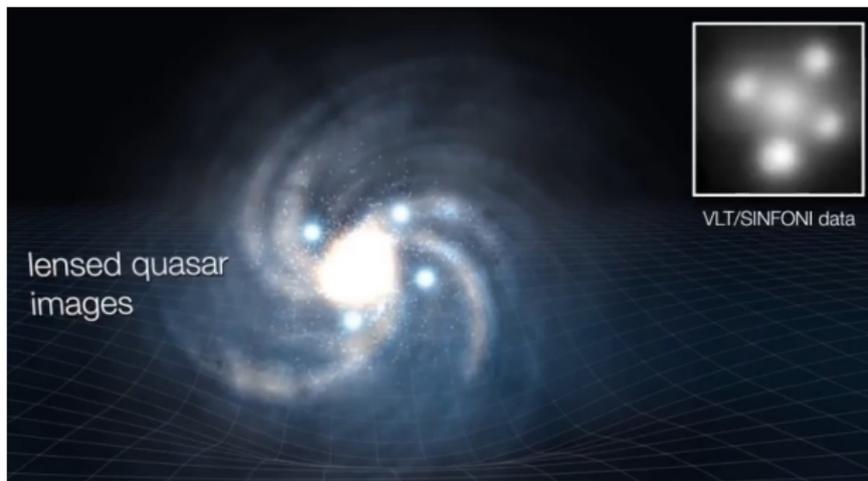
Image Credit: Dobler et al. (2015)

Modeling time delay: The blue time series of brightness is lagging behind by unknown amount of time due to time delay.

# TIME DELAY LENS MODELING CHALLENGE

Time delay lens modeling challenge (Ding+, 2018):

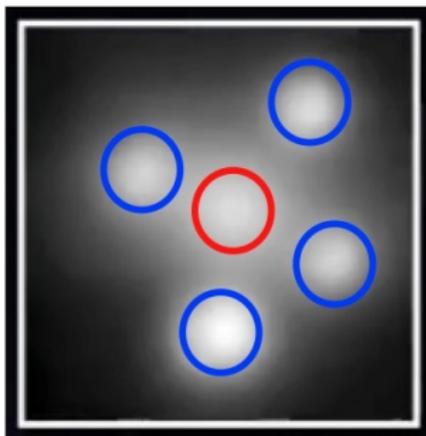
Another blind competition to improve existing lens-modeling techniques.



<https://www.youtube.com/watch?v=iE8x9kDHCFo>

Modeling lens: Lens mass  $\rightarrow$  lens potential  $\rightarrow$  Fermat potential!

# TIME DELAY LENS MODELING CHALLENGE (CONT.)



## Challenges in lens modeling:

- (1) Distributions for **lens mass & brightness**?
- (2) Distribution for **source brightness**?
- (3) How to estimate the unknown parameters in these distributions and unknown positions of lensed images?

# TIME DELAY LENS MODELING CHALLENGE (CONT.)

Elliptical power-law mass density for an angular position  $\theta_i = (\theta_{i1}, \theta_{i2})$ :

$$\kappa_{\text{lens}}(\theta_{i1}, \theta_{i2}) = \frac{3 - \gamma'}{2} \left( \frac{\sqrt{q\theta_{i1}^2 + \theta_{i2}^2/q}}{\theta_E} \right)^{1-\gamma'},$$

where  $\theta_E$  is the Einstein radius,  $q$  is the ellipticity, and  $\gamma'$  is the radial power-law slope.

Surface brightness density (elliptical Sérsic model):

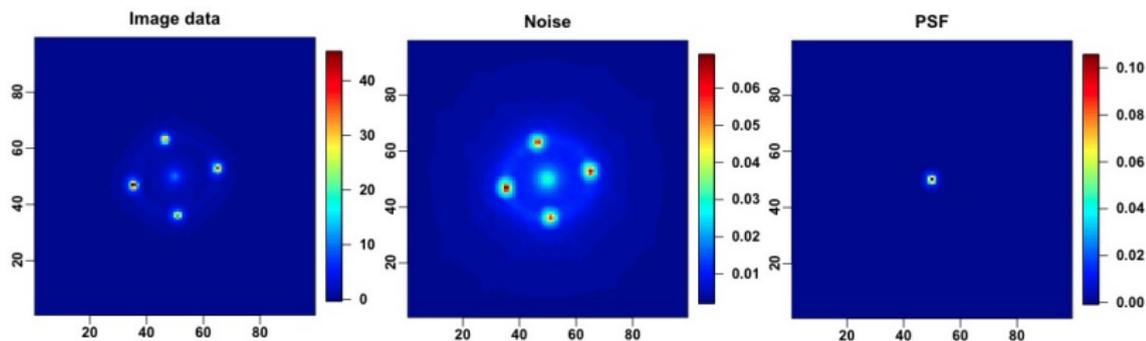
$$I(\theta_{i1}, \theta_{i2}) = A \exp \left[ -k \left( \frac{\sqrt{\theta_{i1}^2 + \theta_{i2}^2/q_L^2}}{\theta_{\text{eff}}} \right)^{1/n_{\text{Sérsic}}} - k \right],$$

where  $A$  is an amplitude,  $k$  is a constant (s.t.  $\theta_{\text{eff}}$  is the effective half-light radius),  $q_L$  is the axis ratio, and  $n_{\text{Sérsic}}$  is the Sérsic index.

# TIME DELAY LENS MODELING CHALLENGE (CONT.)

## Given information:

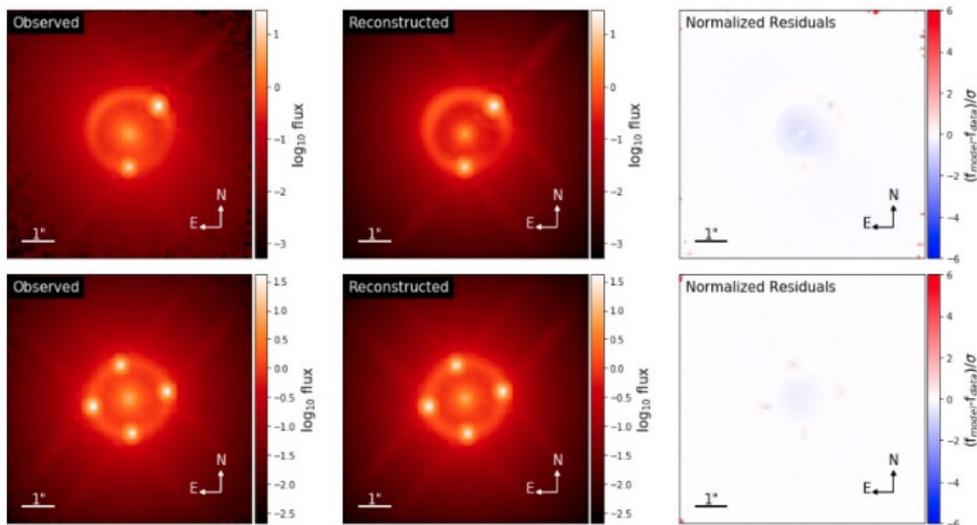
- ▶ HST-like image data ( $99 \times 99$  pixels), noise, and PSF.



- ▶ Time delay estimates and uncertainties, e.g.,  $24.2^{+0.1}_{-0.2}$  days.
- ▶ Line-of-sight lens velocity dispersion (stellar kinematic information), and external convergence,  $\kappa_{\text{ext}} \sim [0, 0.025^2]$ .

# EXAMPLE: TDLMC STAGE 1

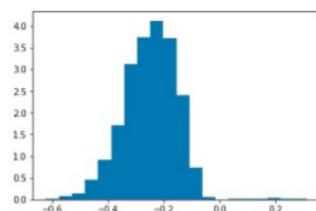
- ▶ The first stage (out of four) has two lenses with the true  $H_o$  known.
- ▶ A Python package `lenstronomy` (Birrer+, 2015, 2016, 2018) fits a lens model on each image (1st column), reconstructs images using the fitted model (2nd), and shows residual plots (3rd = 2nd - 1st).



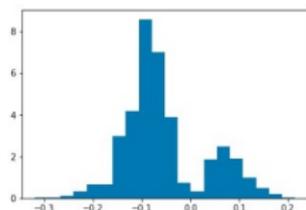
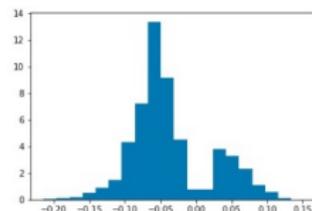
# EXAMPLE: TDLMC STAGE 1

`lenstronomy` (Birrer+, 2015, 2016, 2018) also returns posterior distributions of Fermat potential differences.

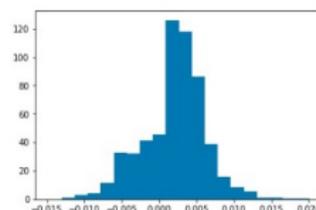
Double lens ( $\Delta\phi_{BA}$ )



Quad lens ( $\Delta\phi_{BA}$ )



Quad lens ( $\Delta\phi_{CA}$ )



Quad lens ( $\Delta\phi_{DA}$ )

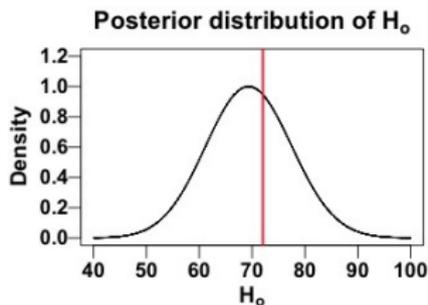
Now we have all necessary information to infer  $H_o$ !

## EXAMPLE: TDLMC STAGE 1 (CONT.)

Considering that  $\Delta t_{ij} = \frac{D_{\Delta t}(H_o, z, \Omega)}{c} \Delta \phi_{ij}$ , Marshall+ (2016) suggest a simple likelihood function of  $H_o$  based on

$$\Delta \phi_{ij} \mid \Delta t_{ij}, H_o \sim N \left[ \frac{c}{D_{\Delta t}(H_o)} \Delta t_{ij}, \sigma_{\Delta \phi_{ij}}^2 \right],$$
$$\Delta t_{ij} \sim N(\Delta t_{ij}^*, \sigma_{\Delta t_{ij}}^{2*}).$$

The resulting posterior of  $H_o$  with known  $\Delta t_{ij}^*$ ,  $\sigma_{\Delta t_{ij}}^{2*}$ ,  $z$ , and  $\Omega$  is



Note: I fitted a lens model, fixing some parameters at their true values.

# CONCLUDING REMARKS

Challenges (at least to me!)

- ▶ Python!
- ▶ No clear likelihood specification in articles → black-box packages?
- ▶ In using `lenstronomy`, how to reflect all the given information including “Noise” data and “lens velocity dispersion”?
- ▶ A better model for  $H_0$ ?
- ▶ 48 lenses (16 lenses for each of 3 stages) to be analyzed by Aug 4.

Please join this project, if you are interested in analyzing image data!



Image Credit: James Montgomery Flagg

# REFERENCE

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